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Modeling and Simulation of an Industrial Furnace with Flue Gas Recirculation for NO_x Control

By

Qing Jiang

Department of Mechanical and Materials Engineering
Faculty of Engineering



Submitted in partial fulfillment of
the requirements of the degree of
Master of Engineering Science

Faculty of Graduate Studies
The University of Western Ontario
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ABSTRACT

This thesis reports research work carried out to construct on-line real-time dynamic feedback controllers that will reduce the NO_x emission in an industrial furnace. The work began with a detailed analysis of the mechanisms for NO_x formation. Based on the knowledge gained, a low NO_x furnace was designed using CFD modeling techniques to optimize the furnace configurations. The arrangement of the mixing box for recirculated flue gas and fresh air has been determined using numerical simulations. The research has shown that flue gas recirculation (FGR) is an effective way to reduce NO_x.

To gain a better understanding of the dynamic characteristics of the furnace, the sensitivity of the furnace to the variations of different furnace inputs has been evaluated in the frequency domain by superimposing sinusoidal signals onto the following three furnace inputs: combustion air flow rate, combustion air temperature, and the pressure head of the recirculation fan. The furnace outputs considered were the mole fraction of NO_x and the mass fraction of oxygen.

Frequency domain based system identification techniques have been used to convert the frequency responses to a set of transfer function representations in an effort to facilitate the control system design. Four transfer functions have been constructed and the accuracy of these transfer functions are further evaluated by means of CFD simulations. It was concluded that these transfer functions can indeed provide an accurate representation of the dynamic behaviours of the furnace around given operating conditions.

To ensure that the furnace operates around the designed operating conditions most favourable to NO_x minimization under various disturbances or uncertainties, possible regulation of the furnace inputs through feedback control has been investigated. Based on the knowledge gained of the dynamic relationships between the furnace inputs and outputs, a control system composed of one PID and two PI controllers has been synthesized by using nonlinear optimization techniques. The performance of the closed-loop control system has been evaluated based on both the linear models and full-scope nonlinear CFD models. In both cases, satisfactory results have been obtained. The main contribution of the thesis was to develop a methodology for the design and analysis of feedback control based NO_x reduction technologies for industrial furnaces.

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TABLE OF CONTENTS

CERTIFICATE OF EXAMINATION	ii
ABSTRACT	iii
ACKNOWLEDGEMENTS	iv
TABLE OF CONTENTS	v
LIST OF FIGURES	viii
LIST OF TABLES	x
NOMENCLATURE	xi
CHAPTER ONE - INTRODUCTION	1
1.1 Background and Motivation	1
1.2 Literature Review	2
1.2.1 The mechanism of thermal NO _x formation	2
1.2.2 Methods to reduce NO _x formation	5
1.2.3 Active combustion control (ACC)	8
1.2.4 CFD simulations	11
1.3 Methodology	11
1.4 Outline of This Thesis	12
1.5 Contributions of This Thesis	13
References	14
CHAPTER TWO – AN INVESTIGATION OF THE CORRELATIONS OF INPUTS/OUTPUTS OF A FGR INDUSTRIAL FURNACE WITH CFD SIMULATION METHOD	18
2.1 Introduction	18
2.2 Configuration and Operating Condition of the FGR Furnace	21

2.3 Mathematical Models of the Combustion Process	23
2.3.1 Turbulent combustion model	23
2.3.2 NO model	26
2.4 Numerical Procedure	28
2.5 Results of Furnace Normal Operating Conditions	28
2.6 Effects of Fluctuations of Furnace Inputs on NO Formation	32
2.6.1 Effect of the fluctuation in the combustion air mass flux	33
2.6.2 Effect of the fluctuation in the combustion air temperature	37
2.6.3 Effect of the fluctuation in the pressure head of the FGR fan	40
2.7 Conclusions	43
Acknowledgement	43
References	44

CHAPTER THREE - DYNAMIC MODEL CONSTRUCTION AND VALIDATION

OF THE FGR FURNACE FOR NO _x EMISSION CONTROL	46
3.1 Introduction	46
3.2 Furnace Configuration	50
3.3 Mathematical Models	52
3.4 Input and Output Representation of the Furnace	55
3.5 CFD Simulation Results	56
3.6 Construction of the Transfer Functions	60
3.7 Validation of the Dynamic Models	62
3.8 Conclusions	71
Acknowledgement	72
References	72

CHAPTER FOUR – THE DESIGN AND VALIDATION OF THE CONTROLLERS

FOR THE FGR FURNACE TO REDUCE NO _x EMISSION	75
4.1 Introduction	75
4.2 The Furnace, Its operating Condition and the Problem Statement	79
4.2.1 The furnace configuration	79

4.2.2 A general strategy for determining desired operating condition for NO _x reduction	81
4.2.3 Furnace operating conditions	82
4.3 Construction of Linear Dynamic Model	83
4.3.1 Full-scale CFD model for the furnace	83
4.3.2 Linear dynamic model of the furnace	86
4.4 Design of Feedback Control System	88
4.5 Validation of the Designed Control System by Nonlinear CFD Simulations	93
4.6 Conclusion	98
References	99
 CHAPTER FIVE – CONCLUSIONS	103
5.1 Summary of the Work	103
5.2 Conclusions	103
5.3 Future Work	105
 APPENDIX A – FREQUENCY RESPONSE PLOTS	106
A.1 The Transfer Function $G(s)_{O_2}$	106
A.2 The Transfer Function $G(s)_{air\ mass}$	107
A.3 The Transfer Function $G(s)_{air\ temp}$	108
A.4 The Transfer Function $G(s)_{fan}$	109
 CURRICULUM VITAE	110

LIST OF FIGURES

Figure 1.1	Excess oxygen concentration vs relative NO _x emission	9
Figure 2.1	Configuration/dimensions of the FGR furnace	22
Figure 2.2	The cone angle of fuel injection	29
Figure 2.3	Velocity vector (m/s) on the plane at $z=0$ m	30
Figure 2.4	Temperature contour (K) on the plane at $z=0$ m	31
Figure 2.5	NO contour (mole fraction) on the plane at $z=0$ m	31
Figure 2.6	NO emission as the combustion air mass flux is varied	36 - 37
Figure 2.7	NO emission as the temperature of the combustion air is varied	38 - 39
Figure 2.8	NO emission as the pressure head of the FGR fan is varied	41 - 42
Figure 3.1	Configuration of the FGR furnace	51
Figure 3.2	Dynamic model structure and input/output variables	55
Figure 3.3	Variation of O ₂ at the furnace outlet relative to the combustion air mass flux	62 - 63
Figure 3.4	Variation of NO at the furnace outlet relative to combustion air temperature	64 - 65
Figure 3.5	Variation of NO at the furnace outlet relative to the combustion air mass flux	66 - 67
Figure 3.6	Variation of NO at the furnace outlet relative to the pressure head of the FGR fan	68 - 69
Figure 4.1	Configuration of the FGR furnace (unit: m)	80
Figure 4.2	The input and output representation of the FGR furnace	86
Figure 4.3	Configuration of the control system	90
Figure 4.4	The step response of the oxygen output controlled by the controller PID ₁	92
Figure 4.5	The step response of the NO output controlled by the controller PI ₂	92
Figure 4.6	The step response of the NO output controlled by the controller PI ₃	93

Figure 4.7	The step responses of O_2 based on the linear and the nonlinear CFD models	96
Figure 4.8	The step responses of NO_x based on the linear and the nonlinear CFD models	96

LIST OF TABLES

Table 2.1	Operating conditions of the furnace	23
Table 2.2	Effect of the fuel injection angle	29
Table 2.3	Effect of the combustion air mass flux	35
Table 3.1	Normal furnace operating conditions	52
Table 3.2	Gain and phase characteristics for O ₂ at the furnace outlet	58
Table 3.3	Gain and phase characteristics for NO at the furnace outlet	59
Table 4.1	Normal furnace operating conditions	82
Table 4.2	Parameters for the designed controllers	91

NOMENCLATURE

Symbol	Description
A, A_i	Constant
$a_0, a_1, a_2, a_3, a_4, a_5, a_6$	Coefficients
B, B_i	Constant
$b_0, b_1, b_2, b_3, b_4, b_5, b_6$	Coefficients
C_1	Constant in turbulent model
C_2	Constant in turbulent model
C_d	Constant in turbulent model
C_g	Constant in turbulent model
C_μ	Constant in turbulent model
E_1	Accumulated error of the input of oxygen concentration
E_2	Accumulated error of the input of NOx emission
e_1	Transient error of the input of oxygen concentration
e_2	Transient error of the input of NOx emission
f	Mixture fraction
f_{O_2}	Mass fraction of O ₂ at the outlet of the furnace
\bar{f}	Mean mixture fraction
\bar{f}^2	Mean mixture fraction variance
G	Gain to build transfer function

G_k	Generation of turbulence kinetic energy due to mean velocity gradients
$G(s)_{air\ mass}$	Transfer function from mass flux of combustion air to NOx
$G(s)_{air\ temp}$	Transfer function from the temperature of combustion air to NOx
$G(s)_{fan}$	Transfer function from the pressure head of the fan to NOx
$G(s)_{O_2}$	Transfer function from mass flux of combustion air to O ₂
h	Convective heat transfer coefficient, [W/m ² .K]
h	Static enthalpy, [J/kg]
k	Turbulence kinetic energy
k_i	Chemical reaction constant of i spice, [m ³ mol ⁻¹ s ⁻¹]
m_{air}	Air mass flux sinusoidal shift, [kg/m ² .s]
m_{fuel}	Mass flow of fuel, [kg/s]
$(m_{air})_{inlet}$	Air mass flux inlet, [kg/m ² .s]
PID_1	The controller of oxygen to air mass flux
PI_2	The controller of NOx to air temperature
PI_3	The controller of NOx to pressure head of FGR fan
P_{fan}	Pressure head sinusoidal shift, [Pa]
(P_{fan})	Pressure head of the FGR fan, [Pa]
S_h	Sources of enthalpy due to chemical reaction and radiation, [J/kg]
T	Gas local temperature, [K]
T_{air}	Air temperature sinusoidal shift, [K]

$(T_{air})_{inlet}$	Air temperature inlet, [K]
t	Time, [s]
u_i, u_j	Mean gases velocity components, [m/s]
u_i', u_j'	Fluctuating air velocity components, [m/s]
u_{max}	Maximum input variable
u_{min}	Minimum input variable
u_o	Input variable at steady operating point
x_i	Coordinate in x, y, z directions, [m]
Y_{NO}	NO mass fraction
y_{max}	Maximum output variable
y_{min}	Minimum output variable
y_{NO}	NOx mole fraction at the outlet of the FGR furnace, [ppm]
y_o	Output variable at steady state operating point
Z_k	Elemental mass fraction for some element, k
Z_{kO}	The mass fraction of element k at oxidizer inlet
Z_{kf}	The mass fraction of element k at fuel inlet

Greek Alphabet

α	Gas absorption coefficient
ε	Dissipation rate of k

ε	Gas radiation emissivity
ω	Frequency, [Rad/s]
μ	Kinematic coefficient of viscosity, [m ² /s]
μ_t	Turbulent viscosity, [m ² /s]
ρ	Density of gases, [kg/m ³]
$\sigma_k, \sigma_\varepsilon, \sigma_h, \sigma_t$	Turbulent Prandtl numbers

CHAPTER ONE

Introduction

1.1 Background and Motivation

Air pollution is a serious problem in modern society. Environmental protection has become a societal responsibility. NO_x emission, which is a collective name for NO and NO₂, is a major air pollution source. NO_x not only causes nitric acid rain, but also forms ground-level ozone in the stratosphere. It is estimated that over 95 percent of all man-made NO_x is produced by the combustion of various fuels in the industrial process [1]. The degeneration of air quality prompts the governments of many countries to establish stricter standards to limit the amount of NO_x released without penalty. According to the Canadian Environment Quality Guidelines [2], the release of NO_x should not exceed the following limits for a furnace or boiler.

Less than 400-1000 $\mu\text{g}/\text{m}^3$ (NO_x/Flue gas) in a consecutive hour;

Less than 200-300 $\mu\text{g}/\text{m}^3$ (NO_x/Flue gas) in 24 consecutive hours;

Less than 60-100 $\mu\text{g}/\text{m}^3$ (NO_x/Flue gas) in a consecutive year.

The development of effective ways to reduce NO_x emission in combustion processes in order to meet the strict limitations placed on industry has become extremely important. Flue gas recirculation (FGR) is an effective way to reduce NO_x emission for standard industrial furnaces. However, FGR furnaces work at a low excess oxygen concentration. A slight drift from the operating point could result in a significant increase in the amount of NO_x emission. Therefore, it is necessary to develop an effective control system for FGR furnaces to provide tight control on the operating conditions.

The main objective of this thesis is to use a novel approach to develop a real time feedback control system for a FGR industrial furnace to reduce NO_x emission. Although many emission monitor systems have been developed to monitor the combustion process in industrial furnaces, few studies have been published on the use of information from an emission monitor system for real-time NO_x emission control. The reason for this situation is that the significant time delay exists in NO_x measurement. Recently, new sensitive NO_x analyzers have been developed and the dead time has been reduced to less than one second. This thesis reports on pioneering research in the development of real-time feedback and online NO_x emission controllers for FGR furnaces.

In order to achieve the main objective, a set of sub-objectives has been completed in the following chapters. A simplified FGR furnace is designed and optimized in Chapter 2 by the results of CFD simulation at an operating point. The input/output relationships of the FGR furnace have been investigated by superimposing sinusoidal signals of different frequencies on the furnace inputs. In Chapter 3, a set of dynamic models in the form of transfer functions has been constructed and validated based on the data acquired in Chapter 2. Finally, the PI and PID controllers for the FGR furnace have been designed and optimized by using the nonlinear least squares method in Chapter 4.

1.2 Literature Review

1.2.1 The mechanism of NO_x formation

The formation of NO_x can be classified into three distinct chemical kinetic processes: thermal NO_x, prompt NO_x, and fuel NO_x. Thermal NO_x is formed by oxidation of nitrogen in the combustion air at a relatively high temperature in a fuel-lean

environment. It strongly depends on the flame temperature. Prompt NOx is produced by a high-speed reaction at the flame front, and fuel NOx is produced by oxidation of nitrogen contained in the fuel. Since the amount of nitrogen in liquid or gas fuels is very minimal, the prompt NOx is very low [3]. Therefore, only thermal NOx is considered in this research.

NOx includes the mixture of NO and NO₂. Both NO and NO₂ are formed during a combustion process. Generally, NO₂ concentration is negligible compared with NO concentration. It is usually considered as a transient intermediate species that exists only at flame conditions, and it can subsequently be converted back to NO in the post-flame region. Therefore, the research of thermal NOx formation usually refers to the thermal NO formation.

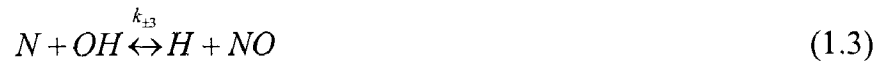
The original formation and verification of the thermal NOx mechanism is attributed to Zeldovich [4, 5], who studied the explosion of gases within a combustion bomb. Hanson and Salimian [6] suggested the use of the extended Zeldovich mechanism to determine the formation of thermal NOx. Thermal NOx comes from the oxidation of molecular nitrogen in the combustion air. The concentration of O atoms in flames grows with temperature due to the dissociation processes of oxygen. If the temperature is high enough, O atoms attack N-N chemical bonds in the direct high activation energy process.



The N atoms react quickly with O₂ to regenerate O atoms by:



This reaction is known as the Zeldovich mechanism. The concentration of NO is further increased by a radical-radical reaction:



in which the rate constants are given by:

$$k_1 = 1.8 \times 10^8 \exp\left(\frac{-38370}{T}\right)$$

$$k_{-1} = 3.8 \times 10^7 \exp\left(\frac{-425}{T}\right)$$

$$k_2 = 1.8 \times 10^4 T \exp\left(\frac{-4680}{T}\right)$$

$$k_{-2} = 3.8 \times 10^3 T \exp\left(\frac{-20820}{T}\right)$$

$$k_3 = 7.1 \times 10^7 \exp\left(\frac{-450}{T}\right)$$

$$k_{-3} = 1.7 \times 10^8 \exp\left(\frac{-24560}{T}\right)$$

The unit of all the rate constants is $m^3 mol^{-1} s^{-1}$. The rate of the NO formation in these reactions is very sensitive to temperature and radical concentrations. Thus, the thermal NO is formed mostly in the flame regions with higher temperatures. The actual thermal NO usually is a little higher than the calculated one if radical concentrations exceed their equilibrium values, which often happens in flame fronts. More thermal NO can be formed under fuel-lean conditions because oxygen concentration affects thermal NO formation.

Based on the quasi-steady state assumption for N concentration, the net rate of NO formation via the above reactions can be determined by

$$\frac{d[NO]}{dt} = 2[O][N_2] \left[1 - \frac{k_{-1}k_{-2}[NO]^2}{k_1k_2[N_2][O_2]} \right] / \left[1 + \frac{k_{-1}[NO]}{k_2[O_2] + k_3[OH]} \right] \quad \text{mol m}^{-3} \text{ s}^{-1} \quad (1.4)$$

where $k_{\pm i} = A_i T^{B_i} \exp(-C_i/T)$. The reaction constants A_i , B_i and C_i are taken from Hanson and Salimian [6].

The concentration of OH in the third reaction in the extended Zeldovich mechanism is given by [7, 8]:

$$[OH] = 2.129 \times 10^2 T^{0.57} \exp(-4595/T) [O]^{0.5} [H_2O]^{0.5} \quad \text{mol/m}^3 \quad (1.5)$$

To determine the O radical concentration, a partial equilibrium approach [9] is used:

$$[O] = AT^B [O_2]^{1/2} \exp(-C/T) \quad \text{mol/m}^3 \quad (1.6)$$

where $A=36.64$, $B=0.5$ and $C=27123$.

1.2.2 Methods to reduce NOx formation

According to the Zeldovich mechanism, the formation of thermal NOx is sensitive to flame temperature and concentration of O₂ in the flame envelope. Therefore, a number of combustion control techniques used to reduce thermal NOx emissions are based on the following three general principles: (1) lower temperature, (2) lower oxygen concentration

in the flame envelope, and (3) reduced residence time at peak temperature. Recently developed techniques to achieve the above conditions are described as [10]:

- (1) Flue gas recirculation (FGR): Relatively cool flue gases are recirculated back into the flame envelope. Relative to the combustion flame in the furnace, flue gases are cooler. Recirculation of these gases back into the flame dilutes the concentration of O_2 in the flame envelope, enlarges the flame envelope, and reduces the peak flame temperature.
- (2) High excess air ratio: The furnace operates at a high excess air ratio to reduce the peak flame temperature. However, this also reduces furnace efficiency.
- (3) Staged air injection: Combustion air is injected into the furnace at different stages. Approximately 60 to 70% of the theoretically required combustion air is injected into the first zone in which all the fuel is partially combusted. This fuel-rich combustion reduces NO_x because of the low oxygen concentration. The rest of the combustion air is injected into the second zone to oxidize the residual fuels. Peak flame temperatures are lowered in both zones, which in turn reduce the NO_x emission.
- (4) Staged fuel injection: A portion of the fuel is injected into the combustion air and burned in the first combustion zone. The NO_x generation rate is low at lower flame temperatures. The remainder of the fuel is injected downstream from the first zone. NO_x emission from the secondary combustion zone is suppressed due to the diluted oxygen concentration.

Generally speaking, an air-staged low NO_x burner can reduce NO_x emission by approximately 30 to 50% compared to a conventional burner. A fuel-staged low NO_x

burner can lower NO_x emission to one third of that generated by a conventional burner. Some high excess air burners can achieve even better results [10]. However, the high level of excess air reduces the efficiency of the furnace. Also, air and fuel staged low NO_x burners tend to have longer and narrower flames than standard burners. This will have impact on the size of the furnace.

A common method used to reduce thermal NO_x emission in a combustion system is flue gas recirculation (FGR) [10]. This technique shows that a portion of the flue gases is fed back by a circulation fan and mixed with the fresh combustion air before entering the furnace. A heat recovery device is commonly used to cool down the flue gases. Otherwise, the temperature of the flue gases would be too high for the fan. With FGR, NO_x formation is suppressed due to the two mechanisms. First, the peak flame temperature is reduced due to the larger mass of gases to be heated. Second, the oxygen concentration in the flame envelope is lowered due to the low oxygen concentration in the recirculated flue gases. Lowering the peak flame temperature has a dominant effect on NO_x reduction. The amount of the flue gas recirculation is limited by the combustion stability of the burner at the low oxygen concentration condition. If the rate of flue gas recirculation reaches 30%, the NO_x output will be at a very low level. However, it will cause flame instability and limit the performance of the furnace and boiler [11]. FGR is usually limited to 20% for natural gas and from 10 to 12% for oil-fired furnaces [12]. NO_x reduction can vary from 45 to 80% at the high recirculation rates. FGR can be achieved by performing external or internal recirculation of flue gases. The internal recirculation of flue gases takes place at the burner where intensive air-swirling occurs. The rate of flue gas recirculation depends on the combustion air swirl number. The

internal recirculation in jet flames has been realized by the low NO_x burners of FLOX (flame lose oxidation) and GAFT (gas dynamic abated flame temperature) [13]. An external fan and a damper can be used to control the amount of flue gas recirculation to achieve external recirculation. Moloney [14] reported that FGR could reduce the particulate emissions and improve the evaporation rate of an industrial boiler. It is demonstrated that the NO_x reductions are achieved by FGR without detrimental combustion effects to the furnace with regards to load, pulsation, vibration, or excessive temperatures [15]. Potentially, FGR also offers an inexpensive alternative compared with other more costly approaches, such as selective catalytic and non-catalytic reduction methods. It was also found that the use of FGR could reduce the CO emission from a furnace [11]. Clearly, FGR is an effective way to reduce NO_x emission.

In this work, only an external flue gas recirculation scheme is considered since most of industrial furnaces are still equipped with conventional burners, and it would be easier to retrofit an existing furnace with an external recirculation mechanism.

1.2.3 Active combustion control

FGR furnaces work only at a low excess oxygen concentration. A small drift from the original operating point could cause a significant increase in NO_x emission. Figure 1.1 shows that the output of thermal NO_x triples while the concentration of O₂ in the flue gas varies from 1.5% to 5% [10]. The flow rate of recirculating flue gases is also sensitive to the fluctuations of combustion airflow rate [11]. Therefore, monitoring systems have been developed to monitor different types of combustion processes,

including continuous emission monitors (CEMS) and predictive emission monitors (PEMS) [16, 17, 18, 19].

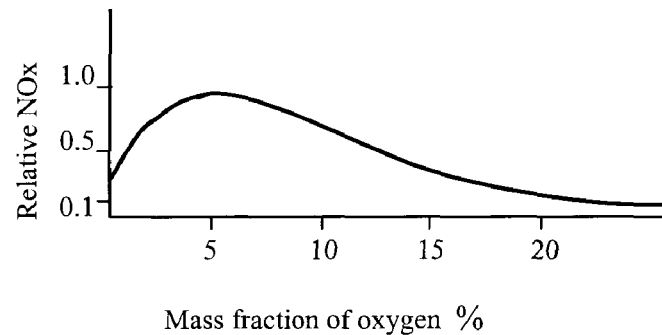


Fig. 1.1 Excess oxygen concentration vs relative NOx emission [10]

However, these monitoring schemes have not been used effectively for real-time closed-loop control purposes. One of the reasons for this is the lack of knowledge of dynamic relationships between a furnace's inputs and its emissions. Recently, stronger efforts have been made to gain a better understanding as to how a furnace behaves in a dynamic environment. A combustion process is a very complicated nonlinear process. It is almost impossible to deduce the relationships between input variables and output variables mathematically based on fluid flow, heat transfer and combustion models. Among existing published work, Matsumura [20] built a multi-input and multi-output model to describe the relationship between the NOx concentration in the flue gases and the furnace input variables. This model was obtained through a recursive least squares method.

Another obstacle the real-time control encounters is the time delay associated with the NOx measurement. A control system with a feed forward term was adopted to overcome this problem [21]. The precise prediction of this measurement delay is a

prerequisite for such a control system as it is based on the prediction of the current NO_x concentration. In recent years, the measurement delay seems to have become less of a problem due to advances in sensor technology [22]. Several manufacturers have announced that they have successfully developed sensitive NO_x analyzers using the chemiluminescent method. The measurement delay could be reduced to less than one second and the minimum detectable concentration is as low as 0.02 ppm. This is encouraging news for control engineers, and now is the right time to develop an effective real-time combustion control system for combustion processes.

Preliminary studies have concluded that real-time feedback control is particularly desirable for optimizing combustion processes, alleviating combustion instabilities, and most of all, reducing the emission of pollutants such as NO_x, CO, etc. [23]. The basic approach of Active combustion control (ACC) is to measure the appropriate furnace variables in real-time and feed such information back to controllers to regulate the furnace inputs accordingly. Depending on the dynamic properties of the combustion processes, the combustion control system can adjust its outputs automatically to meet the desired furnace performance requirements. The performance may include such items as flame stability, range of temperature variations, fuel efficiency, and emission levels. In the current study, the emphasis is placed on the reduction of NO_x emission. Comprehensive coverage of NO_x control techniques can be found in three excellent survey papers [24, 25, 26].

1.2.4 Computational fluid dynamics (CFD) simulations

CFD modeling has found increasing use in the design and evaluation of utility furnaces, combustion optimization and NO_x reduction technologies [27, 28, 29, 30, 31]. This procedure has the following merits: (1) there is no need to build an experimental furnace at an early stage of investigation; (2) it is easy to test different furnace configurations; (3) it is easy to change the input variables; (4) it is easy to realize some particular combustion process that is difficult in the form of practical experiments.

1.3 Methodology

The relationships between the furnace inputs and outputs need to be established to design an effective control system. Once such relationships exist, the desirable feedback control law can be developed to achieve the specified system performance. Detailed relationships between the furnace inputs and outputs will be built and optimal control system can be designed for an industrial furnace with flue gas recirculation (FGR).

Instead of experimental measurement, a CFD simulation is conducted for the combustion process in the FGR furnace. CFD plays two major roles in the current investigation: (1) it provides detailed input and output data based on which the linearized furnace control model can be constructed; and (2) it validates the performance of the designed controller under a realistic nonlinear furnace operating conditions. The FGR model furnace created in this study is a simplified FGR furnace that has the characteristics of flow and combustion of a furnace. The model furnace is optimized according to the numerical results acquired at steady operating conditions.

The transient input and output data at different frequencies are used to determine the gain and time delay. A least squares method is employed to optimize the frequency response transfer functions between the inputs and outputs. A nonlinear optimization method is used to design the PI (Proportional-Integral) and PID (Proportional-Integral-Derivative) controllers. To verify the validity of these dynamic models and controllers, the responses generated from these dynamic models and controllers are compared with those obtained from the numerical solutions by CFD simulations.

1.4 Outline of This Thesis

This thesis is divided into five chapters. Chapter 1 describes the motivation, methodology, research background and literature review, as well as highlights of the contributions. Chapters 2, 3, 4 are composed of three papers submitted to journals. In Chapter 2, a simplified FGR model furnace is obtained based on CFD simulations. Numerical simulations are conducted for the furnace. The NO_x emission and combustion profiles at the steady state are acquired. Finally, the transient relationships between the NO_x emissions and the furnace input variables, such as the inlet combustion air mass flow rate, inlet combustion air temperature, and the pressure head of the FGR fan, are investigated. Chapter 3 concentrates mainly on the development of dynamic models based on frequency response tests, which are suitable for online and real-time feedback control to reduce NO_x emissions from FGR furnaces. These models are verified by comparing the responses generated from these models with those obtained from the numerical solutions using CFD. In Chapter 4, the control strategy for NO_x reduction is discussed. The controllers are designed using the nonlinear optimization method. In order

to verify the performance of the controllers, the signal just behind the PID controller is extracted as an input boundary condition for the model furnace in CFD simulations. The transient NO_x output is then compared with the solutions in the simulation of dynamic reactions. Chapter 5 contains the conclusions of this thesis work.

1.5 Contributions of This Thesis

The research reported in this thesis contains some pioneering work across the disciplines of fluid dynamics, combustion and linear control system technologies. The main contributions can be summarized as follows:

1. A FGR furnace has been designed. Its NO_x emission is only 17% of the standard furnace. An optimal arrangement of the mixing box and the optimal direction of fuel injection are suggested.
2. The sensitivity of the furnace has been investigated using frequency response technologies.
3. The transfer functions representing the furnace input and output relationships are obtained.
4. The optimal design of furnace controllers has been carried out. The performance of the controllers has been validated using CFD simulation studies.

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CHAPTER TWO¹

An Investigation of the Correlations of Inputs/Outputs of a FGR Industrial Furnace with CFD Simulation Method

2.1 Introduction

The emission of NO and NO₂, collectively known as NO_x, is known to be one of the leading causes of a variety of health-related problems. The emission of NO_x from combustion processes in industrial furnaces and boilers is a major pollutant source in our environment. It is estimated that over 95 percent of all man-made NO_x that enters the atmosphere is produced by combustion of various fuels [1]. Due to stringent environmental laws and a sense of responsibility to future generations, it becomes increasingly important to find new ways to cut down on combustion-generated NO_x emissions. According to the Canadian Environment Quality Guidelines [2], the release of NO_x should not exceed the following limits for a furnace or a boiler: 400-1000 µg/m³ (NO_x/Flue gas) in an occasional hour, 200-300 µg/m³ (NO_x/Flue gas) in 24 consecutive hours and 60-100µg/m³ (NO_x/Flue gas) in one consecutive year. One solution to reduce NO_x emission is to use innovative technology to optimize furnace operating conditions.

Both NO and NO₂ are formed during a combustion process. Generally, NO₂ concentration is negligible compared with NO concentration. It is usually considered as a transient intermediate species existing only at flame conditions that is subsequently converted back into NO in the post-flame region. In gas- or oil-fired industrial furnaces,

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the major portion of NO generated is the thermal NO. The prompt NO and reburning NO are usually in a very small quantity [3]. Thus, only the thermal NO is considered in this work. It is well known that the formation of the thermal NO can be determined by the extended Zeldovich mechanism [4], which indicates that the formation of NO depends strongly on the flame temperature and the concentration of oxygen (O_2) in the flame envelope. A number of combustion control strategies based on this knowledge have been developed to reduce the thermal NO emission by limiting the following variables: (1) the peak temperature of the flame envelope; (2) the oxygen concentration in the flame envelope; and (3) the residence time at the peak temperature [5]. An effective technique to reduce the thermal NO formation is to use FGR, where a portion of the exhaust gases at the furnace outlet is fed back to the furnace inlet to mix with the fresh combustion air before entering the furnace. A heat recovery device is commonly used to cool down the flue gases before this mixing process begins. The main effects of such flue gas recirculation are to dilute the O_2 concentration in the flame envelope, enlarge the flame envelope, and reduce the peak flame temperature. Lowering the peak flame temperature has a major effect on the amount of NO formed. The amount of flue gas recirculation is limited by the combustion stability of the burner at low oxygen concentration conditions. Typically, it is limited to 20% for gas-fired furnaces and 10~12% for oil-fired ones. NO can be reduced by 45% to 80% at high recirculation rates. Clearly, FGR is an effective NO emission reduction technique. Potentially, it offers an inexpensive alternative to other more costly approaches such as selective catalytic reduction, non-catalytic reduction, etc. Tompkins [6] also reported that the use of the FGR could also reduce the CO emission from a furnace.

The FGR can be achieved through either external or internal recirculation of flue gases. Internal recirculation of flue gases occurs at burners where intensive air swirling exists. The rate of internal flue gas recirculation depends on the combustion air swirl number. Successful applications of the internal recirculation were realized by the flame loss oxidation and gas-dynamic abated flame temperature burners [7]. To achieve external recirculation, an external fan and a damper could be used to control the amount of flue gas recirculation. Only an external flue gas recirculation scheme is considered in this paper since most industrial furnaces are still equipped with conventional burners, and it would be easier to retrofit an existing furnace with an external recirculation mechanism.

The FGR is an effective way to reduce NO emission. The NO emission is also sensitive to other furnace input variables, especially the combustion air mass flow rate. In practice, FGR furnaces usually operate at a low excess oxygen concentration. A slight variation in the operating conditions could result in a significant change for NO_x emission. The flow rate of the recirculated flue gases is also sensitive to the fluctuation of the inlet combustion air mass flow rate [6]. Therefore, it is imperative to have accurate knowledge about how NO is affected by all the controllable furnace inputs before any active combustion control system can be designed. Such relationships are generally dynamic in nature and are best represented in the frequency domain. The objective here is to determine such relationships through numerical simulations guided by clear physical intuition.

The study concludes that the combustion air mass flux is the most sensitive variable for NO_x emission. Particular attention should be paid in the design of the combustion control system. Other input variables, the temperature of the combustion air and the

pressure head of the FGR fan have relatively fewer effects. The results of this investigation are of significant value to the understanding of the dynamic relationships between furnace input variables and NO_x emission at the furnace output, and they also provide important information for combustion control system design.

This chapter is organized as follows: In Section 2.2, a brief description of the furnace and its operating conditions is provided. Mathematical modeling of the combustion process as well as NO_x model is covered in Section 2.3. The procedure for numerical solutions is given in Section 2.4. The numerical results under normal operating conditions of the furnace are summarized in Section 2.5. The relationships between the NO emission and perturbations of the respective furnace inputs are shown in Section 2.6 and are followed by the conclusions.

2.2 Configuration and Operating Conditions of the FGR Furnace

The configuration of the FGR furnace used in this study is illustrated in Fig. 2.1. Its dimensions and the arrangement of the mixing box have been optimized based on the numerical simulation results. The dimensions of the furnace are $3.75 \times 1.4 \times 1.4 \text{ m}^3$. The burner is located at the center of the left-hand sidewall and the exhaust outlet is at the center of the right-hand sidewall as shown in Fig. 2.1. A flue gas recirculation pipe 0.15 m in diameter is used to recirculate the flue gases back to the inlet of the furnace. The recirculation flue gases are extracted from the center of the top-right side of the furnace as shown in the figure. The dimensions of the mixing box at the inlet of the furnace are $0.3 \times 0.3 \times 0.8 \text{ m}^3$. The combustion air and the recirculation flue gases enter the mixing box in the same direction so that the flue gases and the combustion air can be mixed symmetrically before entering the furnace to avoid any potential deviation of the flame in a particular direction inside the furnace. The stabilizer at the center of the right-hand side

wall of the mixing box is simplified as a round plate 0.07 m in diameter based on the data given by Vahnati [8]. A diffuser with an inlet diameter 0.2 m and exit diameter of 0.35 m is used between the mixing box and the furnace as shown in Fig. 2.1. The fuel and gases are injected into the diffuser through a concentric pipe with an inner diameter of 0.07 m and outer diameter of 0.2 m. The fuel is injected through the center pipe and gases are injected through the annular area between the two pipes. Therefore, this is a non-premixed combustion process.

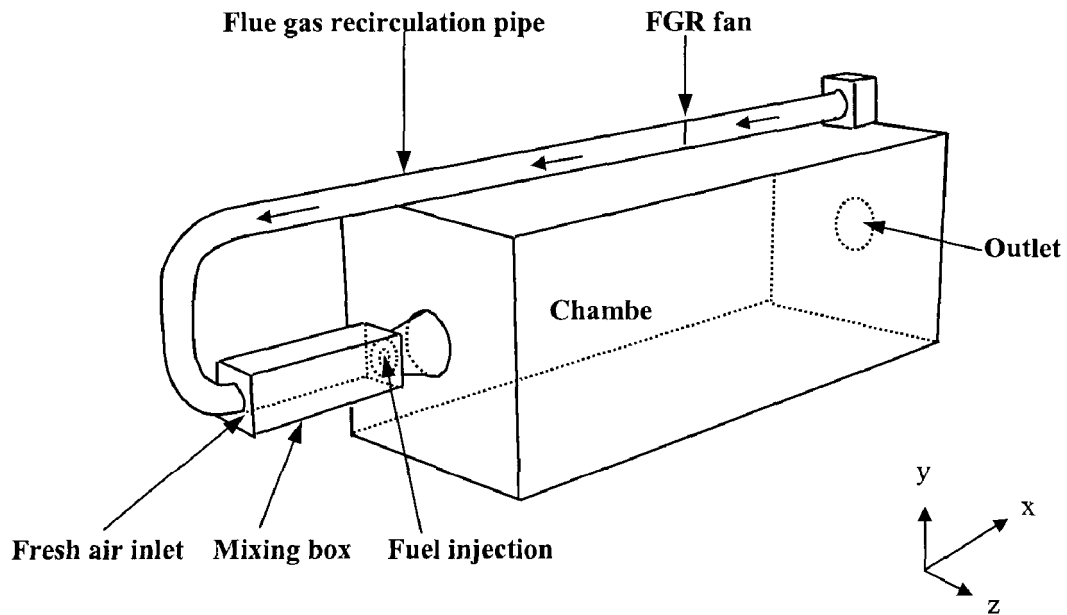


Figure 2.1 Configuration of the FGR furnace

Liquid propane is used as the fuel in the current study. The heat input to the furnace from the fuel is 345 kW. Other parameters under normal operating conditions are shown in Table 2.1. This is a reheating furnace where the bottom wall of the furnace is kept at a constant temperature of 1100 K. The heat output of the furnace is mainly through the

bottom wall. Under normal operating conditions, the combustion air is preheated to 700 K before it enters to the furnace and the FGR mass flow rate is about 8.2% of the total gas mass flow rate entering the furnace. This value is less than the recommended one (10~12%) for liquid fuel. Therefore, a slight positive drift of the pressure head in the FGR fan will not blow away the flame from the stabilizer.

Table 2.1 Operating conditions of the furnace

Fuel (propane, C ₃ H ₈)	Flow rate	0.0075 kg/s
	Temperature	300 K
	Heating value	345 kW
Input combustion air	Flow rate	0.135 kg/s (or 1.849 kg/m ² ·s)
	Temperature	700 K (or 426.85°C)
Heat output	190 kW from the bottom of the furnace	
Pressure head of the FGR fan	33.8 Pa	
Flue gas recirculation rate	0.012 kg/s	
Temperature at the bottom wall	1100 K	
Temperature at the FGR pipe	700K	

2.3 Mathematical Models of the Combustion Process

2.3.1 Turbulent combustion model

For turbulent non-premixed combustion, if the chemical reaction is sufficiently fast and all species and enthalpy have equal diffusion coefficients, the instantaneous thermochemical state of the mixture will be a function of the instantaneous mixture fraction, f , which is defined as

$$f = \frac{Z_k - Z_{kO}}{Z_{kF} - Z_{kO}} \quad (2.1)$$

where Z_k is the element mass fraction for the element k . Subscripts O and F represent the values at the oxidizer and the fuel stream inlet, respectively.

In order to take into account of the dissociation that is important near stoichiometric conditions and intermediate species, the present combustion model is derived based on the assumption that the chemical reactions occur much faster with respect to the turbulent mixing time scale. Therefore, an instantaneous chemical equilibrium always exists. The instantaneous thermochemical state can be determined by minimizing the Gibbs free energy. Temporal fluctuations can be modeled by a PDF (possibility density function). The β -PDF [9, 10] is used in this work.

The turbulent combustion model includes the conservation equations of mass, momentum, energy, turbulence kinetic energy, dissipation rate of turbulent kinetic energy, mixture fraction and its variance. Density-weighted (Favre) averaging is utilized to account for the effects of density changes. The transient three-dimensional Favre-averaged conservation equations in Cartesian coordinates can be expressed as [9, 10]:

Continuity

$$\frac{\partial \rho}{\partial t} + \frac{\partial}{\partial x_i} (\tilde{\rho} \bar{u}_i) = 0 \quad (2.2)$$

where ρ is the density, x_i is the position vector, and u_i is the velocity vector. The variables with a bar are the Favre-averaged values. The variable with a tilde represents the Reynolds-averaged value.

Momentum

$$\frac{\partial}{\partial t} (\tilde{\rho} \bar{u}_i) + \frac{\partial}{\partial x_j} (\tilde{\rho} \bar{u}_i \bar{u}_j) = \frac{\partial}{\partial x_j} \left[\mu_e \left(\frac{\partial \bar{u}_i}{\partial x_j} + \frac{\partial \bar{u}_j}{\partial x_i} \right) - \left(\frac{2}{3} \delta_{i,j} \mu_e \frac{\partial \bar{u}_l}{\partial x_l} \right) \right] - \frac{\partial \tilde{P}}{\partial x_i} \quad (2.3)$$

where $\mu_e = \mu + \mu_t$, $\mu_t = \tilde{\rho} C_\mu \frac{k^2}{\varepsilon}$ and $C_\mu = 0.09$. P is the pressure, μ the molecular viscosity, and μ_t the turbulent viscosity. k and ε represent the turbulent kinetic energy and its dissipation rate, respectively.

Enthalpy

$$\frac{\partial}{\partial t}(\tilde{\rho} \bar{h}) + \frac{\partial}{\partial x_i}(\tilde{\rho} \bar{u}_i \bar{h}) = \frac{\partial}{\partial x_i} \left(\frac{\mu_t}{\sigma_h} \frac{\partial \bar{h}}{\partial x_i} \right) + \bar{S}_h \quad (2.4)$$

where h is the static enthalpy and σ_h is the turbulent Prandtl number. \bar{S}_h consists of sources of enthalpy due to chemical reaction and radiation, and $\sigma_h = 0.7$.

Turbulent kinetic energy and its dissipation rate

$$\frac{\partial}{\partial t}(\tilde{\rho} k) + \frac{\partial}{\partial x_i}(\tilde{\rho} \bar{u}_i k) = \frac{\partial}{\partial x_i} \left(\frac{\mu_t}{\sigma_k} \frac{\partial k}{\partial x_i} \right) + G_k - \tilde{\rho} \varepsilon \quad (2.5)$$

$$\frac{\partial}{\partial t}(\tilde{\rho} \varepsilon) + \frac{\partial}{\partial x_i}(\tilde{\rho} \bar{u}_i \varepsilon) = \frac{\partial}{\partial x_i} \left(\frac{\mu_t}{\sigma_\varepsilon} \frac{\partial \varepsilon}{\partial x_i} \right) + C_1 \frac{\varepsilon}{k} G_k - C_2 \tilde{\rho} \frac{\varepsilon^2}{k} \quad (2.6)$$

where

$$G_k = \mu_t \left(\frac{\partial \bar{u}_j}{\partial x_i} + \frac{\partial \bar{u}_i}{\partial x_j} \right) \frac{\partial \bar{u}_i}{\partial x_i}, \quad C_1 = 1.44, \quad C_2 = 1.92, \quad \sigma_k = 1.0 \text{ and } \sigma_\varepsilon = 1.3.$$

Mixture fraction and its variance

$$\frac{\partial}{\partial t}(\tilde{\rho} \bar{f}) + \frac{\partial}{\partial x_i}(\tilde{\rho} \bar{u}_i \bar{f}) = \frac{\partial}{\partial x_i} \left(\frac{\mu_t}{\sigma_f} \frac{\partial \bar{f}}{\partial x_i} \right) \quad (2.7)$$

$$\frac{\partial}{\partial t}(\tilde{\rho} \overline{f'^2}) + \frac{\partial}{\partial x_i}(\tilde{\rho} \bar{u}_i \overline{f'^2}) = \frac{\partial}{\partial x_i} \left(\frac{\mu_t}{\sigma_f} \frac{\partial \overline{f'^2}}{\partial x_i} \right) + C_g \mu_t \left(\frac{\partial \bar{f}}{\partial x_i} \right)^2 - C_d \tilde{\rho} \frac{\varepsilon}{k} \overline{f'^2} \quad (2.8)$$

where f'^2 is the variance of the mixture fraction, f , and $\sigma_t = 0.7$, $C_g = 2.86$ and $C_d = 2.0$.

As near wall boundary conditions, the values of k and ε at the first grid node are obtained using standard wall functions [11]. The discrete transfer radiation model [12, 13], which is relatively simple and can be applied to a wide range of optical thickness, is employed to calculate the radiation heat transfer. The assumption of gray radiation is acceptable for all inner surfaces of the furnace. The weighted-sum-of-gray-gases model [14, 15] is used to calculate the absorption coefficient.

The liquid fuel injection is modeled by a discrete phase model. The turbulent dispersion of liquid fuel droplets and other forces on the liquid fuel phase have been neglected because the liquid fuel droplets only last for a short period of time and exist only in a small region near the inlet of the furnace.

2.3.2 NO model

The rate of NO formation is much slower than the rate of main hydrocarbon oxidation. Therefore, it is reasonable to assume that the reactions involved in the NO chemistry can be separated from the main combustion reaction mechanism. The NO formation rates and NO concentrations can be calculated using a post processor based on previously calculated velocity, turbulence, temperature, and chemistry fields. The mean NO concentration is obtained by solving the transport equation based on the flow field and the combustion solution. The effect of residence time in NO mechanisms, a Lagrangian reference frame concept, is included through the convection terms in the governing equation represented in the Eulerian reference frame.

$$\frac{\partial}{\partial t}(\tilde{\rho}\overline{Y_{NO}}) + \frac{\partial}{\partial x_i}(\tilde{\rho}u_i\overline{Y_{NO}}) = \frac{\partial}{\partial x_i}\left(\tilde{\rho}D\frac{\partial\overline{Y_{NO}}}{\partial x_i}\right) + \overline{S_{NO}} \quad (2.9)$$

where Y_{NO} is the NO mass fraction and the source term, S_{NO} , is determined from different NO formation mechanisms. The thermal NO is considered in this study. The formation of thermal NO can be determined by the extended Zeldovich mechanism [4], i.e.



Based on the quasi-steady state assumption for N concentration, the net rate of NO formation via the above reactions can be determined by

$$\frac{d[NO]_r}{dt} = 2[O][N_2] \left(1 - \frac{k_{-1}k_{-2}[NO]^2}{k_1[N_2]k_2[O_2]} \right) / \left(1 + \frac{k_{-1}[NO]}{k_2[O_2] + k_3[OH]} \right) \quad (2.11)$$

$$\text{where } k_{\pm i} = A_i T^{B_i} \exp\left(\frac{-C_i}{T}\right)$$

The NO source term can be calculated from

$$S_{NO} = M_{NO} \left\{ \frac{d[NO]_r}{dt} \right\} \quad (2.12)$$

where M_{NO} is the molecular weight of NO. In order to calculate the mean NO formation rate, $\overline{S_{NO}}$, which is required in the mean NO transport equation, the temperature PDF approach [16] is used to include the effect of turbulence on the NO formation. The mean NO formation rate can be determined by

$$\overline{S_{NO}} = \int S_{NO}(T)P(T)dT \quad (2.13)$$

where T is the temperature and $P(T)$ is the PDF. The shape of PDF is assumed to be in the form of a β - function.

2.4 Numerical Procedure

The fluid flow, heat transfer, combustion, and NO_x formation processes in the furnace are simulated using a commercial software package FLUENT [17]. The control volume approach [18] is used in which a nonstaggered grid arrangement is employed to discretize the governing differential equations, Eqs. (2.2) to (2.8). The velocity and pressure fields are linked by the SIMPLE algorithm [18].

The convergence criteria are set at 6×10^{-7} for the residual of the energy equation and 4×10^{-5} for other equations. A grid independence test is carried out using non-uniform grid sizes 119,963 and 175,119. It is found that the results from these two grid sizes are very close. For example, the difference in the peak temperature is only 0.5%. Therefore, the grid 119,963 is selected for the numerical simulations.

The boundary conditions are specified based on the furnace operating condition listed in Table 2.1. The heat loss through the furnace walls excluding the bottom wall is assumed to be negligible.

2.5 Results Under the Furnace Normal Operating Conditions

Since the NO_x emission from the furnace is very sensitive to how the fuel is injected into the furnace, the numerical simulations are performed for the furnace with different fuel injection angles under operating parameters specified in Table 2.1. The results of the analysis are shown in Table 2.2.

Table 2.2 Effect of the fuel injection angle

Case	Fuel injection angle (θ)	Peak flame temp. (K)	NO _x (ppm)	O ₂ Mass fraction	CO (ppm)	Heat output (kW)
0	0.0°	1976.0	74.9	0.0267	<1	190.0
1	5.7°	1980.7	79.9	0.0267	<1	190.2
2	11.3°	1996.7	101.2	0.0267	<1	190.7
3	16.7°	2064.9	202.5	0.0267	<1	196.1

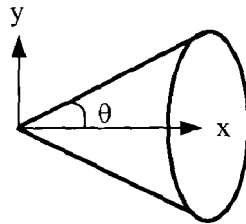


Figure 2.2 The cone angle of fuel injection

Cone injection is used to maintain a symmetrical flame in the furnace. The injection angle listed in Table 2.2 represents half the cone angle shown in Figure 2.2. The injection angle of 0° means that the fuel is injected into the furnace in the horizontal direction. It is noticed that the NO emission from the furnace increases as the fuel injection angle increases. This is because the chemical reactions are very fast and the turbulent dispersion becomes the dominant factor for the flame shape and volume. A divergent fuel injection, i.e. larger fuel injection angle, results in a quicker mix of the combustion air and the fuel. Consequently, a smaller and more intense flame envelope is created in the furnace, which results in a higher peak flame temperature and leads to a higher NO formation in the furnace. When the fuel injection angle changes from 0° to 16.7°, the peak flame temperature increases from 1976 K to 2065 K and the NO emission

from the furnace is almost tripled as indicated in Table 2.2. The results in Table 2.2 clearly illustrate that the NO emission is very sensitive to the peak flame temperature. Furthermore, the results also indicate that the fuel injection angle does not affect the O₂ concentration at the furnace outlet. The CO concentrations are less than 1 ppm for all cases. Additionally, the heat output from the furnace increases slightly (<0.4%) when the fuel injection angle increases except for Case 3 where the heat output increases by 3%. A fuel injection angle of 0° is chosen for the rest of this work since the NO_x emission is minimal at this fuel injection angle.

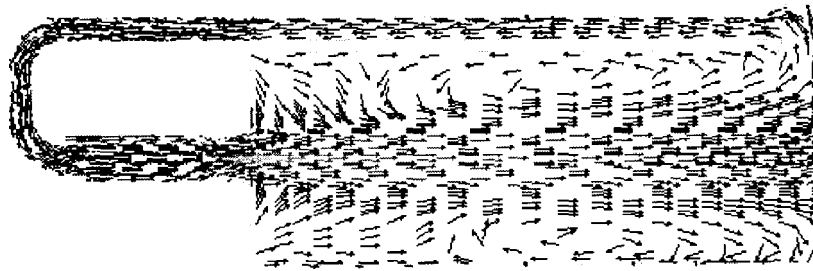


Figure 2.3 Velocity vector on the plane at $z=0$ m

The flow field on the horizontal plane at $z = 0$ m, which cuts through the center of the air and fuel injection pipes is presented in Fig. 2.3. It can be seen from the figure that the velocity distribution in the furnace is almost symmetrical along the central axis, x . This means that the extraction of a small amount of flue gases from the top-right side of the furnace has little effect on the main flow field. The air is injected into the furnace at a high velocity in the x -direction. Therefore, the main flow is in the x -direction. The velocity is very low outside of the main flow region. The figure shows that there are two recirculation zones located on each side of the central x axis in the furnace.

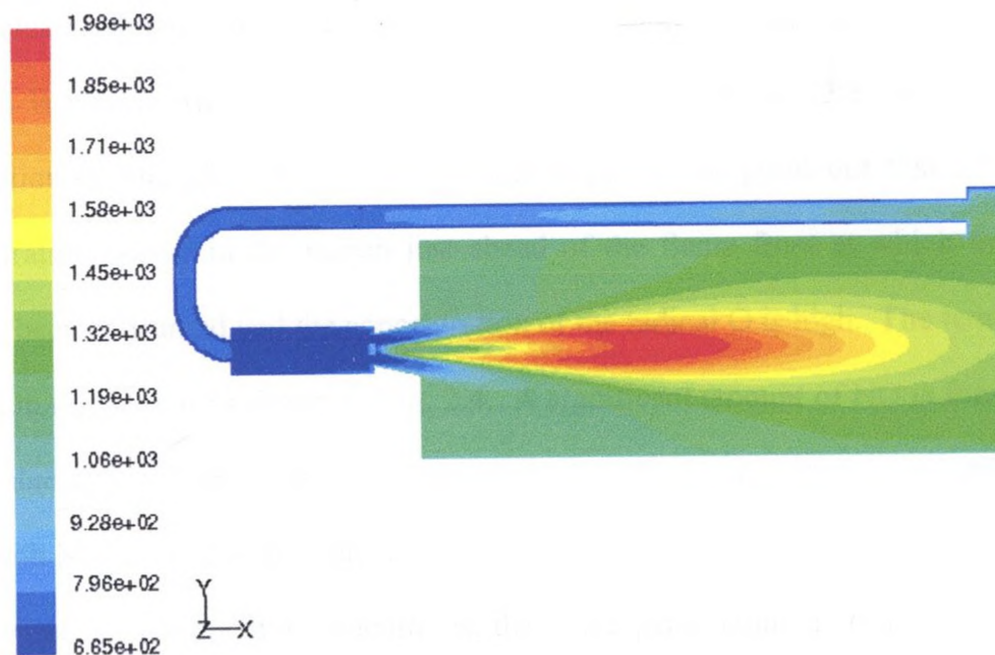


Figure 2.4 Temperature contour (K) on the plane at $z=0$ m

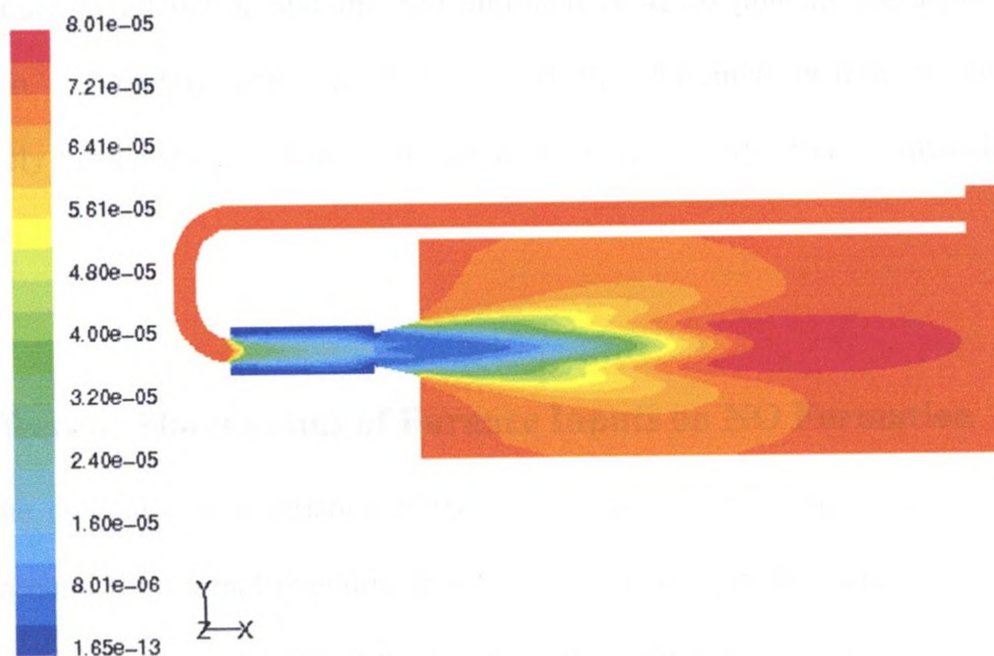


Figure 2.5 NO contour (mole fraction) on the plane at $z=0$ m

Figure 2.4 shows the temperature distribution on the same plane ($z = 0$ m). This figure clearly shows that the main reaction zone, which is located in the centre of the furnace, is characterized by a high temperature profile. Figure 2.5 illustrates the NO distribution on the plane at $z = 0$ m. It is important to point out that a higher NO concentration occurs in the region just ahead of the flame front at which the fuel has already been consumed and the concentration of the radical O is high. The temperature is highest in this region as shown in Fig. 2.4. A significant amount of NO is formed in this region due to the high temperature and high O radical concentration according to the Zeldovich NO formation mechanism.

Under normal operating conditions, the flame peak temperature is 1976 K and the NO emission is 75 ppm. For purpose of comparison, a numerical simulation is also conducted for the furnace shown in Fig. 2.1 but without the FGR. The flame peak temperature is 2070.7 K and the NO emission is 427.0 ppm at the same operating condition. Therefore, using the FGR method, the NO emission from the furnace has effectively been reduced by 82%. Clearly, the FGR is very effective in reducing NO emission.

2.6 Effects of Fluctuations of Furnace Inputs on NO Formation

The dynamic characteristics of the furnace are examined by varying the furnace inputs around the normal operating conditions to investigate the sensitivity of the NO formation to changes of furnace input controllable parameters. The three main inputs: mass flux (mass flow rate per unit flow area) of the combustion air, the temperature of the combustion air and the pressure head of the FGR fan, are disturbed individually by adding low amplitude sinusoidal signals of different frequencies. The amplitudes of these

signals are selected based on maximum allowable perturbations with practical constraints and the stability limits of the combustion process. The output variable considered herein is the mole fraction of NO at the furnace outlet.

2.6.1 Effect of the fluctuation in the combustion air mass flux

The mass flux of the combustion air at the furnace inlet is perturbed by 10% around the furnace normal operating conditions. The resulting mass flux can be represented as:

$$m_{air} = 1.8490 + 0.1849 \sin(\omega t) \text{ [kg/m}^2\text{.s]} \quad (2.14)$$

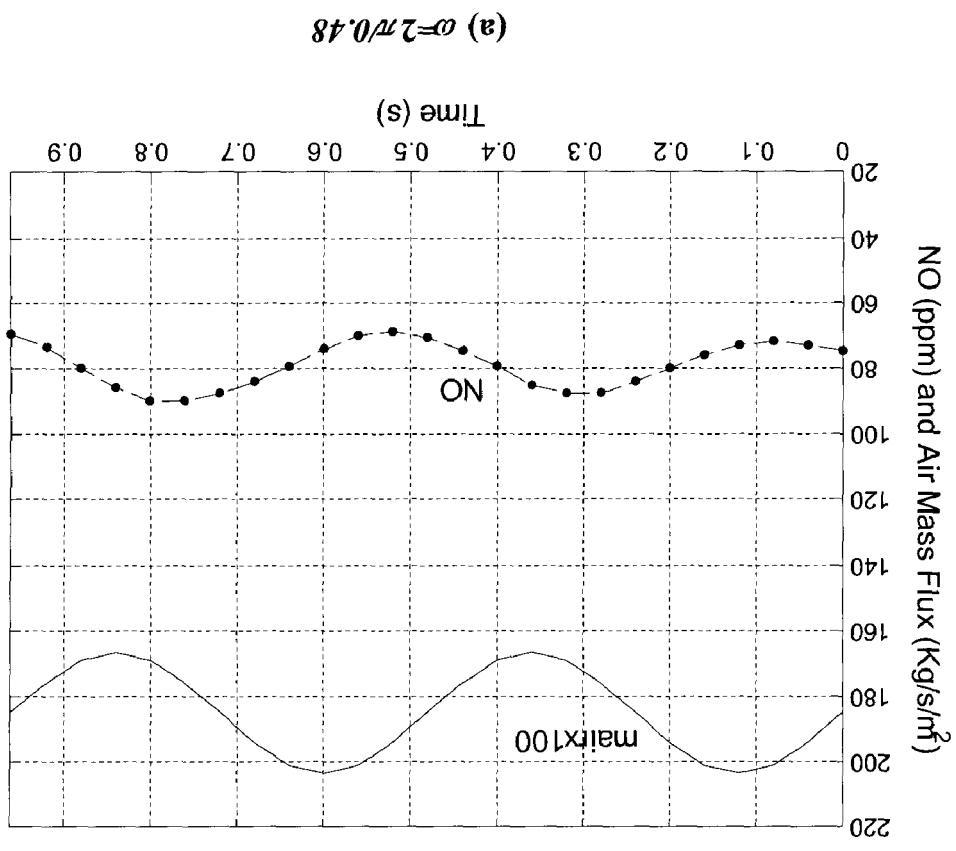
where ω is the frequency in rad/s. The simulations are carried out for the following frequencies: $\omega = 2\pi/150, 2\pi/36, 2\pi/12, 2\pi/3.6, 2\pi/2.1, 2\pi/1.2, 2\pi/0.78$, and $2\pi/0.48$ (rad/s). The results under the frequencies of $2\pi/150, 2\pi/1.2$, and $2\pi/0.48$ are shown in Fig. 2.6. The results show that the variation in NO is dramatic when the input air flow fluctuates at a low frequency. The level of NO emission reaches 210 ppm at $\omega = 2\pi/150$ as shown in Fig. 2.6 (c), which is almost triple the value at the normal operating point. It is important to emphasize that, at a low frequency ($\omega = 2\pi/150$) the NOx emission almost tripled while the mass flow rate of the combustion air has only changed 10% in the positive drift direction from the normal operating point. At a high frequency ($\omega = 2\pi/0.48$), the maximum NO is 90 ppm, which is only about 20% higher than that at the normal operating point. From Fig. 2.6, it can also be seen that the NO fluctuates at the same frequency as that of the input signal.

An increase in the flow rate of the combustion air increases the amount of oxygen available for the reaction with nitrogen, resulting in an increase in NO formation. A decrease in the flow rate of the combustion air will decrease the NO formation. Therefore, at low frequencies, the input signal fluctuation and the output NO variation are

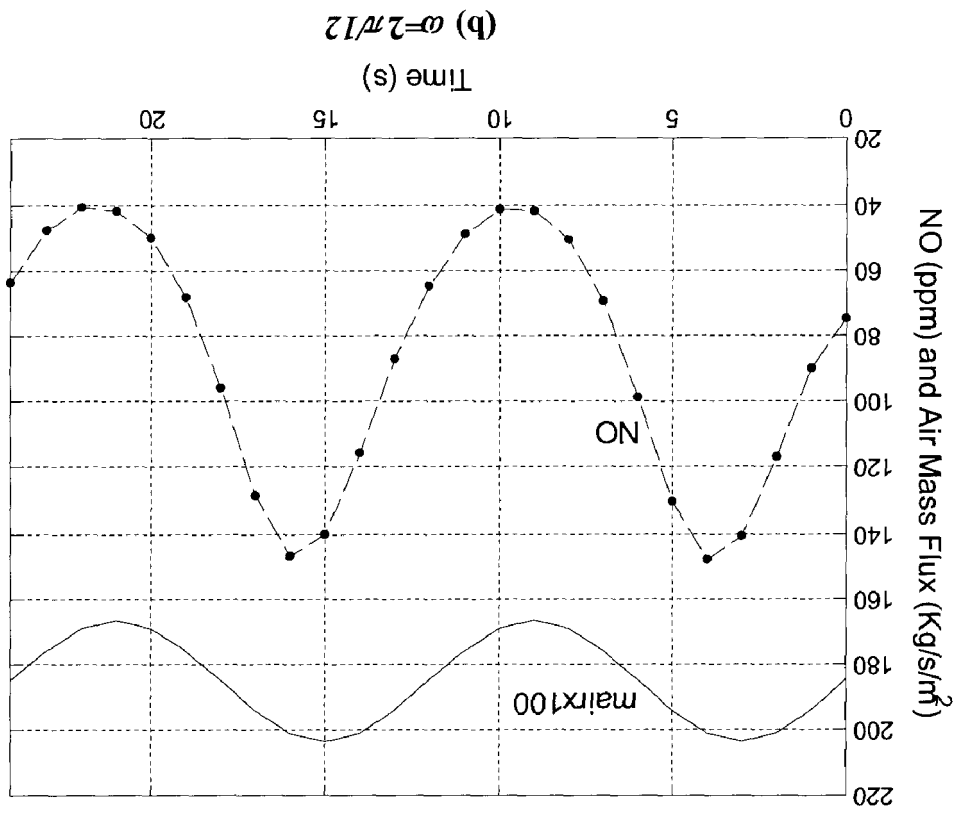
in-phase as shown in Fig. 2.6 (b) and (c). However, the phase shift increases as the frequency of the perturbation increases. For example, At a high frequency with $\omega = 2\pi/0.48$, the input signal fluctuation and the output NO variation are out of phase as shown in Fig. 2.6 (a). However, the amplitude of the variation in output NO at a high frequency is much smaller than that at a low frequency as shown in Fig. 2.6. In fact, such information is very important as far as the real-time control system is concerned because it represents the dynamic nature of the furnace. The detailed numerical simulation results at $\omega = 2\pi/150$ are summarized in Table 2.3. It can be seen from the table that when the NO emission is 210 ppm (at $t = 37.5$ s), the O₂ mass fraction at the outlet of the furnace is 0.0405, which is 52% higher than the value of 0.0267 at the normal operating point. Furthermore, the FGR flow rate drops to 0.0052 kg/s, which is less than half the value of 0.012 kg/s at the normal operating point. The increase in O₂ concentration and the decrease in the flow rate of the flue gas recirculation cause the NO emission to increase. When the mass flow rate of the combustion air changes by 10% in negative drift (at $t = 112.5$ s) from the normal operating point, the flow rate of the flue gas recirculation increases to 0.0178 kg/s, which is about 14% of the total gas mass flow entering the furnace. This is slightly higher than the recommended value ($< 12\%$). The flame may be blown off from the stabilizer. Therefore, low frequency drift must be avoided. The results in Table 2.3 also reveal that the fluctuation of the inlet combustion air mass flux does not affect the CO concentration at the furnace outlet. However, the heat output from the furnace does change when the inlet combustion air mass flux fluctuates as shown in Table 2.3. The amplitude of the heat output fluctuation is less than 4% of the value at the furnace normal operating point.

Table 2.3 Effect of the combustion air mass flux for $\omega=2\pi/150$

Time (sec)	Air mass flux (kg/s.m ²)	FGR (kg/s) $\times 10^4$	Peak/Outlet temperature (K)	NO (ppm)	O ₂ Mass fraction $\times 10^2$	CO (ppm)	Heat output (kW)
0	1.8490	121	1976/1367	74.9	2.67	<1	190
12.5	1.9141	90.1	2009/1366	112	3.10	<1	187
25	2.0091	63.5	2041/1367	169	3.66	<1	185
37.5	2.0339	52.0	2056/1366	210	4.05	<1	183
50	2.0091	61.2	2055/1366	204	4.12	<1	183
62.5	1.9414	87.0	2032/1368	159	3.85	<1	185
75	1.8490	120	1994/1369	99.3	3.28	<1	189
87.5	1.7566	150.6	1953/1369	57.2	2.55	<1	192
100	1.6889	171.1	1923/1367	32.8	1.86	<1	193
112.5	1.6641	178.4	1905/1365	23.4	1.40	<1	193
125	1.6889	172.7	1905/1363	22.6	1.27	<1	193
137.5	1.7566	152.6	1926/1363	31.0	1.50	<1	192
150	1.8490	123	1956/1365	54.0	2.00	<1	191
162.5	1.9141	90.6	2000/1365	95.7	2.75	<1	188
175	2.0091	63.8	2035/1366	155.6	3.44	<1	185
187.5	2.0339	52.0	2054/1366	199.7	3.92	<1	183
200	2.0091	61.0	2052/1367	199	4.05	<1	183
212.5	1.9414	86.8	2031/1368	155.9	3.81	<1	185
225	1.8490	119.8	1994/1369	98.3	3.26	<1	189
237.5	1.7566	150	1952/1369	56.8	2.54	<1	192
250	1.6889	171	1922/1367	32.6	1.86	<1	194
262.5	1.6641	178	1905/1365	23.3	1.40	<1	193
275	1.6889	172.8	1906/1363	22.6	1.27	<1	193
287.5	1.7566	152.8	1926/1365	30.8	1.50	<1	192
300	1.8490	123.5	1956/1365	53.8	2.00	<1	190



(a) $\omega=2\pi/0.48$



(b) $\omega=2\pi/12$

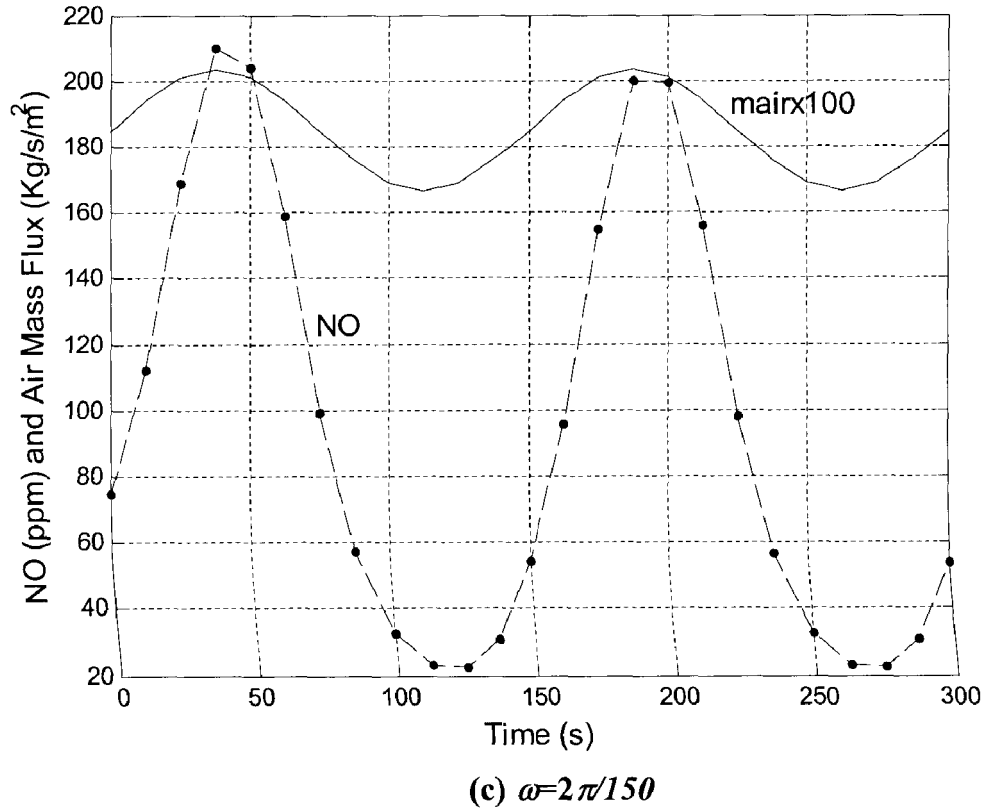


Figure 2.6 NO emission as the combustion air mass flux is varied

2.6.2 Effect of the fluctuation in the combustion air temperature

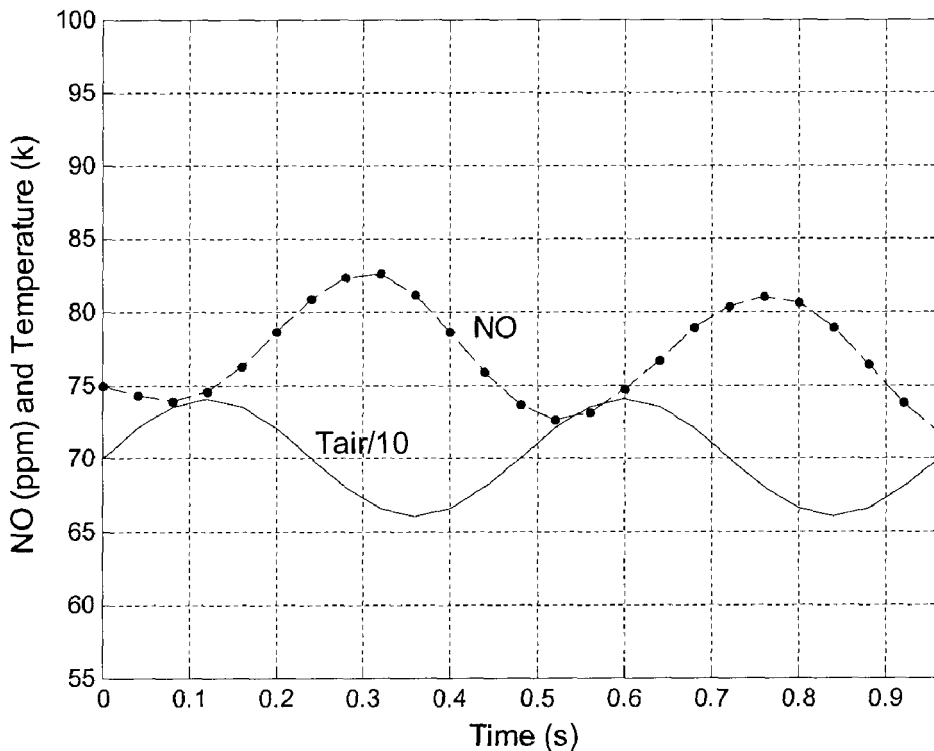
The temperature of the combustion air is assumed to fluctuate sinusoidally around the normal operating conditions as governed by

$$T_{air} = 426.85 + 40 \sin(\omega t) \text{ [}^\circ\text{C]} \quad (2.15)$$

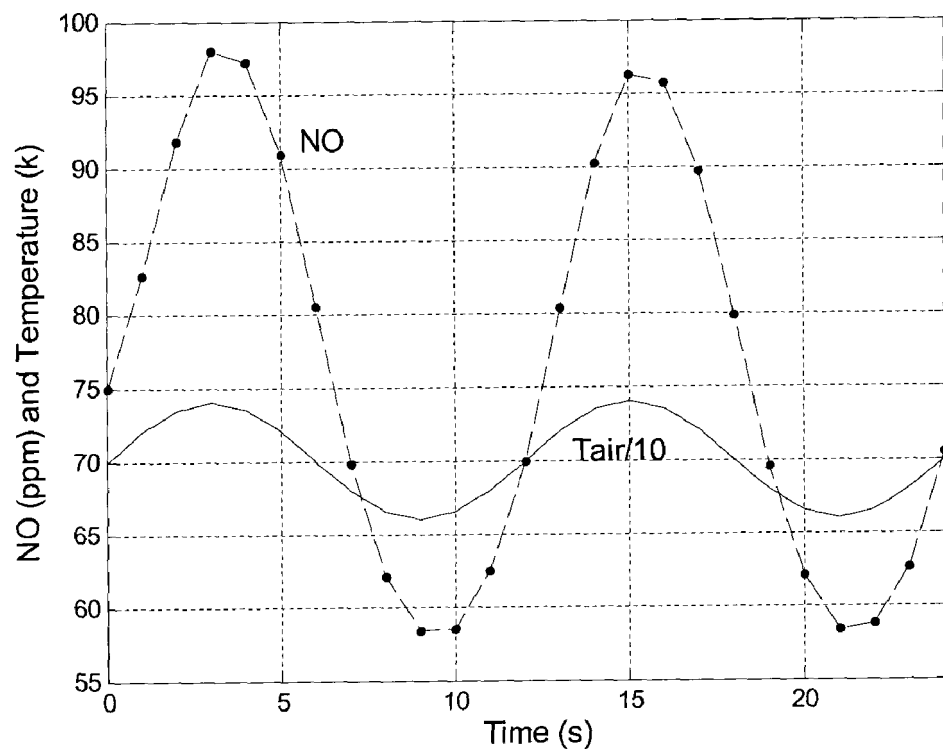
The following frequencies have been considered: $\omega = 2\pi/150, 2\pi/36, 2\pi/12, 2\pi/3.6, 2\pi/2.4, 2\pi/1.2, 2\pi/0.48$, and $2\pi/0.24$ (rad/s). The amplitude of the fluctuation is about 9.4% around the furnace normal operating point. Other input variables/parameters are kept at the furnace normal operating point.

The simulation results for three representative frequencies are shown in Fig. 2.7. The NO emission only fluctuates in the amplitude about 10% of the value at the furnace

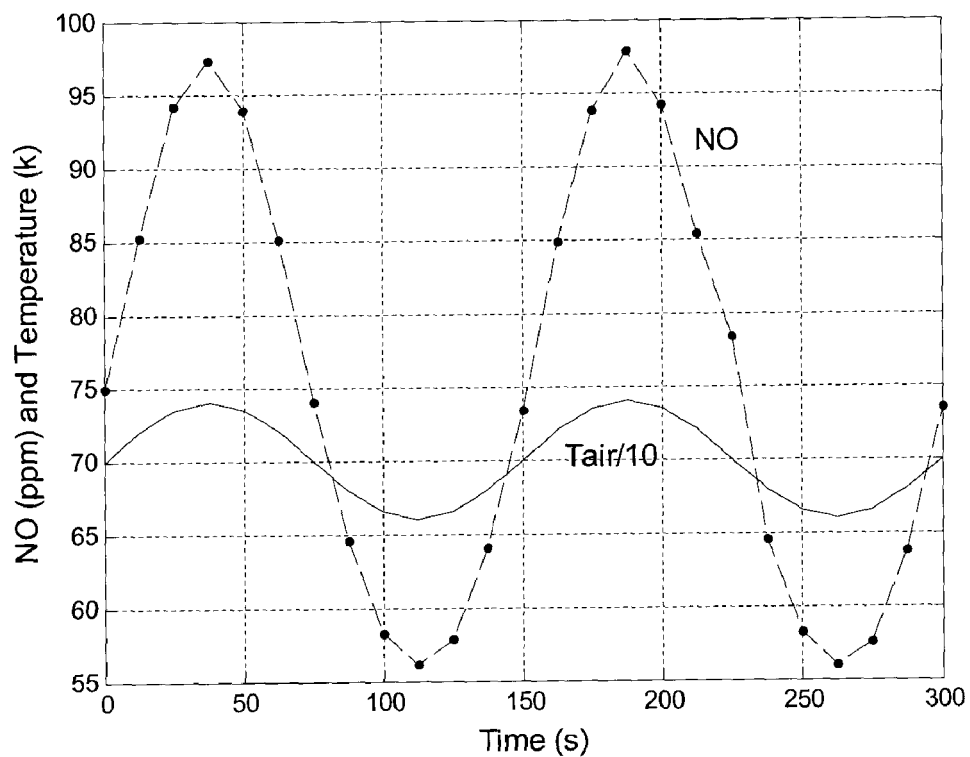
normal operating point at the high frequency ($\omega = 2\pi/0.48$) and about 30% at the low frequency ($\omega = 2\pi/150$). It can be seen that the NO emission is not very sensitive to the fluctuation of the combustion air temperature. This is due to the radiation heat transfer between the flame and the bottom furnace wall, which consumes most of the additional energy due to the temperature increase from the combustion air. Therefore, the flame peak temperature does not increase proportionally to the increase in combustion air temperature. It can also be concluded that the NO emission from the furnace is not sensitive to the fluctuation of the temperature of the recirculated flue gases because its flow rate is only about 10% that of the total flow rate of the combustion air. Thus, the effect of the fluctuation in temperature of the recirculated flue gases can be neglected in the control system analysis without too many adverse consequences in the prediction of NO emission from the furnace.



(a) $\omega=2\pi/0.48$



(b) $\omega = 2\pi/12$



(c) $\omega = 2\pi/150$

Figure 2.7 NO emission as the temperature of the combustion air is varied

From Fig. 2.7, it can be seen that the input signal fluctuation and the output NO variation are in phase at low frequencies as shown in Figs. 2.7 (b) and (c). This is because an increase in the combustion air temperature causes an increase in NO formation and a decrease in the combustion air temperature decreases the NO formation. However, the input signal fluctuation and the output NO variation are out of phase at high frequency as shown in Fig. 2.7 (a). Again, the amplitude of the NO variation at a high frequency is smaller than that at a low frequency as shown in Fig. 2.7.

2.6.3 Effect of the fluctuation in the pressure head of the FGR fan

The variation of the pressure head of the FGR fan can be represented by the following equation:

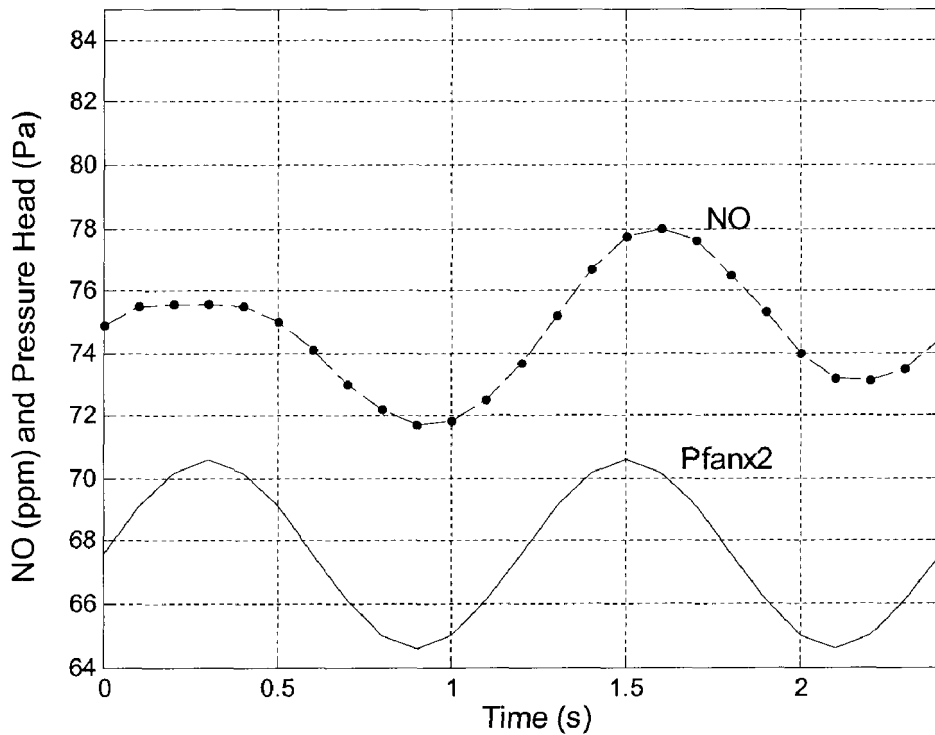
$$P_{fan} = 33.8 + 1.5 \sin(\omega t) \text{ [Pa]} \quad (2.16)$$

where $\omega = 2\pi/150, 2\pi/36, 2\pi/12, 2\pi/3.6, 2\pi/2.4$, and $2\pi/1.2$ (rad/s) have been chosen for the numerical simulations. The amplitude of the fluctuation is about 4.4% around the furnace normal operating point.

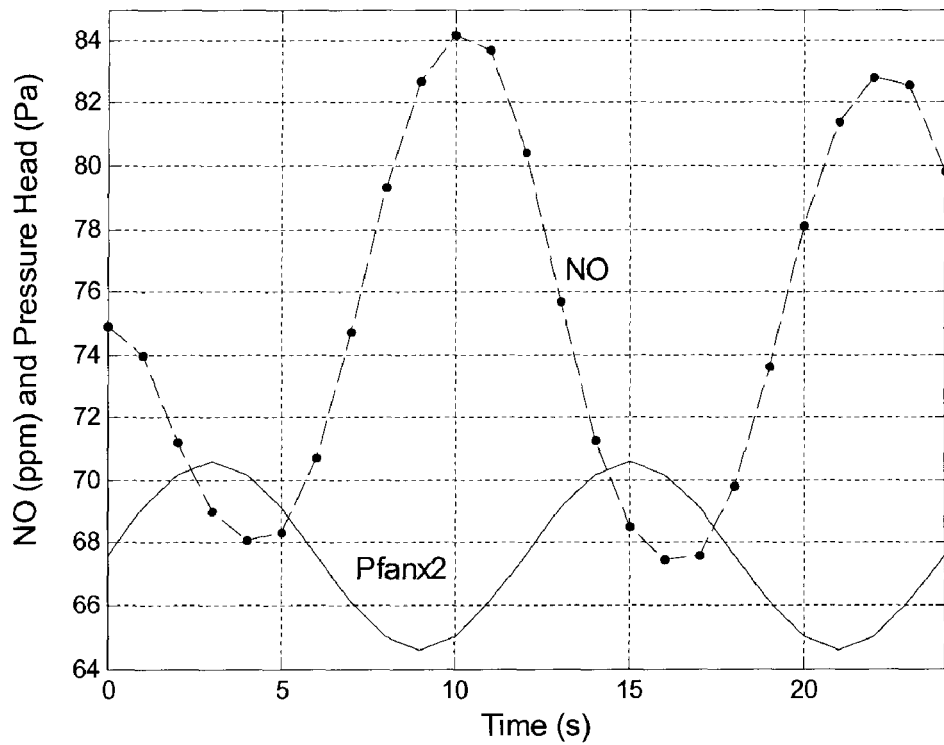
The simulation results at three testing frequencies are shown in Fig. 2.8. The maximum NO emission is less than 85 ppm at all frequencies, which is less than the 14% increase compared with the NO emission at the furnace normal operating point. Therefore, a slight drift in the pressure head of the FGR fan will have a minor effect on the NO emission. The pressure head of the FGR fan increases the flow rate of the recirculated flue gas, which in turn reduces the oxygen concentration. Therefore, the NO emission will be depressed. On the other hand, a decrease in the pressure head of the FGR fan will decrease the amount of flue gas recirculated, which will result in an increase in the NO emission. Hence, at low frequencies, the input signal fluctuation and

the output NO variation are out of phase as shown in Figs. 2.8 (b) and (c). However, at a high frequency, for example, $\omega = 2\pi/1.2$, the input signal fluctuation and the output NO variation are in phase as shown in Fig. 2.8 (a). In fact, as most of physical systems do, the phase shift increases as the frequency of the perturbation increases.

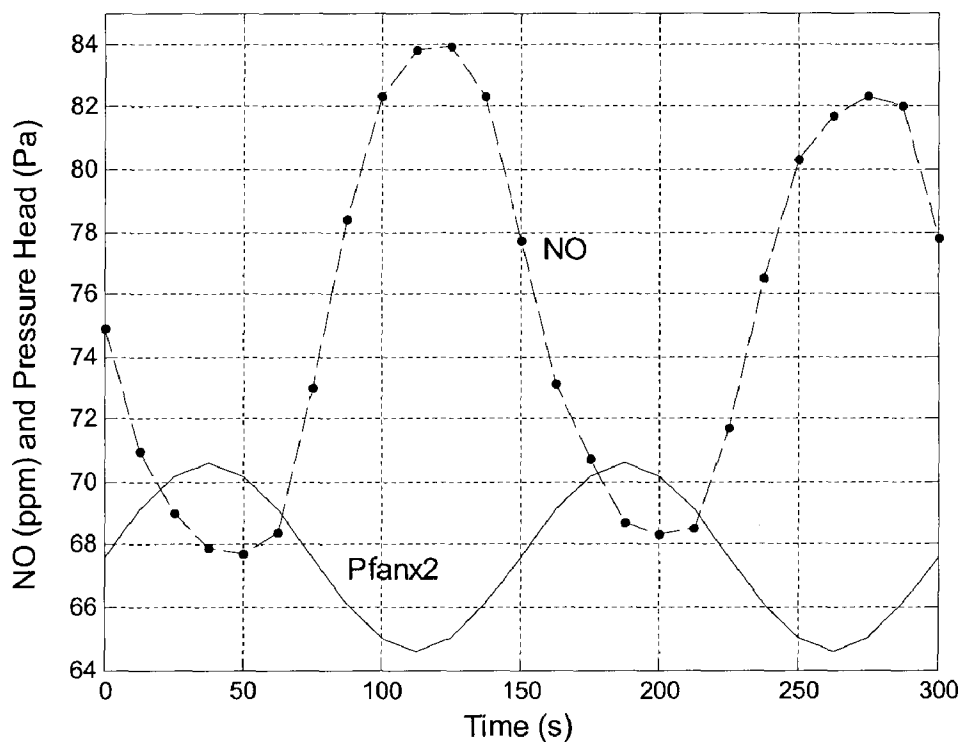
The results shown in Figs. 2.6 to 2.8 indicate that the output NO varies at the same frequency as the input signal fluctuation. This implies that the furnace can be approximated by a linear system around the normal operating point. The higher the frequency, the more phase shift and the less the amplitude of NO fluctuation occur. This means that the furnace, like most of the physical systems, has inertia and lowpass characteristics.



(a) $\omega=2\pi/1.2$



(b) $\omega = 2\pi/12$



(c) $\omega = 2\pi/150$

Figure 2.8 NO emission as the pressure head of the FGR fan is varied

2.7 Conclusions

A FGR furnace has been designed to study the sensitivity of the NO_x emission to the fluctuation of the different furnace input variables. It was concluded that the extraction of a small amount of flue gases for recirculation from the top-right side of the furnace did not affect the main flow field. The use of the FGR can reduce the NO_x emission by 82%. Furthermore, NO_x emission was found to be very sensitive to the fuel injection angle and the fuel injection angle of 0° provides the lowest NO_x emission.

Around the normal operating point, the sensitivity analysis indicates that the NO_x fluctuates at the same frequency as the input variables, and the higher the frequency, the more phase shift and the less the amplitude of the NO_x fluctuation. In other words, the furnace at normal operating conditions can be approximated by a linear system with low-pass frequency characteristics.

NO_x changes drastically when the input combustion air mass flux fluctuates at a low frequency. The NO_x emission is almost tripled when the mass flux of the combustion air makes only 10% positive drift from the normal operating point. Therefore, a stable combustion air mass flow rate is the key to achieve a low NO_x emission furnace. However, it is also found that the NO_x emission is not very sensitive to the temperature of the combustion air. The drift of the pressure head of the FGR fan has the least influence on the NO_x emission.

Acknowledgement

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CHAPTER THREE¹

Dynamic Model Construction and Validation of the FGR Furnace for NO_x Emission Control

3.1 Introduction

As more demanding air pollution standards are placed on combustion systems, there is an increased effort to apply advanced control technologies to meet the stringent demands. Preliminary studies have concluded that ACC (Active Combustion Control) is particularly desirable for optimizing combustion processes, alleviating combustion instabilities, and most of all, reducing the emissions such as NO_x and CO [1].

The basic approach of ACC is to measure the appropriate furnace variables in real-time and feedback such information to regulate the controllable furnace inputs. Depending on the dynamic properties of the combustion process, the combustion control system will adjust the controller outputs automatically to meet the desired furnace performance requirements. The performance may include flame stability, a range of temperature variations, fuel efficiency, and emission levels. Emphasis is placed on the reduction of NO_x emission in the current study. Comprehensive coverage of NO_x control techniques can be found in two excellent survey papers [2, 3]. It is important to note that, in the design of a highly effective ACC system two types of information are essential. One is the knowledge of the dynamic behavior of the furnace, and in particular, the input and output characteristics; the other is the desirable feedback control law needed to

¹ The version of this chapter has been submitted to J. of Combustion Science and Technology in August, 2003

achieve the specified performance. The former is a modeling issue, and the latter is a control synthesis issue. This chapter concentrates on the former.

Since the combustion process in industrial furnaces is a complex process due to the interaction between turbulence and chemical reactions, the modeling usually starts from the conservation equations of mass, momentum and energy. These models are generally in the form of nonlinear partial differential equations [4]. CFD (Computational Fluid Dynamics) methods have been used to simulate the combustion process in industrial furnaces by solving these equations [5, 6]. The CFD methods have also proved to be useful in studying different burner configurations for furnace designs. However, from a real-time feedback control point of view, detailed CFD modeling has very limited use, as most of the control system synthesis techniques rely on input-output models described in terms of ordinary differential equations or transfer functions at a given furnace operating condition. In order to take full advantage of the vast amount of available feedback control techniques, it is highly desirable to model the furnace in terms of transfer functions for the purpose of furnace control. Unfortunately, little work has been done in this regard. The advantage of constructing a transfer function model from CFD simulation results is that it allows someone to study the operational aspects of the furnace without physically constructing it. By doing so, combustion engineers can refine the furnace design as well as its associated control systems.

The main objective of this work is to present a unique procedure to derive transfer function representations of an industrial reheating furnace with external flue gas recirculation. The procedure involves CFD solutions of fundamental equations that describe the fluid flow, heat transfer and chemical reactions in the furnace. The inputs to

the furnace consist of superimposed low amplitude sinusoidal signals of different frequencies to the steady-state normal furnace inputs. The frequency domain information is then used to construct the dynamic representations among three independent furnace inputs: the flow rate of the combustion air, the temperature of the combustion air, and the pressure head of the flue gas recirculation fan and two outputs: NO and O₂ concentrations.

The advantage of having transfer function representations of the furnace is that they can be directly used with both modern and classical control system design techniques to improve the operational performance of the furnace. The contribution of this work lies in the fact that it provides a unique approach to furnace model construction based on CFD analysis and system identification techniques. The work reported herein provides a bridge between the traditional tools used in combustion process analysis, i.e. CFD, and transfer function representations common among the control system community. Such a bridge is extremely important in the future development of advanced control technologies for active combustion controls.

The emission of NO_x, which is a collective name for NO and NO₂, from combustion processes in industrial furnaces or boilers is a major pollutant source. NO_x not only causes nitric acid rain, but also depletes ozone in the stratosphere. It is estimated that over 95 percent of all man-made NO_x that enters the atmosphere is produced by combustion of various fuels [7]. To protect the environment and future generations, the governments of many countries have established increasingly strict laws to limit the amount of NO_x that can be released into the environment without a penalty. According to

the Canadian Environment Quality Guidelines (2003) [8], the release of NO_x must be within the following limits for a furnace or a boiler:

1 hour: 400-1000 µg/m³ (NO_x/Flue gas)

24 hours: 200-300 µg/m³ (NO_x/Flue gas)

1 year: 60-100 µg/m³ (NO_x/Flue gas)

Clearly, it is very important to develop effective ways to reduce NO_x emission in combustion processes. One commonly used method to reduce the thermal NO_x formation in the combustion process in a furnace is to use flue gas recirculation, in which a portion of the flue gases exhausted from the furnace is cooled down, pumped back to the inlet, and mixed with the fresh combustion air before entering the furnace. There are two main reasons why NO_x formation can be reduced when the FGR is used. First, the peak flame temperature in the furnace can be lowered due to the increased amount of cold gas entering the furnace. Secondly, the oxygen concentration in the flame envelope can be diluted by the recirculated flue gases. In practice, the amount of the flue gases recirculated is limited by the combustion stability at low oxygen concentration. The FGR is usually limited to 20% for gas-fired furnaces and 10~12% for oil-fired furnaces. The reduction in NO_x can be as high as 45% to 80% at the high recirculation rates. Therefore, the FGR is an effective way to reduce the NO_x emissions. As well the FGR can be classified into two types based on how the flue gas recirculation is carried out - internal and external. Internal recirculation of flue gases requires intensive air swirling at the burner. External recirculation uses an external fan and a damper to control the amount of flue gases recirculated. This chapter focuses on the external flue gas recirculation since most industrial furnaces are still equipped with conventional burners and it is easier to retrofit an existing furnace with a damper and a recirculation fan. FGR

furnaces usually operate at low excess oxygen concentration in practice. A small amount of drift from the normal operating point could cause significant change in NO_x emission. Further, the flow rate of the recirculation flue gases is sensitive to fluctuations of the inlet airflow rate [9].

This chapter is organized as follows: the configuration of the furnace and its operating condition under investigation are described in the next section. The mathematical models that describe the fluid flow, heat transfer, and combustion process are summarized in Section 3.3. The control model structures and some CFD simulation results are presented in Sections 3.4 and 3.5, respectively. A set of transfer functions are constructed based on the CFD simulation data in Section 3.6 with model validation in Section 3.7.

3.2 Furnace Configuration

Figure 3.1 illustrates the configuration of the furnace used in this study. The dimensions of the furnace are $3.75 \times 1.4 \times 1.4 \text{ m}^3$. The burner is located at the center of the left-side wall and the exhaust outlet is located at the center of the right-side wall of the furnace. A flue gas recirculation pipe 0.15 m in diameter is installed to recirculate the flue gases from the outlet back to the inlet of the furnace. The recirculation flue gases are extracted from the center of the top-right side of the furnace as shown in the figure. The dimensions of the mixing box at the inlet of the furnace are $0.3 \times 0.3 \times 0.8 \text{ m}^3$. The combustion air and the recirculation flue gases enter the mixing box in the same direction so that they can be mixed symmetrically before entering the furnace to avoid any potential deviation of the flame in a particular direction inside the furnace. The stabilizer at the center of the right-side wall of the mixing box is simplified as a round plate of 0.07

m in diameter. A diffuser with the inlet diameter of 0.2 m and exit diameter of 0.35 m is used between the mixing box and the furnace as shown in Fig. 3.1. The fuel and gases are injected into the diffuser through a concentric pipe with an inner diameter 0.07 m and outer diameter of 0.2 m. The fuel is injected through the center pipe and gases are injected through the annular area between the two pipes. This is a non-premixed combustion process.

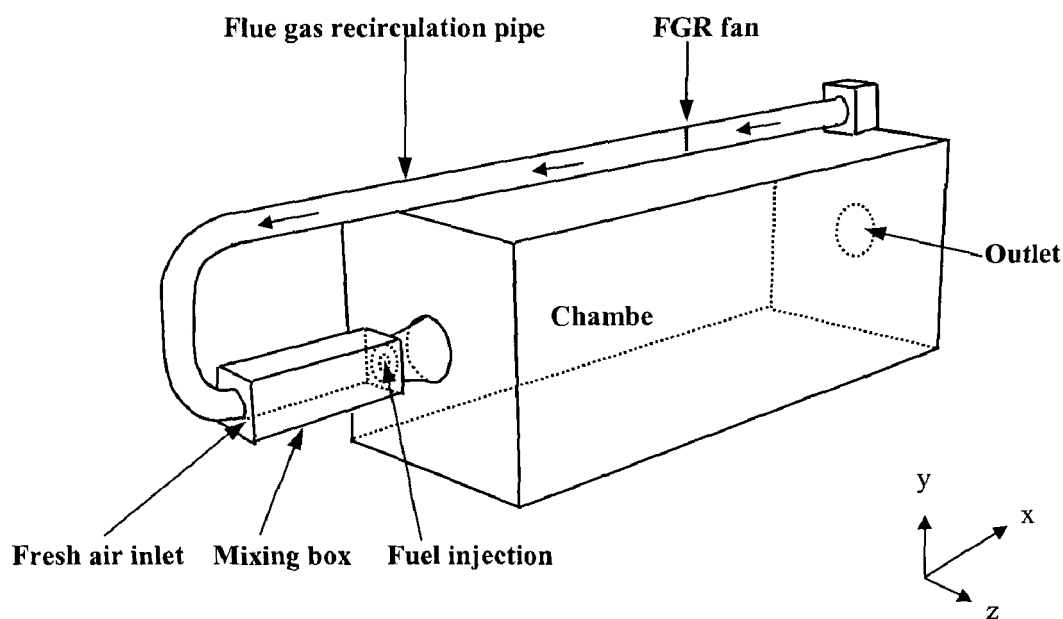


Figure 3.1 Configuration of the FGR furnace

The main operating parameters at the furnace operating point are given in Table 3.1. Liquid propane is used as the fuel. The heat input to the furnace from the fuel is 345 kW. The bottom furnace wall is set at a constant temperature of 1100 K and the rest of the walls are assumed to be insulated. The combustion air is preheated to a temperature of 700 K before it enters the furnace.

Table 3.1 The normal furnace operating conditions

Fuel (propane, C ₃ H ₈)	Flow rate	0.0075 kg/s
	Temperature	300 K
	Heating value	345 kW
Input combustion air	Flow rate	0.135 kg/s (or 1.849 kg/m ² ·s)
	Temperature	700 K (or 426.85°C)
Heat output	190 kW from the bottom of the furnace	
Pressure head of the FGR fan	33.8 Pa	
Flue gas recirculation rate	0.012 kg/s	
Temperature at the bottom wall	1100 K	
Temperature at the FGR pipe	700K	

3.3 Mathematical Models

Instead of conducting experiments on the furnace itself, a numerical method is employed to simulate the fluid flow, heat transfer, and combustion process in the furnace based on the conservation equations of mass, momentum, and energy. The Favre-averaged conservation equations of mass, momentum and energy are given as [10, 11]:

$$\frac{\partial \rho}{\partial t} + \frac{\partial}{\partial x_i}(\tilde{\rho} \bar{u}_i) = 0 \quad (3.1)$$

$$\frac{\partial}{\partial t}(\tilde{\rho} \bar{u}_i) + \frac{\partial}{\partial x_j}(\tilde{\rho} \bar{u}_i \bar{u}_j) = \frac{\partial}{\partial x_j} \left[\mu \left(\frac{\partial \bar{u}_i}{\partial x_j} + \frac{\partial \bar{u}_j}{\partial x_i} \right) - \left(\frac{2}{3} \delta_{ij} \mu \frac{\partial \bar{u}_l}{\partial x_l} \right) - \frac{\partial \tilde{P}}{\partial x_i} + \frac{\partial}{\partial x_j} \left(-\tilde{\rho} \bar{u}'_i \bar{u}'_j \right) \right] \quad (3.2)$$

$$\frac{\partial}{\partial t}(\tilde{\rho} \bar{h}) + \frac{\partial}{\partial x_i}(\tilde{\rho} \bar{u}_i \bar{h}) = \frac{\partial}{\partial x_i} \left(\frac{\mu_t}{\sigma_h} \frac{\partial \bar{h}}{\partial x_i} \right) + \bar{S}_h \quad (3.3)$$

where x_i is the position vector, u_i is velocity vector, ρ is density, P is pressure, μ is molecular viscosity, μ_t is turbulent viscosity, h is static enthalpy, and σ_h is the turbulent Prandtl number. The source term, S_h , in Eq. (3.3) consists of sources of enthalpy due to chemical reactions and radiation. The quantities with an overbar are the Favre-averaged values and the quantities with a tilde represent the Reynolds-averaged value. The prime denotes the fluctuation about the Favre average.

The Reynolds stresses, $-\tilde{\rho} \overline{u'_i u'_j}$, in Eq. (3.2) must be modeled in order to close Eq. (3.2). The Boussinesq hypothesis is used to relate the Reynolds stresses to the mean velocity gradients:

$$-\tilde{\rho} \overline{u'_i u'_j} = \mu_t \left(\frac{\partial \overline{u_i}}{\partial x_j} + \frac{\partial \overline{u_j}}{\partial x_i} \right) - \frac{2}{3} (\tilde{\rho} k + \mu_t \frac{\partial \overline{u_i}}{\partial x_i}) \delta_{ij} \quad (3.4)$$

$$\mu_t = \tilde{\rho} C_\mu \frac{k^2}{\varepsilon} \quad (3.5)$$

where k and ε are the turbulent kinetic energy and its dissipation rate, respectively. The values of k and ε are obtained from the solution of their transport equations. For the standard k - ε model [12], k and ε transport equations are expressed as,

$$\frac{\partial}{\partial t} (\tilde{\rho} k) + \frac{\partial}{\partial x_i} (\tilde{\rho} \overline{u_i k}) = \frac{\partial}{\partial x_i} \left(\frac{\mu_t}{\sigma_k} \frac{\partial k}{\partial x_i} \right) + G_k - \tilde{\rho} \varepsilon \quad (3.6)$$

$$\frac{\partial}{\partial t} (\tilde{\rho} \varepsilon) + \frac{\partial}{\partial x_i} (\tilde{\rho} \overline{u_i \varepsilon}) = \frac{\partial}{\partial x_i} \left(\frac{\mu_t}{\sigma_\varepsilon} \frac{\partial \varepsilon}{\partial x_i} \right) + C_1 \frac{\varepsilon}{k} G_k - C_2 \tilde{\rho} \frac{\varepsilon^2}{k} \quad (3.7)$$

where $G_k = \mu_t \left(\frac{\partial \overline{u_j}}{\partial x_i} + \frac{\partial \overline{u_i}}{\partial x_j} \right) \frac{\partial \overline{u_i}}{\partial x_i}$, $C_1 = 1.44$, $C_2 = 1.92$, $C_\mu = 0.09$, $\sigma_k = 1.0$ and $\sigma_\varepsilon = 1.3$.

As near wall boundary conditions, values of k and ε at the first grid node are obtained using semi-empirical formulas known as standard wall functions [13]. Wall functions are used to bridge the viscosity-affected region between the wall and the fully turbulent region.

The effect of turbulent fluctuations on combustion is accounted for with an assumed-shape probability density function (PDF), the β -PDF [10, 14]. The P-1 model [15, 16] was used to calculate the radiation heat transfer at first. However, it did not provide a reasonable temperature distribution in the flue gas recirculation pipe due to the small local optical thickness in the pipe. Therefore, the discrete transfer radiation model (DTRM) [17, 18] is employed for the calculation of the radiation heat transfer. The DTRM is a relatively simple model and can be applied to a wide range of optical thicknesses. The assumption of gray radiation is acceptable for all inner surfaces of the furnace. The weighted-sum-of-gray-gases model [16, 19] is used to calculate the absorption coefficient. The chemistry model based on the chemical equilibrium concept, which assumes that the chemical reaction is rapid enough for chemical equilibrium to always exist at the molecular level, is employed to specify the instantaneous thermochemical state of the combustion mixture. The liquid fuel injection is modeled by a discrete phase model. The turbulent dispersion of liquid fuel droplets and other forces on the liquid fuel phase are neglected because the liquid fuel droplets last for a very short period of time and exist only in a very small region near the inlet of the furnace.

Both NO and NO₂ are formed during a combustion process. Generally, the concentration of NO₂ is negligible in comparison to NO concentration. It is usually considered as a transient intermediate species that exists only at flame conditions, and it

is subsequently converted back into NO in the post-flame region. In gas- or oil-fired industrial furnaces, a major portion of the NO generated is the thermal NO. Thus, only the thermal NO is considered in this work. The mean NO concentration is obtained by solving its transport equation based on the flow field and combustion solution from the main combustion simulations. The temperature PDF approach [20] is used to account for the effect of turbulence on the NO formation. The CFD software FLUENT (2001) [21] is used for the CFD simulations.

3.4 Input and Output Representation of the Furnace

In order to construct a dynamic model suitable for real-time NO emission control, the frequency domain approach is employed to describe the variables that affect the NO formation in the furnace. As shown in Fig. 3.2, the input variables to the furnace are the fluctuation of mass flux (mass flow rate per unit flow area) of the combustion air, m_{air} , the fluctuation of temperature of the combustion air, T_{air} , and the fluctuation of pressure head of the FGR fan, P_{fan} . The output variables are the fluctuation of mole fraction of NO, y_{NO} , and the fluctuation of the mass fraction of O₂, f_{O2} , at the outlet of the furnace.

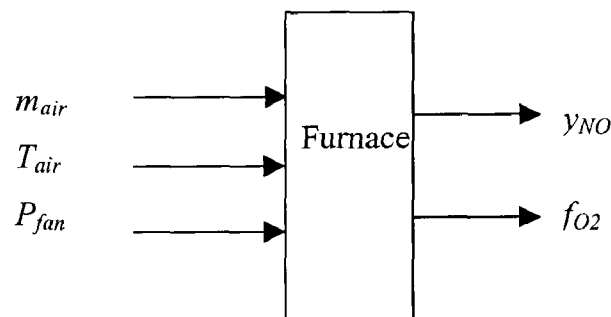


Figure 3.2 Dynamic model structure and input/output variables

The frequency domain model consists of frequency responses of the furnace at different operating conditions. The frequency responses are measured by adding sinusoidal signals of different frequencies onto the furnace input variables. These sinusoidal signals are expressed as:

$$\begin{aligned} m_{air} &= 0.1849 \sin(\omega t) \text{ [kg/m}^2\text{.sec]} \\ T_{air} &= 40 \sin(\omega t) \text{ [K]} \\ P_{fan} &= 1.5 \sin(\omega t) \text{ [Pa]} \end{aligned} \tag{3.8}$$

where ω is the frequency in rad/sec and t is time in seconds.

It is important to mention that the combustion in the furnace is a complex nonlinear process. Using the signals in Eq. (3.8), only a linear approximation is obtained. The constructed control models are only valid around given furnace operating conditions. This does not pose a problem for control system design if the control objective is to regulate the furnace around a given operating point.

3.5 CFD Simulation Results

The CFD simulations of the combustion process in the furnace are carried out by numerically solving the governing equations, Eqs. (3.1), (3.2), (3.3), (3.6), and (3.7), for the fluid flow and heat transfer under the following inlet conditions:

$$\begin{aligned} (m_{air})_{inlet} &= 1.849 + 0.1849 \sin(\omega t) \text{ [kg/m}^2\text{.sec]} \\ (T_{air})_{inlet} &= 700 + 40 \sin(\omega t) \text{ [K]} \\ (P_{fan})_{inlet} &= 33.8 + 1.5 \sin(\omega t) \text{ [Pa]} \end{aligned} \tag{3.9}$$

The constant terms in Eq. (3.9) correspond to the inputs at the furnace normal operating point.

CFD simulations are performed for six to eight different frequencies ranging from 0.04 to 26 rad/sec. The following two issues are considered when selecting these frequencies: (i) the bandwidth of the furnace; and (ii) the capability of the CFD models to handle rapidly changing signals. The range of frequencies for the input signals is selected based on a priori knowledge of the furnace.

Since the inlet conditions are time-dependent, CFD simulations are performed at each time step and the simulation results, including the concentrations of NO and O₂ at the furnace outlet, are recorded at every time step. It is important to point out that the concept of time step in CFD is different from that of the sampling interval in real-time control. The time step in CFD is the discretization time used to discretize the transient terms in the governing equations for fluid flow and heat transfer. It must be small enough to obtain an accurate numerical solution. On the other hand, the sampling interval in control system implementation is the discrete time step that the controller uses to take the measurement and generate the corresponding control signals. The CFD time step is much smaller than the sampling interval in most cases. Normally, there are several time steps within a single sampling interval.

The gain is defined as follows:

$$G = \frac{(y_{\max} - y_{\min}) / y_0}{(u_{\max} - u_{\min}) / u_0} \quad (3.10)$$

y_{\max} , y_{\min} are the maximum and minimum output variables, respectively; u_{\max} , u_{\min} are the maximum and minimum input variables, respectively and they are all in the same period.

y_0 and u_0 are the output and input variables at the steady original operating point respectively.

The gain and phase differences between the selected furnace input and the furnace output from the CFD simulations are calculated. The results for the mass fraction of O_2 at the furnace outlet are listed in Table 3.2.

Table 3.2 Gain and phase characteristics for O_2 at the furnace outlet

Input Variables	Frequency rad/s	Phase Delay (Degree)	Gain
Combustion air mass flux	0.0419	10	5.200
	0.1745	35	2.507
	0.5236	60	1.496
	1.745	100	0.658
	2.992	157	0.416
	5.236	240	0.187

The mass fraction of O_2 at the furnace outlet is almost independent of the changes in the pressure head of the FGR fan and the combustion air temperature at the furnace inlet. Therefore, it can be considered as decoupled from these two inputs and only the results related to the combustion air mass flux are listed in Table 3.2. The frequency responses for the mole fraction of NO at the furnace outlet are listed in Table 3.3. It is observed from Tables 3.2 and 3.3 that the furnace outputs are sensitive to changes in the inputs in the frequency range of 0.04 – 13 rad/sec. When the frequency extends beyond

13 rad/sec, very few changes are observed at the outputs. This means that the furnace is a low-pass system.

Table 3.3 Gain and phase characteristics for NO at the furnace outlet

Input Variables	Frequency rad/s	Phase Delay (Dgree)	Gain
Combustion air mass flux	0.0419	12	11.812
	0.1745	20	8.058
	0.5236	30	7.044
	1.745	60	4.948
	2.992	103	3.542
	5.236	120	1.807
	8.055	120	0.940
	13.09	135	1.273
Combustion air temperature	0.0419	6	2.958
	0.1745	10	2.993
	0.5236	15	2.765
	1.745	40	2.457
	2.618	60	2.246
	5.236	105	1.334
	13.09	135	0.770
	26.18	180	0.804
Pressure head of the FGR fan	0.0419	12	2.346
	0.1745	20	2.663
	0.5236	45	2.512
	1.745	90	1.820
	2.618	120	1.414
	5.236	210	0.737

3.6 Construction of the Transfer Functions

Based on the frequency response information, it is concluded that the dynamic model of the furnace can be represented in terms of the following general transfer function structure:

$$G(s) = \frac{b_6s^6 + b_5s^5 + b_4s^4 + b_3s^3 + b_2s^2 + b_1s + b_0}{a_6s^6 + a_5s^5 + a_4s^4 + a_3s^3 + a_2s^2 + a_1s + a_0} \quad (3.11)$$

The constants, a and b , in Eq. (11) are then obtained using the least squares parameter estimation technique with appropriate dynamic compensations and the frequency responses given in Tables 3.2 and 3.3. The transfer function from the mass flux of the combustion air at the furnace inlet to the mass fraction of O_2 at the furnace outlet can be expressed as:

$$G(s)_{O_2} = \frac{8.3875s^2 + 36.594s + 46.590}{s^5 + 3.1926s^4 + 27.868s^3 + 37.260s^2 + 78.147s + 10.000} \quad (3.12)$$

Similarly, the transfer function from the mass flux of the combustion air at the furnace inlet to the mole fraction of NO at the furnace outlet is found to be:

$$G(s)_{air\ mass} = \frac{-0.7532s^6 + 5.6356s^5 - 21.589s^4 + 423.76s^3 + 494.10s^2 + 2930.0s + 320.37}{s^6 + 4.3640s^5 + 62.070s^4 + 136.12s^3 + 402.91s^2 + 408.38s + 25.090} \quad (3.13)$$

The transfer function from the temperature of the combustion air at the furnace inlet to the mole fraction of NO at the furnace outlet can be represented by:

$$G(s)_{air\ temp} = \frac{-23.6270s^3 - 133.77s^2 + 2398.2s + 20890}{s^4 + 39.555s^3 + 900.74s^2 + 3972.1s + 7478.8} \quad (3.14)$$

Finally, the transfer function from the pressure head of the FGR fan to the mole fraction of NO at the furnace outlet is:

$$G(s)_{fan} = \frac{7.1681s - 63.801}{s^3 + 4.6133s^2 + 25.700s + 22.654} \quad (3.15)$$

Caution is advised when estimating the transfer functions as there could be multiple transfer functions with orders ranging from third to sixth, which could provide a satisfactory match for the recorded frequency response data. Effort has been made to ensure that (i) the transfer function obtained must correspond to a stable system, i.e. the real parts of all the poles must be negative and (ii) the frequency responses of the model must be in good agreement with the results obtained from the CFD simulations. All of the above four transfer functions satisfy these two conditions. The Bode plots of these transfer functions are shown in Appendix A.

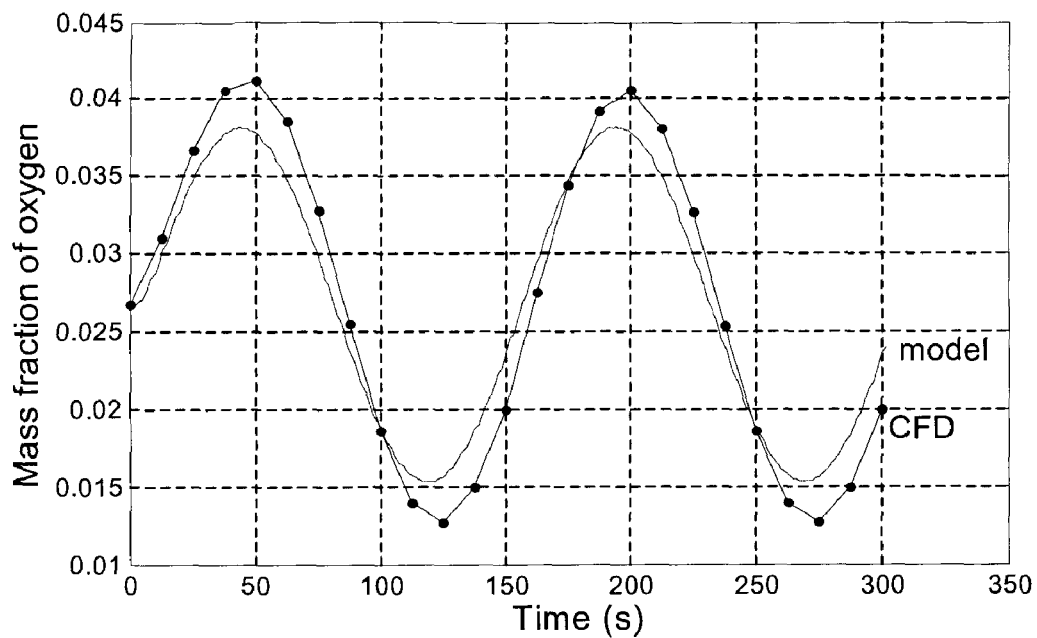
Finally, the dynamic relationships between the furnace input and output variables can be represented by the following linear model:

$$\begin{bmatrix} y_{NO}/75.58 \\ f_{O_2}/0.02674 \end{bmatrix} = \begin{bmatrix} G(s)_{air\ mass} & G(s)_{air\ temp} & G(s)_{fan} \\ G(s)_{O_2} & 0 & 0 \end{bmatrix} \begin{bmatrix} m_{air}/1.849 \\ T_{air}/426.85 \\ P_{fan}/33.8 \end{bmatrix} \quad (3.16)$$

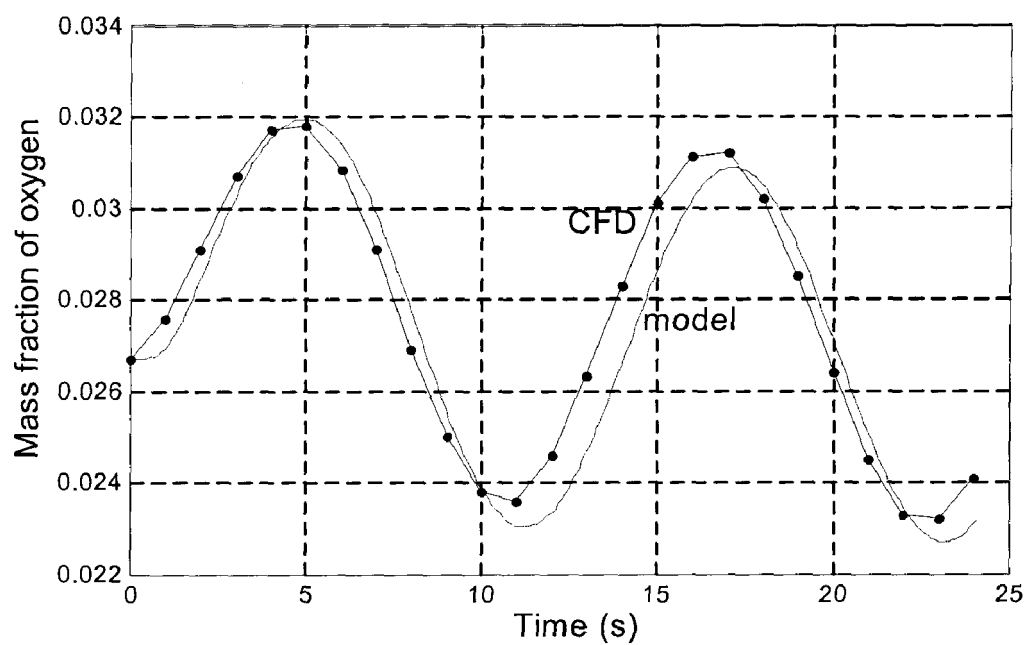
The constant terms in Eq. (3.16) correspond to the inputs and outputs at the furnace normal operating point.

3.7 Validation of the Dynamic Models

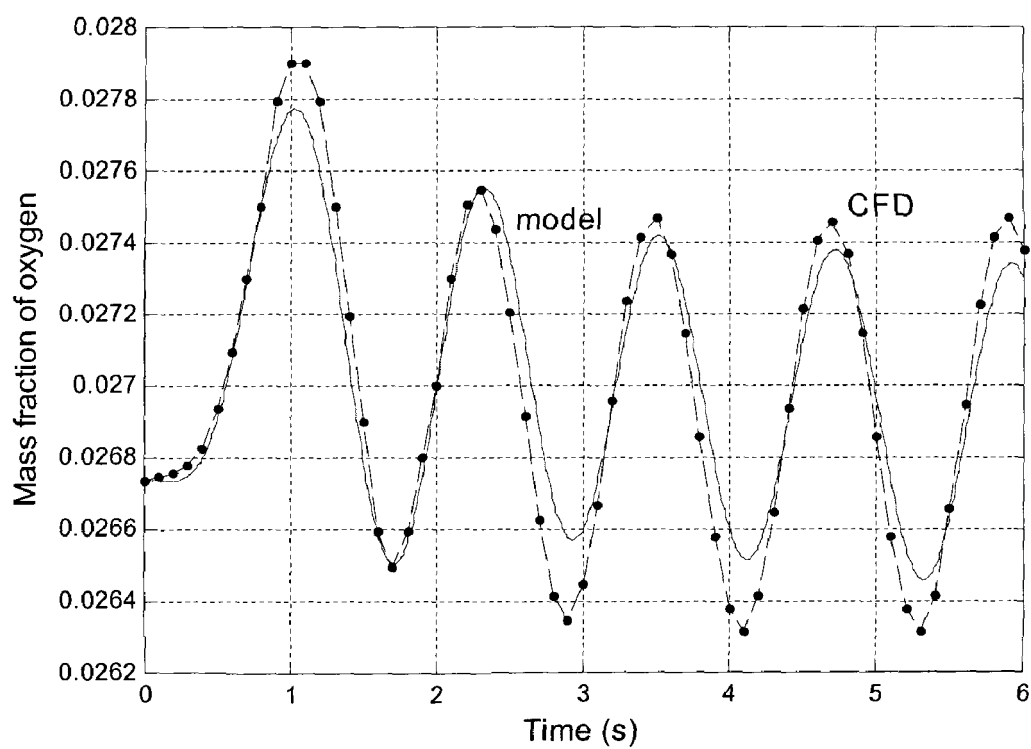
The comparison of the results obtained by the CFD simulations with those generated from the constructed dynamic models (Eqs. (3.12)-(3.15)) at different frequencies are presented in Figs. 3.3 to 3.6. The legends, “CFD” and “model”, in the figures denote the results obtained by CFD simulations and those generated by the dynamic models, respectively. In all the figures, dotted lines represent the CFD simulation results and solid lines represent the results generated from the constructed dynamic models.



(a) $\omega=2\pi/150$



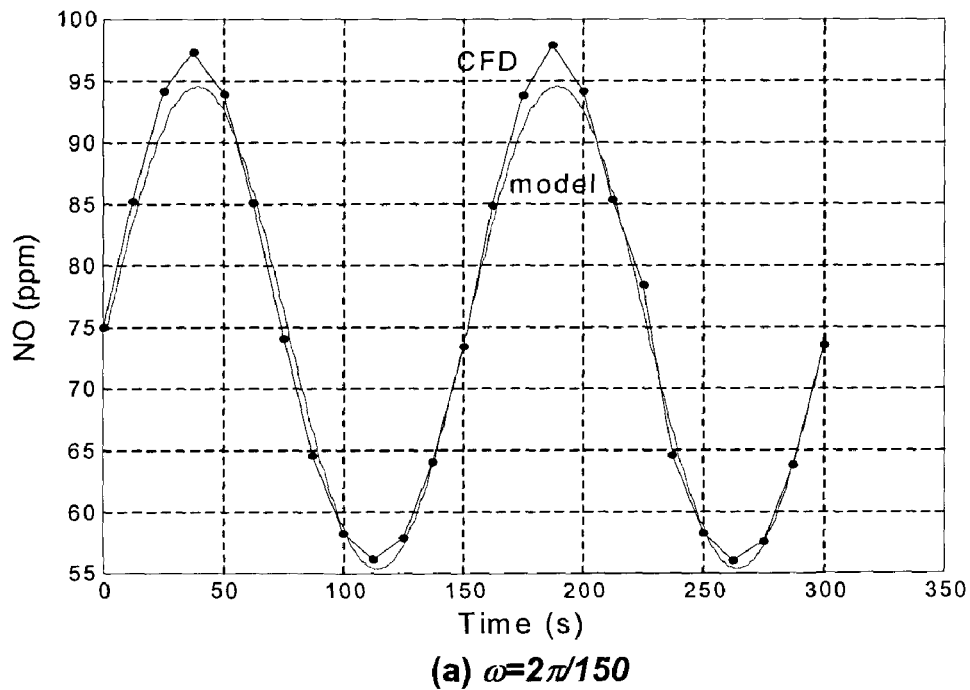
(b) $\omega=2\pi/12$



(c) $\omega=2\pi/1.2$

Figure 3.3 Variation of O_2 at the furnace outlet relative to the combustion air mass flux

It can be seen from Fig. 3.3 that the estimation of the mass fraction of O_2 by the dynamic model is in an excellent agreement with the CFD simulations. The relative error in amplitudes is less than 9% and the difference in phase is very small at the low frequency ($\omega = 2\pi/150$). The phase shift increases slightly at the middle frequency ($\omega = 2\pi/12$). However, the maximum error which occurs at $t=15$ sec is still less than 5%. The model is very accurate at the high frequency ($\omega = 2\pi/1.2$) although more cycles are needed to get a stationary fluctuation due to the low pass dynamic nature of the furnace. These results show that the constructed dynamic model is reasonably accurate for the estimation of the mass fraction of O_2 at the furnace outlet.



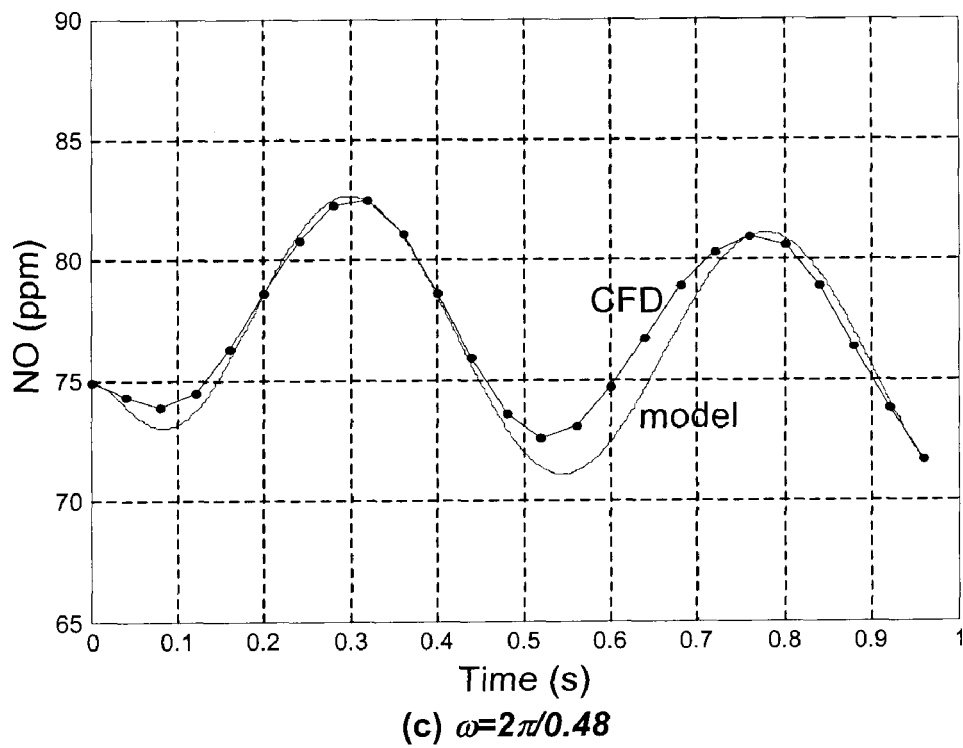
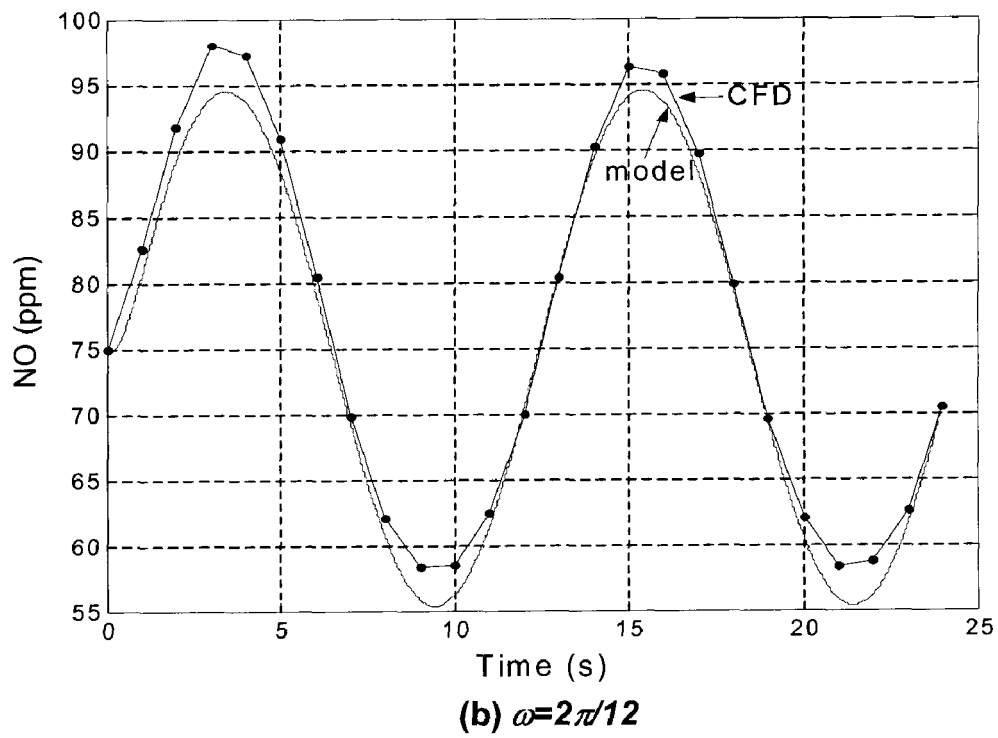
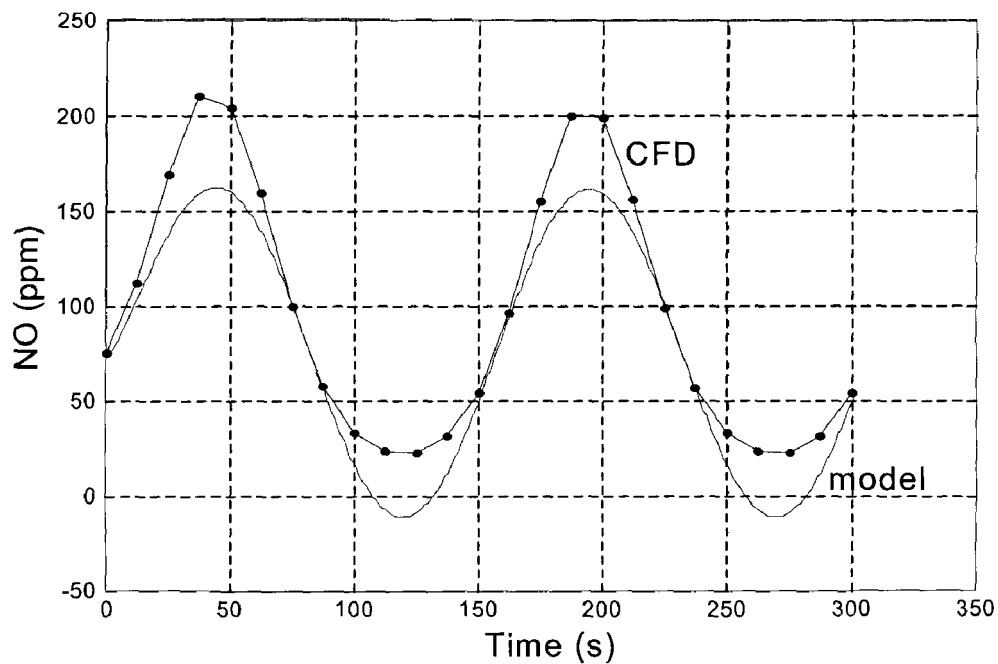
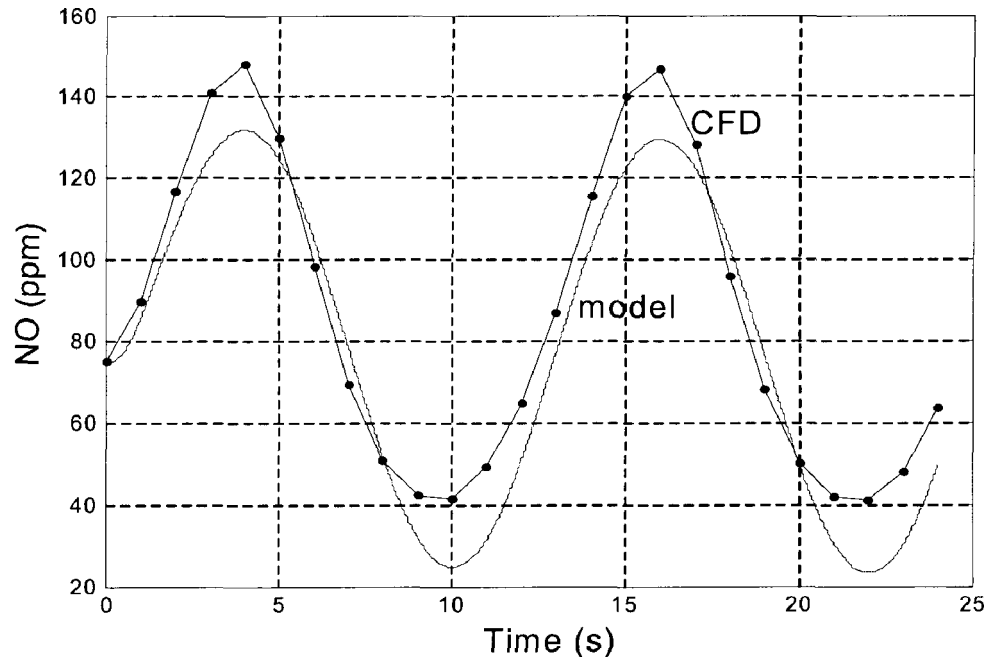


Figure 3.4 Variation of NO at the furnace outlet relative to combustion air temperature

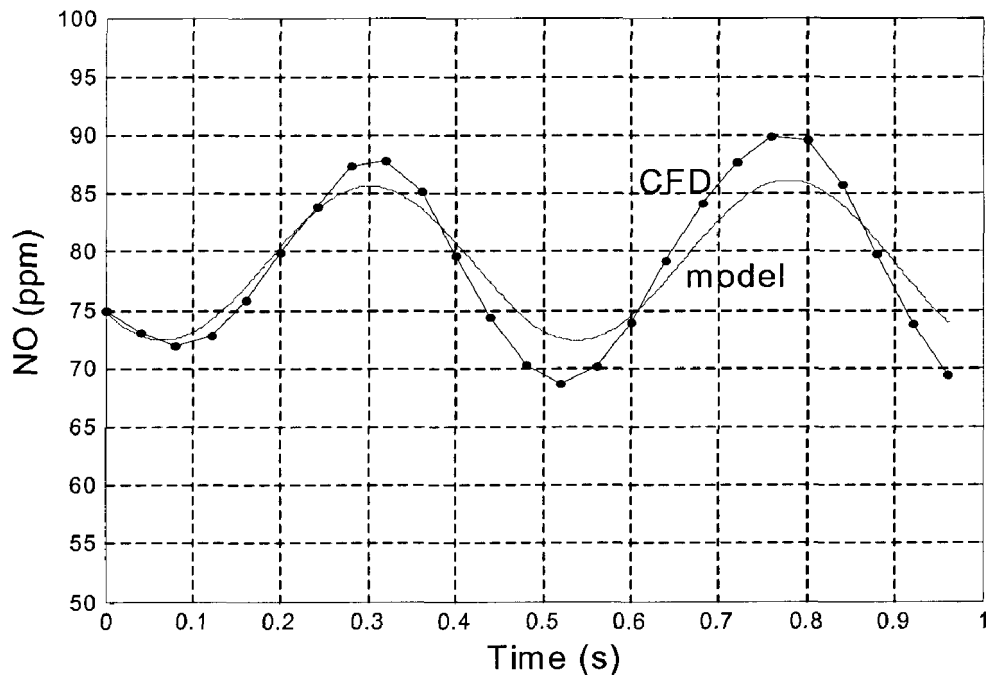
Figure 3.4 shows the comparison of the NO emission predicted by the dynamic models and that obtained from the CFD simulations when the combustion air temperature at the furnace inlet fluctuates. The phase shift is very small and the maximum error in the amplitude is less than 4 ppm for all the frequencies considered. The predicted results from the dynamic model match almost perfectly with the results from the CFD simulations. Clearly, the constructed dynamic model is very accurate in this case.



(a) $\omega=2\pi/150$



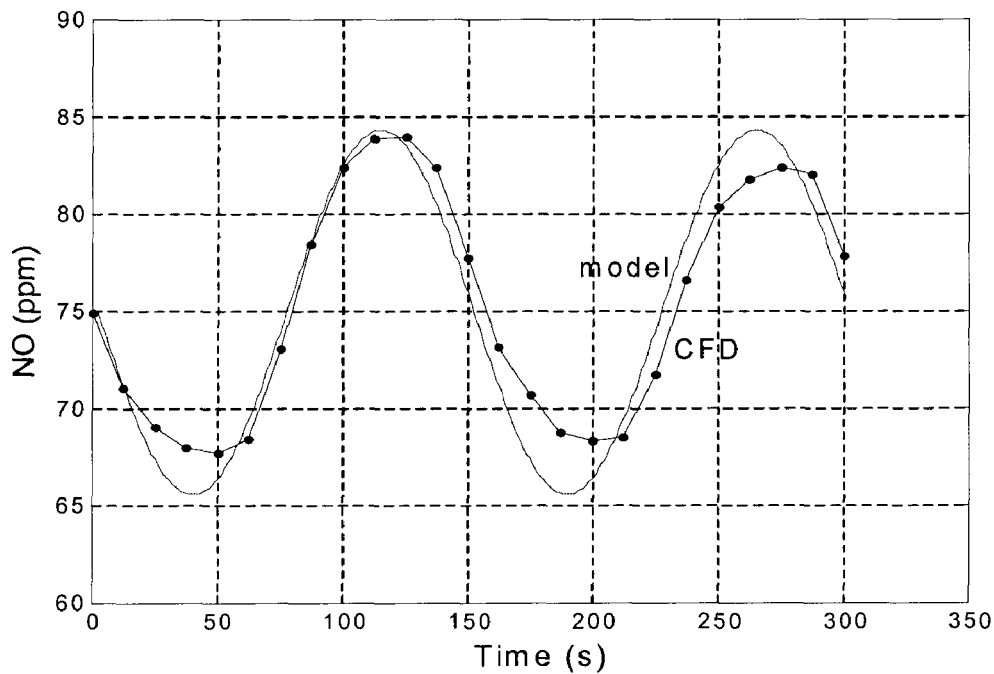
(b) $\omega = 2\pi/12$



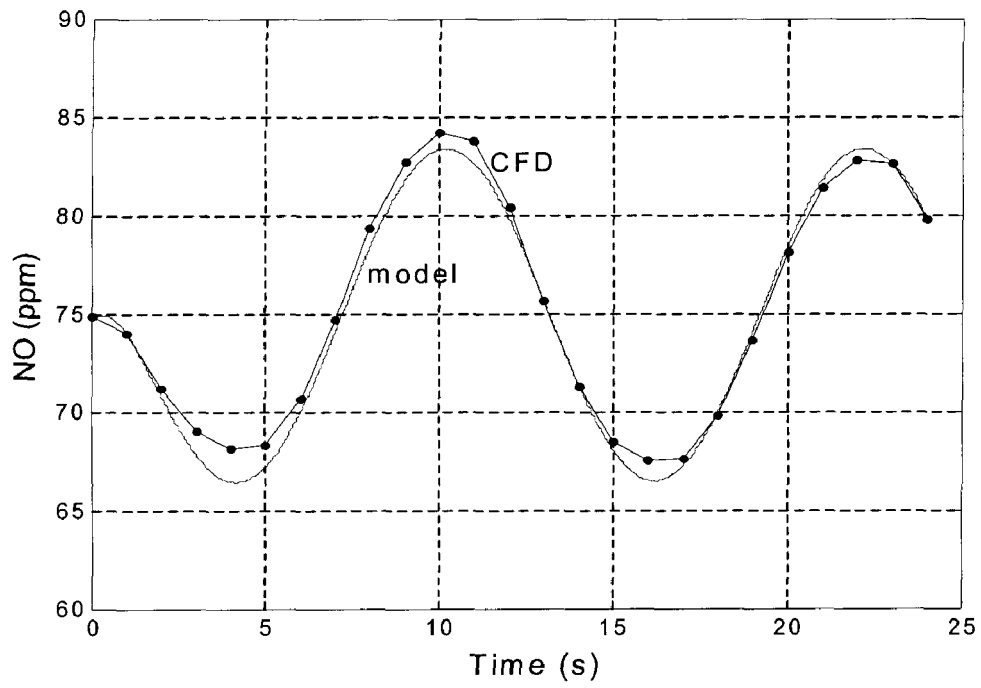
(c) $\omega = 2\pi/0.48$

Figure 3.5 Variation of NO at the furnace outlet relative to the combustion air mass flux

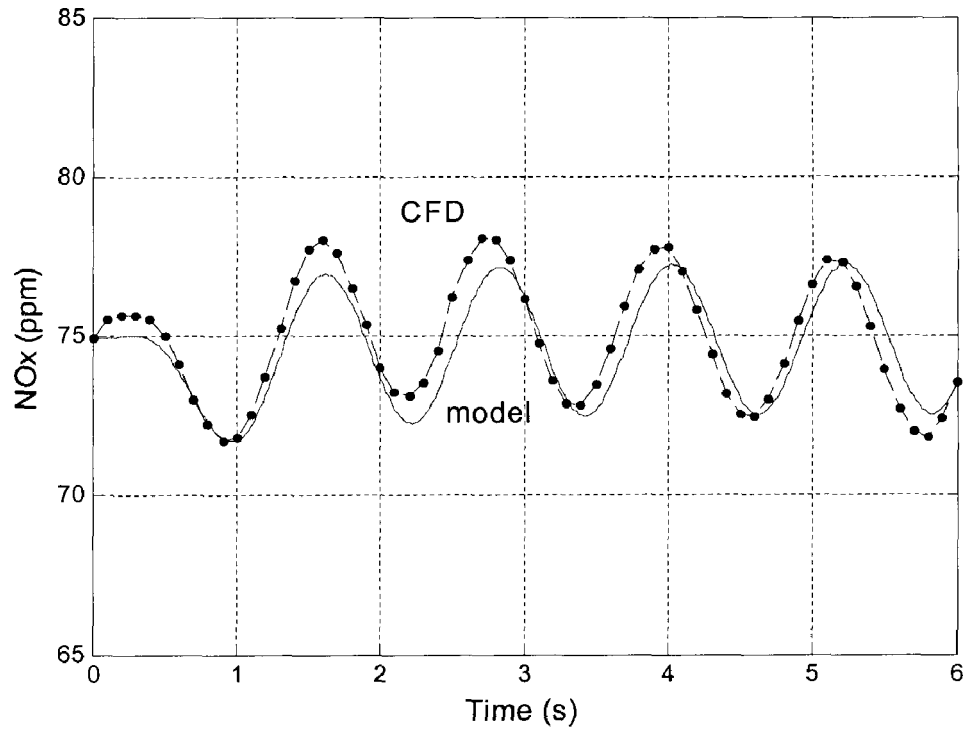
When analyzing the dynamic relationships between the NO formation and changes in the combustion air mass flux, some differences are observed between the CFD results and those generated from the dynamic model, as shown in Fig. 3.5. The error in the NO amplitude is more noticeable at low and middle frequency ranges. This may be due to the nonlinear characteristics between the NO formation and the combustion air mass flux. If, however, the level of NO control is limited to the range of 74.9 ± 10 ppm, this model can still provide satisfactory results. It is seen from Fig. 3.5 that the transfer function model can indeed capture the dynamics of the furnace for NO ranging between 60 and 100 ppm. Figure 3.5 shows that the fluctuation in the furnace input combustion air mass flux has a great effect on the NO formation. Figure 3.5 also shows that NO changes drastically when the input combustion air mass flux fluctuates at a low frequency.



(a) $\omega=2\pi/150$



(b) $\omega = 2\pi/12$



(c) $\omega = 2\pi/1.2$

Figure 3.6 Variation of NO at the furnace outlet relative to the pressure head of the FGR fan

Figure 3.6 shows the comparison of the NO emission predicted by the dynamic models and that obtained from the CFD simulations when the pressure head of the FGR fan fluctuates. The error in the NO amplitude is less than 2.5 ppm and a slight phase shift exists at low frequencies. When the frequency of the signal increases from $2\pi/150$ to $2\pi/12$ rad/sec, the error in the amplitude reduces and the phase difference disappears. When the frequency is increased beyond $2\pi/1.2$ rad/sec, the NO amplitude itself is only about 4 ppm. Figure 3.6(c) shows that there is a response delay due to the inertia of the furnace at high frequency. This transfer function is also an excellent representation between the pressure head of the FGR fan and the NO emission. It is observed from Fig. 3.6 that the change in the pressure head of the FGR fan has the least effect on the NO formation.

Based on the results obtained, it becomes clear that the combustion air mass flux is one of the most effective control inputs as far as the NO emission from the furnace is concerned. As discussed earlier, the combustion air mass flux not only has a strong influence on the NO emission but it also affects the O₂ concentration at the furnace outlet. With currently available oxygen sensors, it is worthwhile to investigate how to minimize NO emission by controlling the mass flux of the combustion air at the furnace inlet. If the mass fraction of excess air can be controlled in the range of 2.5% to 2.8%, the change of the NO emission caused by the change of the combustion air mass flux will be limited to the range from 60 to 100 ppm.

3.8 Conclusions

To optimize the operational aspects of industrial furnaces and to minimize NO emission through active combustion control, it is important to have some knowledge of the dynamic relationships between the furnace inputs and outputs. A set of dynamic models in terms of transfer functions has been constructed in this study for an industrial reheating furnace with flue gas recirculation. The inputs to these models are the mass flux of combustion air and the temperature of the combustion air at the furnace inlet, and the pressure head of the flue gas recirculation fan. The outputs are the NO concentration and the O₂ concentration at the furnace outlet. The study concludes that the NO emission is very sensitive to the change in the combustion air mass flux at the furnace inlet, and is relatively less sensitive to the variations in the other input variables.

To obtain the dynamic model for this multi-input and multi-output system, a CFD simulation is conducted to study the combustion process in the furnace based on the conservation equations of mass, momentum, and energy. Low amplitude sinusoidal signals at different frequencies have been superimposed to the nominal furnace operating input signals in the CFD simulation. The dynamic relationships between these inputs and outputs at each frequency are obtained in terms of the frequency responses. The frequency domain information is further converted to transfer function representations by means of a least squares based system identification technique. The order of the transfer functions ranges from third order to sixth order. These dynamic models are validated by comparing the full-scale CFD simulation results with those generated based on the constructed dynamic models and satisfactory results have been obtained. These models provide a good starting point for the design of real-time active combustion control

systems to minimize NO_x emissions. The control system design aspect of the work will be reported separately.

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CHAPTER FOUR¹

The Design and Validation of the Controllers for the FGR Furnace to Reduce NO_x Emission

4.1 Introduction

NO and NO₂, collectively called NO_x, are the key precursors to the formation of ground-level ozone, which is known to contribute to health and environmental problems. It is estimated that over 95 percent of all man-made NO_x is produced by burning various fuels [1]. To protect the health of humans and the environment, many countries have enacted strict laws to limit the amount of penalty-free NO_x emission. In Canada, according to the Canadian Environment Quality Guidelines [2], the release of NO_x from an industrial furnace must be within the following limits:

1 hour: 400-1000 $\mu\text{g}/\text{m}^3$ (NO_x/Flue gas)

24 hours: 200-300 $\mu\text{g}/\text{m}^3$ (NO_x/Flue gas)

1 year: 60-100 $\mu\text{g}/\text{m}^3$ (NO_x/Flue gas)

To reduce NO_x emission, many different techniques have been investigated, including changing the fuels used or adding additives [3], modification to the combustion chambers and fuel injectors, [4], as well as through feedback controls. A comprehensive review of existing techniques for NO_x control can be found in two recent survey papers [5, 6].

Generally speaking, the NO_x formed from industrial furnaces can be attributed to three distinct chemical kinetic processes: thermal NO_x, fuel NO_x, and prompt NO_x.

¹ The work contained in this chapter was submitted to J. of Combustion Science and Technology in January 2004

However, the prompt NO and fuel NO are usually in very small quantities and only thermal NO_x is considered in this work. In gas- or oil-fired industrial furnaces, the majority of NO_x is NO, and the concentration of NO₂ is negligible in comparison to that of NO.

It is well understood that the thermal NO_x relate closely to the hottest zones inside the furnace [7]. A desirable combustion environment must be maintained to reduce the formation of thermal NO_x in the furnace and to steer away from favorable conditions for NO_x formation. A significant amount of research has been done to design low NO_x burners by optimizing the detail design of the furnace, such as dimensions, locations of fuel/air injection, and the operating condition, e.g. temperature, pressure etc. For example, it has been shown that the flue gas recirculation (FGR) is an effective way to reduce NO_x emissions in industrial furnaces [8]. However, this scheme works well only at a low excess oxygen concentration. A slight deviation from this condition could result in a significant increase in the amount of NO_x generated. Therefore, the optimal operation is as important, if not more, as the optimal design of a furnace.

It is easy to understand that the design parameters will be fixed once the furnace is constructed. However, the operating conditions may be subject to many operational uncertainties. To ensure that the furnace operate at the desired condition, users must rely on active combustion control systems.

A combustion control system maintains the furnace operation at the desired conditions by manipulating the external control variables based on the operational information of the furnace in real-time. The main objective is to minimize any excursion of the furnace operating variables from their desired values when subjected to

disturbances and hence to reduce the potential hottest zones to reduce the NO_x formation. Clearly, this is a regulation problem from a control system point of view. The solution to this problem can be achieved through some feedback control strategies.

In the current research, the furnace input variables that can be manipulated are: (a) the mass flow rate of the combustion air; (b) the temperature of the combustion air; and (c) the pressure head of the flue gas recirculation fan. The control system relies on the real-time measurements of two furnace outputs: oxygen (O₂) and the NO concentrations at the furnace outlet.

Other potentially undesirable substances in addition to NO_x have to be considered. The most notable ones are CO and CO₂. Care must be taken so as not to get into a situation where NO_x is minimized at the expense of the other undesirable emissions. These issues have to be carefully considered at the furnace design stage, which is beyond the scope of the present research. Assuming that the desired operating condition is determined through appropriate furnace design and analysis, the objective of the current research is to show how to maintain furnace operation at the design conditions through feedback controls.

It is imperative to have sufficient knowledge about the relationships between the manipulated furnace inputs and the measured furnace outputs in order to design an effective feedback control system. Unfortunately, a furnace is a highly nonlinear system and the fluid flow, heat transfer and combustion processes are also very complex. Even though full-scale Computational Fluid Dynamic (CFD) models have been constructed based on principles of fluid flow, heat transfer and combustion processes for open-loop

studies, such models cannot be used directly for the design of closed-loop feedback controllers.

A novel approach is developed in chapter to circumvent such a difficult situation. Since the main issue dealt with in this study is to maintain the desired operating condition for the furnace, it is possible to represent the nonlinear furnace by linear dynamic models around the desired operating condition. These linear models are then be used in the feedback control system design. To construct accurate linear dynamic system models, detailed CFD solutions must be found and dynamic system identification techniques have to be employed.

In fact, CFD modeling is not new to furnace design and evaluation and is used in combustion optimization and NO_x reduction technologies [9, 10, 11, 12, 13]. CFD plays two major roles in the current investigation: (1) linear dynamic model construction; and (2) full-scope performance evaluation of the designed feedback control systems in a nonlinear furnace environment.

A considerable amount of research has been carried out on the use of feedback control systems to reduce NO_x emission. Interested readers can refer to [5, 6, 14, 15] and reference thereafter for details on this subject. The main contribution of this paper is to show how CFD can be used effectively to design and evaluate optimal feedback controllers to maintain the desired furnace operating conditions and hence to achieve NO_x reduction.

Since the controller relies on the real-time information of the furnace, the availability of sensors to provide on-line measurements for the concept to be viable must be considered. So far as the current research is concerned, sensors and transducers for O₂

are readily available. As for on-line NO_x measurement, significant progress has been made recently [16]. Several manufacturers have announced the availability of sensitive NO_x analyzers using the chemiluminescent method. The measurement delay can be reduced to no more than one second and the minimum detectable concentration is as low as 0.02 ppm. The availability of such sensors will further enhance the practice value of the current investigation.

The paper is organized as follows: In Section 4.2, the configuration, the operating conditions of the FGR furnace used in this study are described with the problem statement. The construction of a linear dynamic model for the furnace that incorporates the operating conditions is covered in Section 4.3. The optimal control strategy is analyzed and the design is carried out in Section 4.4. The performance of the designed control systems is evaluated in Section 4.5 using both the linear dynamic models and the full-scope nonlinear CFD models. Finally, conclusions are discussed in Section 4.6.

4.2 The Furnace Configuration, Operating Condition and the Problem Statement

4.2.1 The furnace configuration

The furnace used in the current study is a reheating furnace with FGR as shown in Fig. 4.1. The dimensions of the furnace are $3.75 \times 1.4 \times 1.4 \text{ m}^3$. The burner is located at the center of the left-side wall and the exhaust outlet is located at the center of the right-side wall as illustrated. A flue gas recirculation pipe 0.15 m in diameter is installed to circulate the flue gases from the rear top of the furnace back to the inlet. It re-enters the furnace from the center of the top-right side of the furnace as shown.

The dimensions of the mixing box at the inlet of the furnace are $0.3 \times 0.3 \times 0.8 \text{ m}^3$. The combustion air and the recirculation flue gases enter the mixing box in the same direction so that they can be mixed symmetrically before entering the furnace to avoid any potential deviation of the flame in a particular direction inside the furnace. The stabilizer at the center of the right-side wall of the mixing box is simplified as a round plate of 0.07 m in diameter. A diffuser with an inlet diameter 0.2 m and an exit diameter 0.35 m is used between the mixing box and the furnace is shown in Fig. 4.1. The fuel and gases are injected into the diffuser through a concentric pipe with the inner diameter of 0.07 m and the outer diameter 0.2 m. The fuel is injected through the center pipe. The combustion air and flue gases are injected through the annular area between the two pipes.

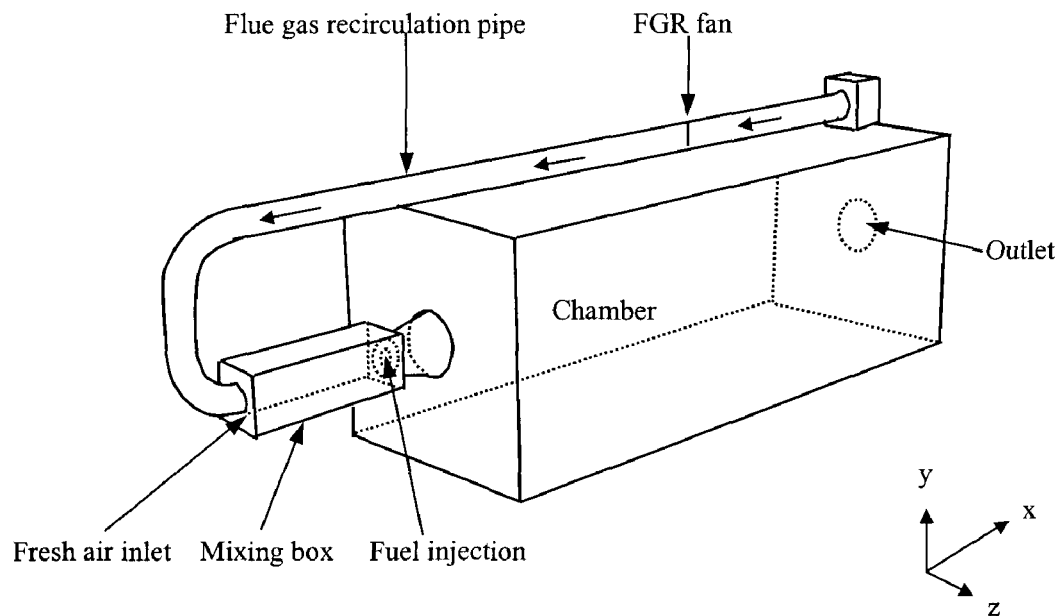


Figure 4.1 Configuration of the FGR furnace

The controllable furnace inputs are the flow rate, the temperature of the combustion air and the pressure head of the FGR fan. The actuators for these three variables are: air flow fan, pre-heater, and damper in the flue gas recirculation path. It is also assumed that the oxygen and NO_x sensors are located at the immediate exhaust outlet.

4.2.2 A general strategy for determining desired operating conditions for NO_x reduction

As in any dynamic system, different system inputs affect the system behaviors in different ways. Industrial furnaces are no exception. Based on an earlier study [17], it is concluded that the combustion air mass flux, which is mass flow rate per unit flow area, not only has a significant affect on the NO emission but also on the oxygen concentration at the furnace outlet. A simple strategy to determine the desired operating conditions for the furnace is to use the information from the oxygen concentration at the furnace outlet to determine the amount of mass flux of the combustion air at the furnace inlet for minimum NO emission. In fact, if the mass fraction of excessive air can be kept in the range of 2.5% to 2.8%, the corresponding NO emission due to the fluctuation of the combustion air mass flux can be limited to the range of 60 to 100 ppm [17]. After the combustion air mass flux is determined, the NO_x emission can be further reduced through proper adjustments to the combustion air temperature and the pressure head of the FGR fan. The characteristics of the furnace are such that this kind of decoupled design is possible. Such a decoupled design also allows one to easily consider CO emission levels while minimizing NO because only the combustion air mass flow rate has a dominant effect on the CO emission in this furnace configuration. Through proper

analysis and CFD simulations, the desired operating conditions of the furnace can be established.

The main objective of this paper is to design a real-time control system to maintain the furnace at the desired operating condition. Any further elaboration on the determination of such conditions here are beyond the scope of the current research.

4.2.3 The furnace operating condition

Based on the furnace control strategy outlined previously, the desired operating condition is determined and the corresponding parameters are summarized in Table 4.1. Since the furnace considered is a reheating furnace, the temperature at the furnace bottom wall is set at a constant value of 1100 K. It is assumed that the rest of the walls are insulated. The parameters of the fuel channel remain unchanged during normal operation. The furnace can be controlled through the flow rate and the temperature of the combustion air. As shown, their nominal values are 0.135 kg/s and 700K, respectively. The pressure head of the FGR fan, which is nominally set at 33.8 Pa, can also be adjustable.

Table 4.1 The normal furnace operating conditions

Fuel (propane, C ₃ H ₈)	Flow rate	0.0075 kg/s
	Temperature	300 K
	Heating value	345 kW
Input combustion air	Flow rate	0.135 kg/s (or 1.849 kg/m ² ·s)
	Temperature	700 K (or 426.85°C)
Heat output	190 kW from the bottom of the furnace	
Pressure head of the FGR fan	33.8 Pa	
Flue gas recirculation rate	0.012 kg/s	
Temperature at the bottom wall	1100 K	
Temperature at the FGR pipe	700K	

4.3 Construction of Linear Dynamic Model

To design an appropriate feedback controller for the furnace that maintains the desired operating condition, it is important to have causal relationships between the furnace inputs and the corresponding outputs. The full-scale mathematical model that describes the fluid flow, heat transfer and combustion process in the furnace can be derived by applying the mass, momentum and energy conservation laws. The resulting equations are nonlinear partial differential equations. These equations not only describe the input and output relations of the furnace, but also the fluid flow, heat transfer, and combustion variables internal to the furnace. These equations are very useful in the performance of the analysis and evaluation of the furnace characteristics and design parameters. Unfortunately, they are not suitable for feedback control system synthesis. Even though fluid flow, heat transfer and combustion process are highly nonlinear and the internal variables depend on the space, the furnace input and output characteristics around an operating point can still be approximated using a space-independent linear dynamic process, for which linear dynamic equations can be obtained. Based on these equations, the design process for the feedback controller can be simplified considerably.

4.3.1 Full-scale mathematical model for the furnace

Based on the fluid flow, heat transfer, and combustion process in the furnace, the following mathematical model is obtained. It consists of Favre-averaged conservation equations and a series of secondary models. The Favre-averaged conservation equations of mass, momentum and energy are given as [18, 19]:

$$\frac{\partial \rho}{\partial t} + \frac{\partial}{\partial x_i} (\tilde{\rho} \bar{u}_i) = 0 \quad (4.1)$$

$$\frac{\partial}{\partial t} (\tilde{\rho} \bar{u}_i) + \frac{\partial}{\partial x_j} (\tilde{\rho} \bar{u}_i \bar{u}_j) = \frac{\partial}{\partial x_j} \left[\mu \left(\frac{\partial \bar{u}_i}{\partial x_j} + \frac{\partial \bar{u}_j}{\partial x_i} \right) - \left(\frac{2}{3} \delta_{ij} \mu \frac{\partial \bar{u}_l}{\partial x_l} \right) - \frac{\partial \tilde{P}}{\partial x_i} + \frac{\partial}{\partial x_j} (-\tilde{\rho} \overline{u'_i u'_j}) \right] \quad (4.2)$$

$$\frac{\partial}{\partial t} (\tilde{\rho} \bar{h}) + \frac{\partial}{\partial x_i} (\tilde{\rho} \bar{u}_i \bar{h}) = \frac{\partial}{\partial x_i} \left(\frac{\mu_t}{\sigma_h} \frac{\partial \bar{h}}{\partial x_i} \right) + \bar{S}_h \quad (4.3)$$

where x_i is the position vector, u_i is velocity vector, ρ is density, P is pressure, μ is molecular viscosity, μ_t is turbulent viscosity, h is static enthalpy, and σ_h is the turbulent Prandtl number. The source term, S_h , in Eq. (4.3) consists of sources of enthalpy due to chemical reaction and radiation. The quantities with an overbar are the Favre-averaged values. The quantity with a tilde represents the Reynolds-averaged value. The prime denotes the fluctuation about the Favre average. The Reynolds stresses, $-\tilde{\rho} \overline{u'_i u'_j}$, in Eq. (4.2) must be modeled in order to solve it. The Bousinesq hypothesis is used to relate the Reynolds stresses to the mean velocity gradients as follows:

$$-\tilde{\rho} \overline{u'_i u'_j} = \mu_t \left(\frac{\partial \bar{u}_i}{\partial x_j} + \frac{\partial \bar{u}_j}{\partial x_i} \right) - \frac{2}{3} (\tilde{\rho} k + \mu_t \frac{\partial \bar{u}_l}{\partial x_l}) \delta_{ij} \quad (4.4)$$

$$\mu_t = \tilde{\rho} C_\mu \frac{k^2}{\varepsilon} \quad (4.5)$$

where k and ε are the turbulent kinetic energy and its dissipation rate, respectively. The values of k and ε are obtained from the solution of their transport equations. For the standard k- ε model [20], k and ε transport equations are expressed as,

$$\frac{\partial}{\partial t}(\tilde{\rho}k) + \frac{\partial}{\partial x_i}(\tilde{\rho}\overline{u_i k}) = \frac{\partial}{\partial x_i}\left(\frac{\mu_t}{\sigma_k} \frac{\partial k}{\partial x_i}\right) + G_k - \tilde{\rho}\varepsilon \quad (4.6)$$

$$\frac{\partial}{\partial t}(\tilde{\rho}\varepsilon) + \frac{\partial}{\partial x_i}(\tilde{\rho}\overline{u_i \varepsilon}) = \frac{\partial}{\partial x_i}\left(\frac{\mu_t}{\sigma_\varepsilon} \frac{\partial \varepsilon}{\partial x_i}\right) + C_1 \frac{\varepsilon}{k} G_k - C_2 \tilde{\rho} \frac{\varepsilon^2}{k} \quad (4.7)$$

where $G_k = \mu_t \left(\frac{\partial \overline{u_j}}{\partial x_i} + \frac{\partial \overline{u_i}}{\partial x_j} \right) \frac{\partial \overline{u_i}}{\partial x_i}$, $C_1 = 1.44$, $C_2 = 1.92$, $C_\mu = 0.09$, $\sigma_k = 1.0$ and $\sigma_\varepsilon = 1.3$.

As near wall boundary conditions, values of k and ε at the first grid node are obtained using semi-empirical formulae known as standard wall functions [21]. Wall functions are used to bridge the viscosity-affected region between the wall and the fully turbulent region.

The effect of turbulent fluctuations on the combustion is accounted for with an assumed-shape probability density function (PDF), the β -PDF [22, 23]. The discrete transfer radiation model (DTRM) [24, 25] is employed for the calculation of the radiation heat transfer. The assumption of gray radiation is acceptable for all inner surfaces of the furnace. The weighted-sum-of-gray-gases model [26, 27] is used to calculate the absorption coefficient. The chemistry model is based on the chemical equilibrium concept which assumes that the chemical reaction is rapid enough for chemical equilibrium to always exist at the molecular level is employed to specify the instantaneous thermo-chemical state of the combustion mixture. The liquid fuel injection is modeled using a discrete phase model. The turbulent dispersion of liquid fuel droplets and other forces on the liquid fuel phase are neglected because the liquid fuel droplets last for a very short period of time and exist only in a very small region near the inlet of the furnace. The mean NO concentration is obtained by solving its transport equation

based on the flow field and combustion solution from the main combustion simulations. The temperature PDF approach [28] is used to account for the effect of turbulence on the NO formation.

4.3.2 Linear dynamic model of the furnace

Although the knowledge of the internal furnace variables are of interest in furnace design and analysis, these variables cannot be incorporated into the control system design process directly. From a control system point of view, it is more important to focus on input and output relations of the furnace. The furnace is modeled in this study using a three-input and two-output system as illustrated in Fig. 4.2. The input variables are the mass flux (mass flow rate per unit flow area) of the combustion air, m_{air} , and the temperature of the combustion air, T_{air} , at the furnace inlet, and the pressure head of the FGR fan, P_{fan} . The measurable output variables are the mole fraction of NO, y_{NO} , and the mass fraction of O₂, f_{O2} , at the furnace outlet.

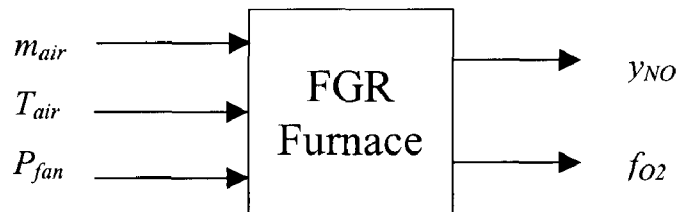


Figure 4.2 The input and output representation of the FGR furnace

It is important to note that the above variables are in the form of deviation from the values at the desired furnace operating condition. The relationships among these variables

can be represented in terms of the transfer functions between appropriate inputs and the corresponding outputs.

The construction of these transfer functions requires the results from CFD simulations of the furnace. To obtain the linearized relationships among those input and output variables, low amplitude sinusoidal signals at different frequencies are added to the corresponding furnace inputs, and the resulting variations of the furnace outputs obtained by CFD simulations are recorded. Through proper analysis of these input and output values, the transfer functions between the furnace inputs and outputs are obtained by using least-squares based system identification techniques. Interested readers are referred to [29] for details. The transfer functions are shown as follows:

$$G(s)_{O_2} = \frac{8.3875s^2 + 36.594s + 46.590}{s^5 + 3.1926s^4 + 27.868s^3 + 37.260s^2 + 78.147s + 10.000} \quad (4.8)$$

$$G(s)_{air\ mass} = \frac{-0.7532s^6 + 5.6356s^5 - 21.589s^4 + 423.76s^3 + 494.10s^2 + 2930.0s + 320.37}{s^6 + 4.3640s^5 + 62.070s^4 + 136.12s^3 + 402.91s^2 + 408.38s + 25.090} \quad (4.9)$$

$$G(s)_{air\ temp} = \frac{-23.6270s^3 - 133.77s^2 + 2398.2s + 20890}{s^4 + 39.556s^3 + 900.74s^2 + 3972.1s + 7478.8} \quad (4.10)$$

$$G(s)_{fan} = \frac{7.1681s - 63.801}{s^3 + 4.6133s^2 + 25.700s + 22.654} \quad (4.11)$$

where $G(s)_{O_2}$ represents the relationship between the mass flux of the combustion air at the furnace inlet and the mass fraction of oxygen at the furnace outlet. $G(s)_{air\ mass}$ is the transfer function from the mass flux of the combustion air at the furnace inlet to the mole

fraction of NO at the furnace outlet. $G(s)_{air\ temp}$ is the transfer function from the temperature of the input combustion air to the mole fraction of NO at the furnace outlet. $G(s)_{fan}$ is the transfer function between the pressure head of the FGR fan and the mole fraction of NO at the furnace outlet.

$$\begin{bmatrix} f_{O_2} \\ y_{NO} \end{bmatrix} = \begin{bmatrix} G(s)_{O_2} & 0 & 0 \\ G(s)_{air\ mass} & G(s)_{air\ temp} & G(s)_{fan} \end{bmatrix} \begin{bmatrix} m_{air} \\ T_{air} \\ P_{fan} \end{bmatrix}$$

It is important to point out that, since the mass fraction of the oxygen at the furnace output does not depend on the temperature of the combustion air or the pressure head of the FGR fan, the transfer functions $G(s)_{12}$ and $G(s)_{13}$ are zero. Therefore, there are four non-zero transfer functions that represent the input and the output variables of the furnace around the operating conditions.

4.4 Design of Feedback Control System

Although the desired operating conditions for the furnace with minimal NOx emission are determined using CFD simulations, a practical furnace is always subject to disturbances during its operation. In order to keep the furnace operating condition close to the designed ones, the furnace inputs have to be regulated continuously to reduce any deviations. The main objective of the controllers is to maintain the mass fraction of oxygen and the mole fraction of NOx at their designed values.

Even though the furnace is a multi-input and multi-output system, the non-dependence of the oxygen output from the combustion air temperature and the pressure

head of the FGR fan has made the decoupled controller design possible. To be more precise, the oxygen feedback loop can be designed independent of that of the NO feedback loops. The measured oxygen level at the furnace outlet can be used to maintain the mass flow of the combustion air at a desired level, while also ensuring that other system variables such as the CO emission level satisfy the desired levels. The remaining two furnace inputs can then be used to further reduce the NO emission.

There are many control schemes that can achieve the intended control functions. One of the simplest and most popular controller structures is the PID type. Thus, the controllers with PID structure have also been selected for use in this work. The transfer function of a PID controller takes the following form:

$$G(s)=K_P+K_I/s+K_Ds \quad (4.12)$$

where K_P , K_I , and K_D are controller parameters. The input to the controller is the derivation between the desired and the measured furnace outputs; in this case, one is the oxygen and the other is NO. The controller generates appropriate signals to regulate the corresponding furnace inputs. Because there are three furnace input variables, the control system consists of three separate controllers. The overall structure of the control system is shown in Fig. 4.3. Due to the dynamic nature of the furnace from combustion air temperature and the pressure head of the FGR fan to NO output, derivative actions are not required. Therefore, the control system consists of one PID and two PI controllers. There are a total of seven parameters that need to be selected to achieve the desired dynamic performance.

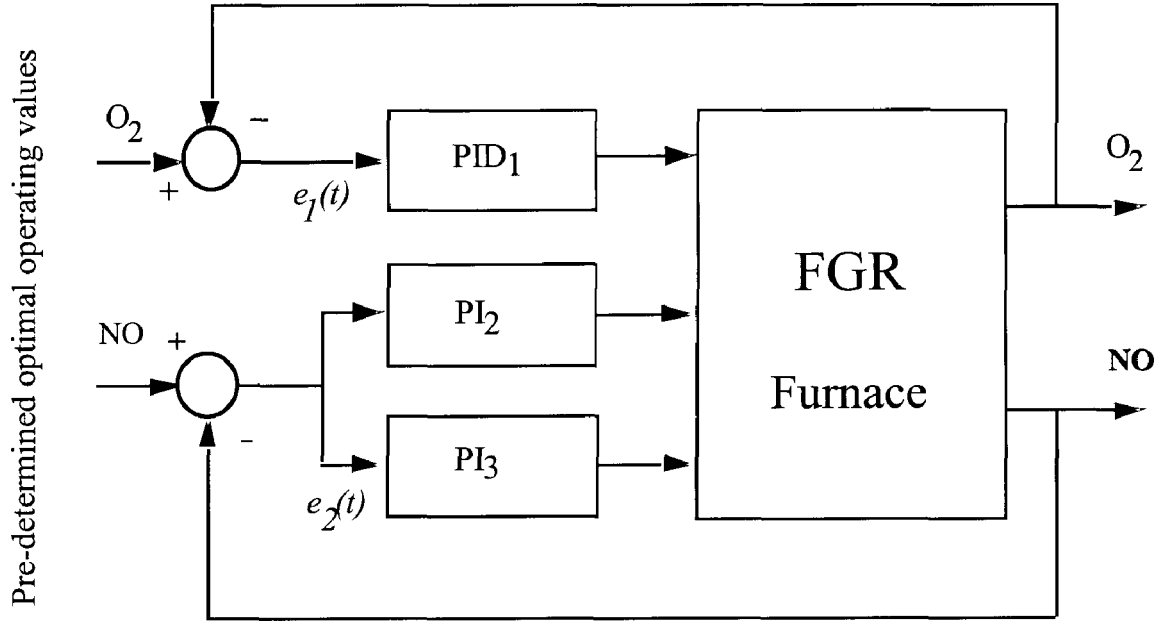


Figure 4.3 Configuration of the control system

These parameters in this study are chosen through an off-line nonlinear optimization technique based on simulated closed-loop system responses. The optimization problem can be formulated as follows:

$$\min(f(K_p, K_I, K_D)) = e_1^2(t_1) + e_1^2(t_2) + \dots + e_1^2(t_m)$$

$$\min(f(K_p, K_I)) = e_2^2(t_1) + e_2^2(t_2) + \dots + e_2^2(t_m) \quad (4.13)$$

where $e_1(t_i)$ and $e_2(t_i)$ represent the deviations of O_2 and NO from their desired value at time step i , respectively. Therefore, this optimization has a clear physical significance.

The resulting controller parameters are shown in Table 4.2. Even though the solution to the optimization process in Eq. (4.13) may not be globally optimal, the simulation results indicate that the designed control system performs satisfactorily. The step responses of the three closed-loop systems, which are generated with Simulink in MATLAB, are illustrated in Figs. 4.4-4.6. The results indicate that the feedback control system has excellent transient and steady state responses (less than 15% overshoot and less than 1 second of 90% settling time). There is a negative response in Figure 4.5 at the rising time, which is mathematically caused by the transfer function and has no physical meaning. The performance of these controllers is evaluated again in the next section using results of full-scale CFD simulations of the furnace in next section.

Table 4.2 Parameters for the designed controllers

Transfer function	PID controller	K_P	K_I	K_D
$G(s)_{O_2}$	PID ₁	1.6143	0.2693	0.0795
$G(s)_{air\ temp}$	PI ₂	0.4630	1.2894	0
$G(s)_{fan}$	PI ₃	0.4784	0.5836	0

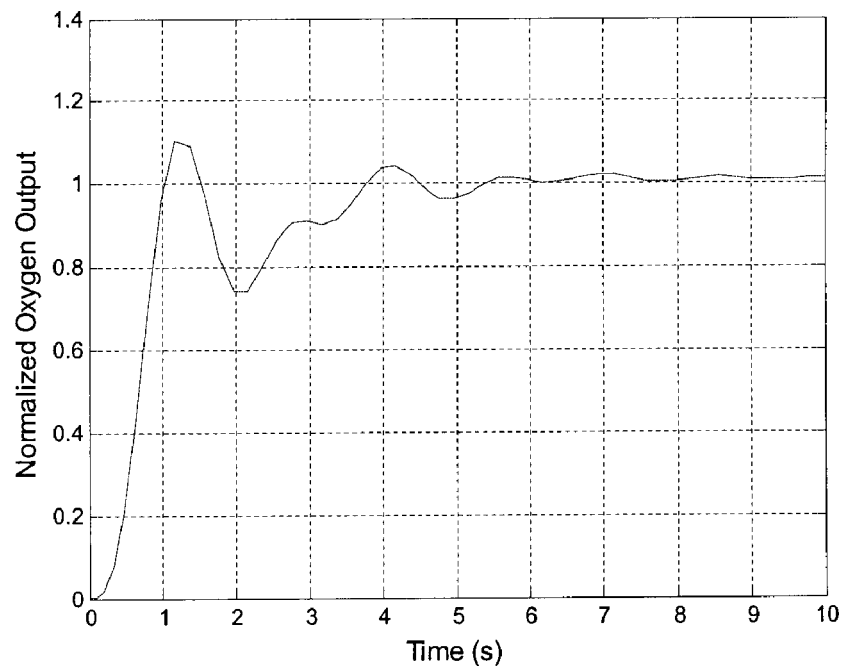


Figure 4.4 The step response of the O_2 output controlled by the controller PID_1

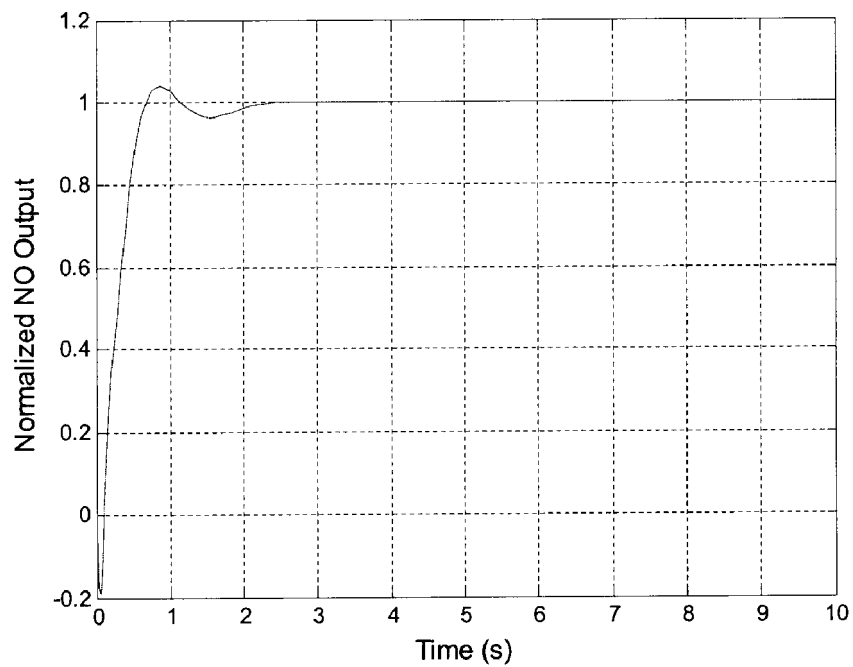


Figure 4.5 The step response of the NO output controlled by the controller PI_2

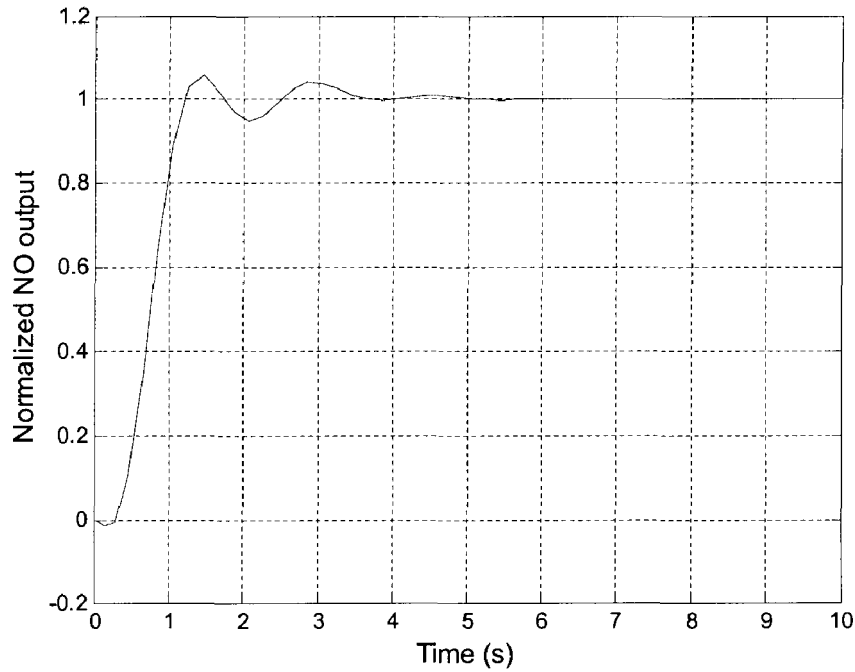


Figure 4.6 The step response of the NO output controlled by the controller PI_3

4.5 Validation of the Designed Control System by Nonlinear CFD Simulations

Difficulties in design of the controllers directly based on the nonlinear partial differential governing equations for the fluid flow, heat transfer and combustion process in the furnace necessitate that the design is carried out based on the linearized dynamic model for the furnace representations. Even though the simulations in the linear domain confirm the effectiveness of the designed controllers, it is still crucial to validate their performance in a full-scale nonlinear environment. This can be carried out by invoking the PID control algorithms within the CFD simulation process in a step-by-step manner. Specifically, the oxygen concentration and NO mole fraction at the furnace outlet are calculated at every time step. These output variables are then used to adjust the furnace

input variables, i.e. the mass flow rate and the temperature of the combustion air, and the pressure head of the FGR fan, for the subsequent time step.

All the signals dealt with in Section 4.4 are deviations of the furnace variables from their desired values in the full-scope simulation. The inputs to the furnace are, therefore, the superposition of the control signals on the values at the desired operating conditions as follows:

$$(m_{air})_{inlet} = 1.849 + m_{air} = 1.849 + 1.849 \times pid_1(t_{K-1}) \quad [Kg/m^2.s] \quad (4.14)$$

$$(T_{air})_{inlet} = 426.85 + T_{air} = 426.85 + 426.85 \times pi_2(t_{K-1}) \quad [^{\circ}C] \quad (4.15)$$

$$(P_{fan})_{inlet} = 33.8 + P_{fan} = 33.8 + 33.8 \times pi_3(t_{K-1}) \quad [Pa] \quad (4.16)$$

In which,

$$pid_1(t_K) = 1.6143e_1(t_K) + 0.2693[E_1(t_{K-1}) + e_1(t_K) \times \Delta t] + 0.0795 \frac{e_1(t_K) - e_1(t_{K-1})}{\Delta t} \quad (4.17)$$

$$pi_2(t_K) = 0.4630e_2(t_K) + 1.2894[E_2(t_{K-1}) + e_2(t_K) \times \Delta t] \quad (4.18)$$

$$pi_3(t_K) = 0.4784e_2(t_K) + 0.5836[E_2(t_{K-1}) + e_2(t_K) \times \Delta t] \quad (4.19)$$

In which, $e_1(t_K) = 0.05 - f_{O_2}(t_{K-1}) / 0.02674$

$$e_2(t_K) = 0.05 - y_{NO_x}(t_{K-1}) / 74.9$$

E_1 , E_2 are accumulated errors. Δt is the sampling interval. It is important to point out that the concept of time steps in CFD is different from that of the sampling interval in control system simulations. The time step in a CFD simulation is the discretizing step for the governing fluid flow and heat transfer equations. These steps must be small enough to obtain accurate numerical solutions for the partial differential equations. On the other hand, the sampling interval in a control system is the discrete time step that the controller

takes to generate the control inputs to the furnace. The CFD time step is much smaller than the control sampling interval in most cases. Normally, there are several discretizing steps within a single sampling interval. However, for the sake of easy plotting, the plotting interval of the CFD simulation results is given as 0.2 seconds.

The results of the full scale CFD simulations are shown in Figs. 4.7 and 4.8 (asterisk lines) when subjected to a 5% change from the desired oxygen and the NO_x levels. For comparison, the corresponding simulation results based on the linear dynamic models are also included (solid lines). It is noted that this 5% change is just a way to perturb the system and to examine the performance of the control systems in regulating the system response. In a practical situation, the perturbations can have many different origins.

It can be seen that the results from the full-scope nonlinear simulation are in good agreement with those obtained based on linear models. It is important to mention that in Figs. 4.7 and 4.8, the relative scale is chosen to zoom in the difference between the two simulation results. In fact, the steady state difference between the linear and nonlinear models is less than 5% for both outputs.

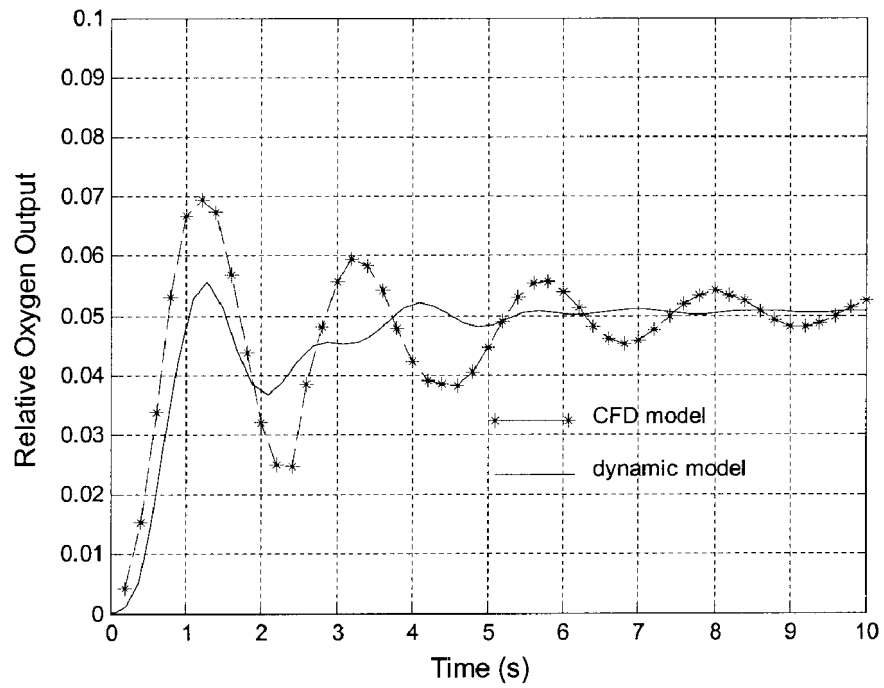


Figure 4.7 The step responses of O₂ based on the linear and the nonlinear CFD models

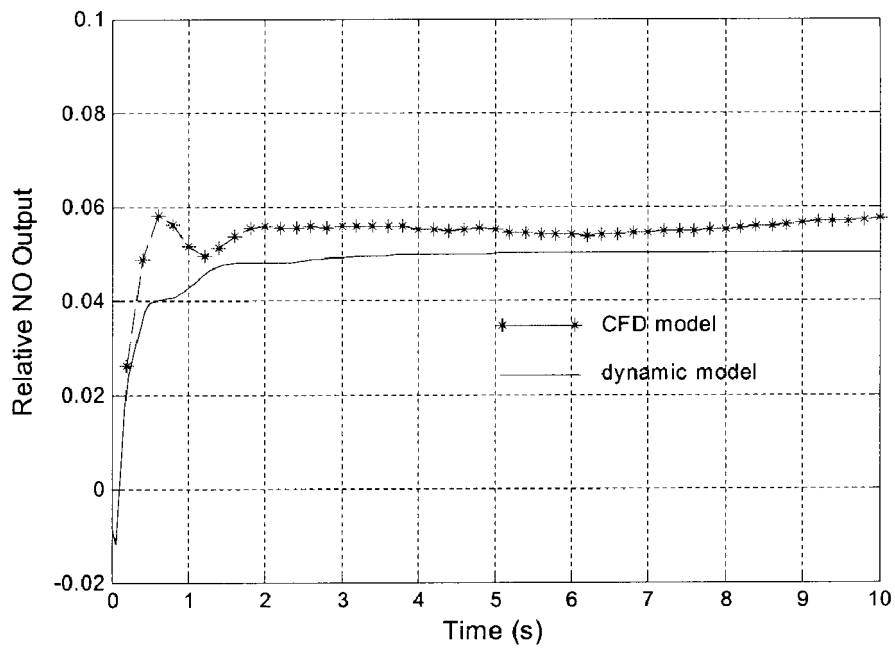


Figure 4.8 The step responses of NO_x based on the linear and the nonlinear CFD models

There are several potential sources of error that contribute to the above discrepancies. The major source of error is in the derivation of the linear models based on the nonlinear CFD equations. Theoretically, the characteristics of a furnace are those of a space-dependent dynamic system. It is often known as “distributed parameter” system. The dimensions of its corresponding linear equation are of an infinite order. However, in the current study, the highest order of the linear system is only six. Hence, some dynamics of the furnace are left out in this modeling process.

The second source of error is due to the time dependent (and iteration dependent) numerical solutions of the CFD equations with PID controllers embedded between the sampling intervals. At the beginning of each iteration, newly generated controller outputs are incorporated as the new inputs to the furnace, which can cause potential numerical inconsistency between subsequent simulation steps.

The third source of error is probably due to the negligence of the influence of the mass flow rate of the combustion air to the NO using the decoupled control design strategy. Even though the design process has been significantly simplified without considering the coupling terms, such simplification does have some negative effects on the overall accuracy of the linear model simulations.

Finally, one has to face the fact that no matter how closely a nonlinear system can be represented by a linear one, it is always an approximation. A general observation from Fig. 4.7 indicates that the controller synthesizes system based on the linear models tends to overestimate the damping of the actual system.

In closing, it is also important to emphasize that the linear models and the corresponding controllers discussed here are for the specific furnace operating conditions. If the operating conditions change for any reason, the controllers will likely need to be modified as well. Fortunately, for industrial reheating furnaces, there are only a finite number of operating conditions that need to be considered. Therefore, it is possible to synthesize a set of feedback controllers that correspond to each operating condition, and to use gain-schedule techniques to switch among them.

4.6 Conclusions

NO_x formation in an industrial FGR furnace has been analyzed in this paper. Recognizing the fact that NO_x is particularly sensitive to the oxygen content of the combustion air input, a control strategy has been chosen to use the measured oxygen content in the exhaust to control the air mass flow of the combustion air at the furnace inlet first. The measured NO_x signal is then used to adjust the temperature of the combustion air and the pressure head of the FGR fan to further reduce the amount of NO_x at the exhaust. However, the design of such feedback controllers cannot be easily carried out in the nonlinear domain. This chapter shows that it is possible to represent the nonlinear characteristics of a FGR furnace by a multi-input and multi-output linear dynamic system around a certain chosen operating point in terms of transfer functions. Based on these transfer functions, a feedback control system can be synthesized to provide continuous regulation to the furnace so that the variation of the furnace never deviates significantly from the desired operating point in the presence of disturbances. A novel method based on off-line nonlinear optimization has been used to select the most

appropriate controller parameters. Finally, the control system designed has been evaluated by embedding it to the CFD based nonlinear furnace simulations. Excellent results have been obtained.

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CHAPTER FIVE

Conclusions

5.1 Summary of the Work

The objectives of this thesis are to construct on-line real-time dynamic feedback controllers to reduce the NO_x emission in an FGR industrial furnace. At the beginning of this research, a simplified FGR furnace is designed whose dimensions, dynamical head of FGR fan, and arrangement of mixing box are optimized by the CFD results using code FLUENT. Based on the results at the steady state, the dynamic relationship between the inputs and outputs is investigated by imposing low amplitude sinusoidal signals of different frequencies at the inputs around the operating point. Then, the dynamic model is constructed by a linear least squares method in the form of a series of transfer functions which are validated by the CFD simulations. Finally, nonlinear optimization is used to obtain optimal PID controllers to minimize any deviations of the furnace from the operating point, and the controllers are validated by the results of CFD simulation.

5.2 Conclusions

The research in this thesis resulted in several conclusions given below:

- It is found that the combustion air and the recirculation flue gases should enter the mixing box in the same direction as the fuel injection. In this way, the flue gases and the combustion air can be mixed symmetrically before entering the furnace thus avoiding potential deviation of the flame in a particular direction inside the FGR furnace.

- FGR is an effective way to reduce NO_x emissions. Compared with standard industrial furnaces emissions can be reduced by 87%.
- The NO_x output is very sensitive to the direction of fuel injection. The simulation results show that direct injection (zero cone angle) is the best way, and most of the NO_x is produced just behind of the far flame front.
- NO_x will change dramatically if the combustion air fluctuates at very low frequency. The NO_x output will triple the value at the operating point if the mass flow of combustion air makes only a 10% positive drift from the operating point. The NO_x output is not as sensitive to the temperature of combustion air as it is to flow rate of the combustion air. A drift of the pressure head of the FGR fan will cause the least effect on the NO_x output. The fluctuations of the flow rate and temperature of combustion air have little effect on the heat output from the furnace. Only the drift of flow rate of the combustion air will cause obvious fluctuations of excess oxygen at the outlet of the furnace.
- The dynamic model can be described as three inputs and two outputs. The inputs to this model consist of the pressure head of the FGR fan, the temperature of the combustion air, and the flow rate of the combustion air. The outputs are NO_x mole fraction and excess oxygen ratio. All relationships between inputs and outputs can be described using the transfer functions except for the relationship between NO_x and combustion air flow rate.
- The CFD simulations have been shown that the optimally designed PID and PI controllers can indeed minimize the deviation of the furnace from its desired operating conditions and hence can prevent any unnecessary NO_x formation.

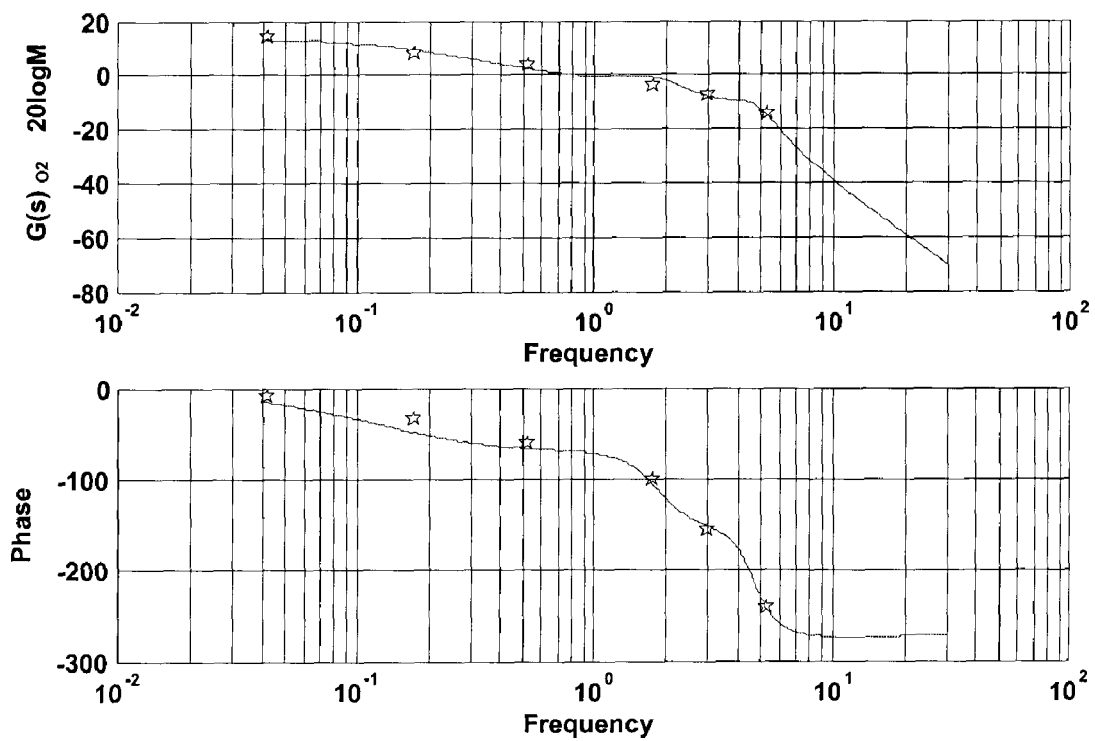
5.3 Future Work

- It is suggested to design and build an experimental FGR furnace with measurement equipments and control devices. More funds are needed to support this significant investigation.
- The control model needs to be validated against the experimental data.
- Fuel nozzles with different cone angles are to be tested for NO_x emission release.
- The flue gases usually contaminate the detectors. It is suggested that a carbon filter be installed in the FGR pipe and the detectors be set just behind of the carbon filter.

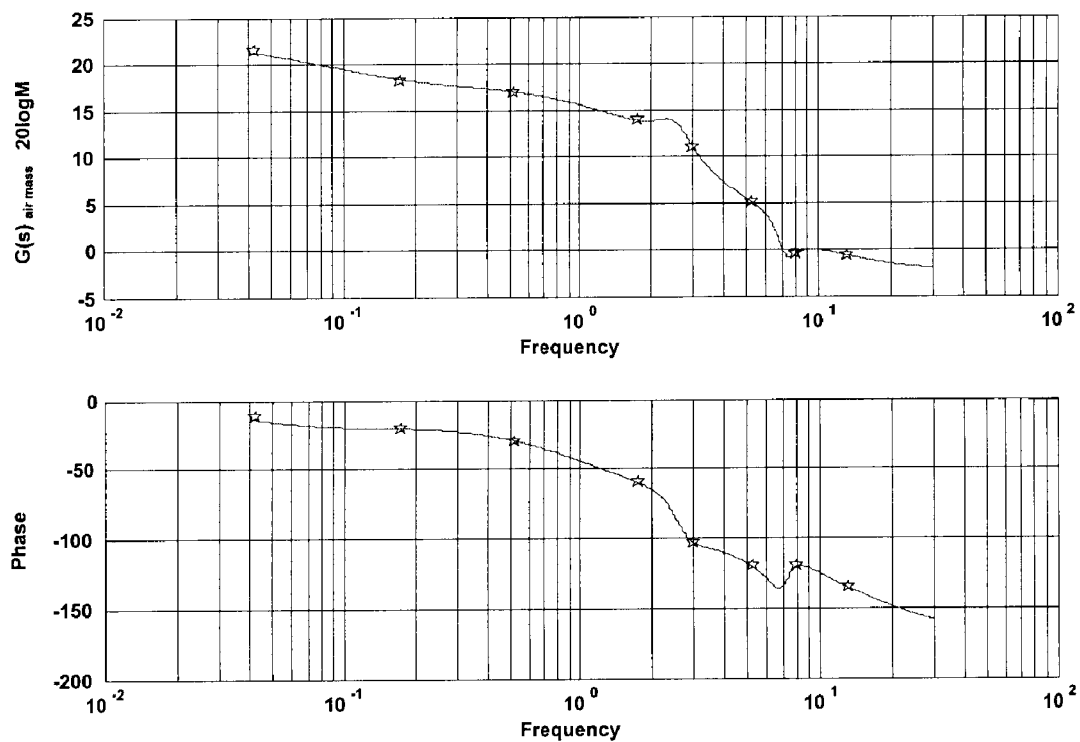
APPENDIX A

Frequency Response Plots for Transfer Functions (3.12) – (3.15)

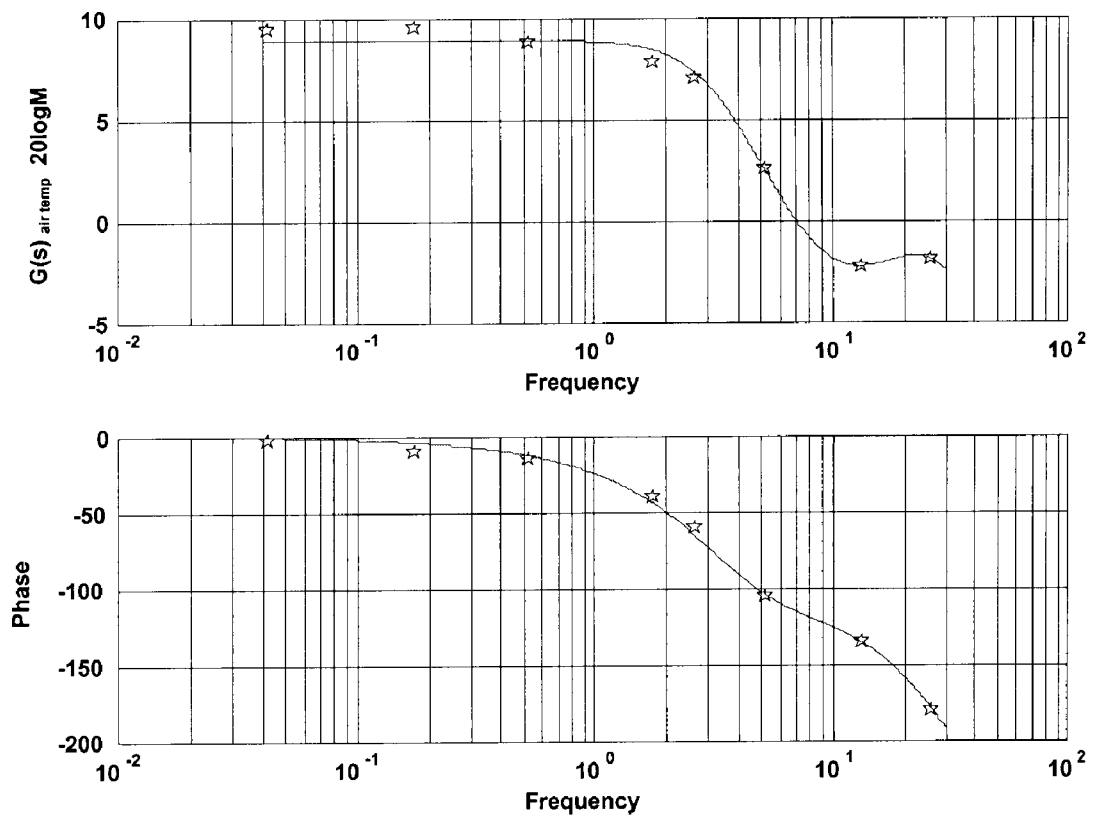
A.1 The Transfer Function $G(s)_{02}$



A.2 The Transfer Function $G(s)_{air\ mass}$



A.3 The Transfer Function $G(s)_{air\ temp}$



A.4 The Transfer Function $G(s)_{fan}$

