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1	Thermal preference and performance in a sub-Antarctic caterpillar: a test of the coadaptation
2	hypothesis and its alternatives
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17 ABSTRACT

Physiological ecologists have long assumed that thermoregulatory behaviour will evolve to 18 optimise physiological performance. The coadaptation hypothesis predicts that an animal's 19 preferred body temperature will correspond to the temperature at which its performance is 20 optimal. Here we use a strong inference approach to examine the relationship between thermal 21 preference and locomotor performance in the caterpillars of a wingless sub-Antarctic moth, 22 Pringleophaga marioni Viette (Tineidae). The coadaptation hypothesis and its alternatives 23 (suboptimal is optimal, thermodynamic effect, trait variation) are tested. Compared to the 24 25 optimal movement temperature (22.5°C for field-fresh caterpillars and 25, 20, 22.5, 25 and 20°C following seven day acclimations to 0, 5, 10, 15 and 5-15°C respectively), caterpillar 26 thermal preference was significantly lower (9.2°C for field-fresh individuals and 9.4, 8.8, 8.1, 27 28 5.2 and 4.6°C following acclimation to 0, 5, 10, 15 and 5-15°C, respectively). Together with the low degree of asymmetry observed in the performance curves, and the finding that 29 acclimation to high temperatures did not result in maximal performance, all, but one of the 30 31 above hypotheses (i.e. 'trait variation') was rejected. The thermal preference of *P. marioni* 32 caterpillars more closely resembles temperatures at which survival is high (5-10°C), or where feeding is optimal (10°C), than where locomotion speed is maximal, suggesting that thermal 33 preference may be optimised for overall fitness rather than for a given trait. 34

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Keywords: Caterpillars, Coadaptation, Fluctuating temperatures, Locomotion, Thermal
 performance curves, Thermal preference

39 **1. Introduction**

Because temperature determines the rate of most biological processes, ectotherms are usually assumed to select body temperatures that optimise performance. If fitness is positively related to performance, organisms that prefer optimum temperatures should have an advantage over those that do not (Huey and Bennett, 1987; Angilletta et al., 2002a; Huey et al., 2003). In consequence, natural selection should result in similarity between the optimum and preferred temperatures because this should maximise Darwinian fitness (Martin and Huey, 2008; Anderson et al., 2011), resulting in thermal coadaptation.

47 Thermal coadaptation has been reported in many ectotherm taxa, including reptiles (Van Berkum, 1986; Huey and Bennett, 1987; Garland et al., 1991; Kubisch et al., 2011), 48 insects (Sanford and Tschinkel, 1993; Forsman, 1999; Calabria et al., 2012), nematodes 49 50 (Anderson et al., 2011), and fish (Khan and Herbert, 2012). Nonetheless, mismatches between 51 thermoregulatory behaviour and thermal physiology are common. For example, in lizards, optimal locomotor performance is achieved at a higher temperature than preferred body 52 53 temperatures (reviewed in Martin and Huey, 2008; Fernandez et al., 2011). Similar findings for population growth have been reported for insects (Smith, 1965; Langer and Young, 1976; 54 Allsopp et al., 1980; Allsopp, 1981; White, 1987; Jian et al., 2002) and other ectotherms 55 (Åkesson, 1976; Zhang and Lefcort, 1991; Prevedelli and Simonini, 2001; Jia et al., 2002; 56 Tepler et al., 2011). 57

58 Several hypotheses have been proposed to explain this departure from coadaptation, 59 particularly when optimum temperatures are higher than preferred temperatures. First, Martin 60 and Huey (2008) suggested that preferred temperatures should be lower than optimum 61 temperatures (hereafter the 'suboptimal is optimal' hypothesis) because asymmetric 62 performance curves mean that performance decreases rapidly above the optimum temperature 63 (Huey and Stevenson, 1979; Huey and Kingsolver, 1989). Thus, preference should be for lower temperatures to minimise the risk of reduced performance (and possibly death) whenthermoregulation is imperfect (Martin and Huey, 2008).

Second, Asbury and Angilletta (2010) hypothesised that the thermodynamic effect (i.e. 66 poorer performance at low temperatures because biochemical reactions proceed more slowly, 67 (Frazier et al., 2006; Angilletta et al., 2010)) means that natural selection should favour a 68 thermal optimum that is higher than body temperature. On the basis of this thermodynamic 69 70 effect, it is argued that adaptation or acclimation to warm environments should therefore confer greater performance compared to colder environments (i.e. "hotter is better") (Angilletta 2009; 71 72 Angilletta et al. 2010). Asbury and Angilletta (2010) argued that selection driven by a thermodynamic effect could explain differences between thermoregulatory behaviour and 73 74 thermal physiology. This is particularly true for the large differences between preferred 75 temperature and the thermal optimum found in some studies (e.g. c. 8°C for geckos (Angilletta et al. 1999) and 17°C for marine invertebrates (Tepler et al. 2011)). We term this the 76 'thermodynamic effect' hypothesis. 77

78 We term a third hypothesis as the 'trait variation' hypothesis. According to this hypothesis, if optimum temperatures vary among physiological processes, then no single 79 thermal preference will be optimal for all systems (Huey and Stevenson, 1979). In 80 consequence, thermal preference may depend on where the major constraints for fitness lie 81 under a given set of conditions. For example, when nutrients are plentiful, preference for high 82 83 temperature in migratory locusts favours maximal growth rather than efficient utilization of nutrients, but when nutrients are limited, the preferred temperature is lowered to maximize 84 efficiency (Miller et al., 2009; Coggan et al., 2011; Clissold et al., 2013). This hypothesis 85 86 reflects the more general one that there may be differential effects of temperature on individual traits and on overall fitness, and that understanding the relationships between the adaptive value 87 of particular traits and overall fitness is important (Kingsolver and Woods, 1997; Woods and 88

Harrison, 2002). Moreover, these effects may take different forms depending on whether
environmental temperatures are relatively constant or variable (Williams et al., 2012; Colinet
et al., 2015; Kingsolver et al., 2015).

92 Although all of these hypotheses enjoy some empirical support, they have rarely been examined simultaneously. The strong inference approach (Platt, 1964) adopts joint exploration 93 of alternative explanations for variations in thermal performance (Huey et al., 1999). Here, we 94 95 apply this approach to caterpillars of the flightless sub-Antarctic moth, Pringleophaga marioni, for which the thermal biology is well-known (Klok and Chown, 1997; Sinclair and Chown, 96 97 2003; Sinclair et al., 2004; Sinclair and Chown, 2005, 2006; Haupt et al., 2014a,b, 2016; Chown et al., 2016). Specifically, we examine the relationship between thermal preference 98 (T_{pref}) and the thermal optimum (T_{opt}) for locomotion. First, we compare T_{opt} and T_{pref} . If these 99 traits are similar, the coadaptation hypothesis cannot be rejected. If they are different, and the 100 101 magnitude of this difference is relatively small and the performance curve asymmetric, the 'suboptimal is optimal' hypothesis cannot be rejected. Alternatively, we determine whether 102 variation in performance curves following exposure to different acclimation regimes accords 103 with the expectations of a thermodynamic effect (i.e. is hotter better?), thus testing the 104 'thermodynamic effect' hypothesis. Finally, we determine whether or not thermal preference 105 aligns with performance measures other than locomotion, and specifically those that may be 106 significant for a relatively long-lived (ca 1 year) detritivorous caterpillar (Haupt et al., 2014a). 107 108 If so, and all other hypotheses are rejected, the 'trait variation' hypothesis cannot be rejected.

109

110 2. Materials and methods

111 *2.1. Study site and species*

Pringleophaga marioni Viette (Tineidae) is a flightless moth, the caterpillars of which occur
in virtually all habitats on the sub-Antarctic Marion and Prince Edward islands (46.9°S, 36.7°E)

114 (Crafford et al., 1986; Haupt et al., 2014a, 2016). The caterpillars are detritivores and take 115 nearly a year to progress through this stage (Haupt et al. 2014a). Field collected caterpillars 116 have a critical thermal minimum (CT_{min}) between -1.6 and 0.1°C, and a critical thermal 117 maximum (CT_{max}) range of 37.7 to 38.7°C (Klok and Chown, 1997).

Marion Island has a low mean annual air temperature of 6.5° C with relatively stable average ambient air temperatures ranging from 2°C in winter to 7°C in summer and a total annual precipitation of 1900 mm (Le Roux and McGeoch, 2008). At low altitudes (4-6 m a.s.l), soil microhabitat temperatures are 6.1 ± 2.7 (°C) (mean \pm s.d.; range: -1 to 22.5°C). At higher altitudes (400 m a.s.l) where *P. marioni* are also found (Crafford et al., 1986), mean soil temperatures are 3.8 ± 3.4 (°C) (mean \pm s.d.; range: -8.0 to 20.0°C; Lee et al., 2009; Haupt et al., 2016).

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126 2.2. Collection and acclimation

This study was undertaken in the laboratory on Marion Island during relief voyages in 2010, 2011, and 2012 (each voyage included 4-6 weeks at the station). Caterpillars were collected from abandoned wandering albatross nests (*Diomedea exulans*), where they occur in high numbers (Haupt et al., 2016), and returned to the laboratory within six hours of collection. Individuals were placed in petri dishes filled with albatross nest material, which served as both refuge and food (Haupt et al., 2014a). Maintaining individuals separately was necessary to avoid cannibalism (French and Smith, 1983).

To determine if exposure to different acclimation regimes results in demonstration of a thermodynamic effect, caterpillars were held for seven days in incubators (MIR 154, Sanyo, Osaka, Japan, accurate to $\pm 0.5^{\circ}$ C) set at 0°C, 5°C, 10°C and 15°C. The timing of acclimation period was based on previous trials showing acclimation responses within a week for this species (Sinclair and Chown, 2003) and for insects generally (Weldon et al., 2011). The effects

of variable temperature regimes were also examined by acclimating caterpillars to a fluctuating 139 temperature of 5-15°C (see also Chown et al., 2016 who found that this treatment results in a 140 lower metabolic rate relative to a constant mean temperature of 10°C). Constant temperatures 141 fall within the soil microhabitat temperature range for this species on Marion Island (Chown 142 and Crafford, 1992; Lee et al., 2009) and the fluctuating temperature simulates conditions 143 within wandering albatross nests where caterpillars are abundant (Haupt et al. 2016). A group 144 of caterpillars were also kept at 5°C for only three days, and these field-fresh individuals served 145 as a control (Deere and Chown, 2006). 146

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148 *2.3. Thermal preference trials*

An important consideration during measures of thermal preference is the likelihood that low 149 thermal preference values may be a result of animals effectively trapped at the lower end of the 150 thermal gradient. Body temperatures and therefore locomotor speed of small ectotherms match 151 temperatures at a given location, thus making it difficult to distinguish between thermal 152 preference (selecting a specific temperature) and thermal dependence of movement (which 153 means the animal cannot move away from low temperatures), thus biasing estimates of thermal 154 preference downward (Dillon et al., 2012). Here we not only considered this possibility a 155 priori, and designed our experiments to avoid it, but we also analysed the data adopting both a 156 more liberal approach to this effect and a more conservative one. Specifically, the low 157 158 temperature end of the preference gradient was set at 0°C, a temperature 0.6°C higher than average critical thermal minimum (CT_{min}) for the species (Klok and Chown 1997). Then, 159 because the maximum recorded value of CT_{min} is 0.1°C, we also undertook analyses excluding 160 all individuals which showed preference temperatures lower than 0.2°C (see below). 161

Thermal preference was first determined along a gradient from *c*. 0-15°C, reflecting the
 microclimate temperatures on Marion Island (Chown and Crafford 1992). Because caterpillars

showed no defined preference on this gradient (Table S1), this experiment was then repeated 164 on a gradient of c. 0-30°C using a different group of individuals. Experiments were conducted 165 on a 75-cm temperature gradient (see Fig. S1) with temperatures controlled at each end using 166 a refrigerated circulator (LTC 12, Grant Instruments Ltd., Cambridge, UK). Temperatures 167 along the gradient were measured and recorded every 5 s using eight evenly-spaced 40-gauge 168 Type T thermocouples connected to an eight channel SQ800 Grant Squirrel data logger (Grant 169 170 Instruments Ltd, Cambridge, U.K.). Dark walk-through "tunnels" constructed from plastic tubing served as refuges along the gradient and were placed at intervals corresponding with the 171 172 thermocouple positions following Marais and Chown (2008) (See "B" in Fig. S1).

At the beginning of each experiment, individuals were weighed (± 0.5 mg; AE163 173 balance, Mettler-Toledo, EngNet, South Africa). An individual was then placed in the centre 174 175 of the gradient and the apparatus was covered with black plastic to allow caterpillars to choose 176 temperatures in the dark. After one hour, the temperature corresponding to the position of the caterpillar was recorded. In another experiment (using a different group of individuals), the 177 temperature of the entire gradient was set to c. 10°C. This constant temperature gradient 178 provided a control to confirm that caterpillars show a thermal preference as opposed to 179 favouring particular ends of the apparatus (Anderson et al., 2007). 180

181

182 *2.4. Locomotor performance trials*

The locomotion speed of individual caterpillars (n = 28 per acclimation temperature) was measured using a temperature-controlled walking stage with a hardboard interior surface (see Fig S2). A refrigerated circulator (LTC 12, Grant Instruments, Cambridge, UK) controlled the temperature of the stage which was measured via a Type-K thermocouple connected to a digital thermometer (CHY 507, Firemate, Taiwan). To avoid heat shock affecting performance at lower temperatures (Lachenicht et al., 2010), individuals were examined first at randomized

189	test temperatures of 0°C, 5°C, 10°C, 15°C and 20°C, and then at high temperatures of 25°C,
190	30°C and 35°C as these temperatures approach the CT_{max} of 38°C for <i>P. marioni</i> .

At the start of each experiment, an individual caterpillar was weighed (as above) and 191 then placed in the centre of the walking stage and held under a plastic container for four minutes 192 to equilibrate to the temperature being tested. The caterpillar was then released and when it 193 moved without faltering, the distance that the head capsule moved over a 20 s period was 194 195 recorded. The trial was repeated three times in succession. The longest distance recorded was used in the analyses, because lower values may reflect an individual's unwillingness to move, 196 197 rather than its inability to move faster (Huey and Bennett, 1987; Angilletta et al., 2002b). Between different temperatures, individual caterpillars were returned to the petri dish they were 198 taken from and held at their acclimation temperature for a minimum of one hour before the 199 next temperature trial. 200

From these measurements, the key performance traits of optimum temperature (T_{opt}), maximum speed at the optimum temperature (U_{max}), and performance breadth (the index of the breadth of the curve, T_{br}) were obtained. The optimum temperature and maximum speed were chosen from the experimental data (i.e. the test temperature with the greatest speed) (Gilchrist, 1996), and these values were used to calculate T_{br} for each individual using Gilchrist's (1996) formula:

$$Tbr = \sqrt{\Sigma[\frac{Ui(Ti - Topt)}{Umax}]}2$$

207

208

where T_{opt} is the temperature at which an individual moved the fastest, U_{max} is the maximum speed at T_{opt} , and U_i is the speed at T_i , i.e. speed at a given test temperature.

211

212 2.5. Data analyses

(Equation 1)

Regression analyses revealed no relationships between body mass and each performance trait 213 or thermal preference (p > 0.05 in all cases, results not shown), indicating that mass was not 214 responsible for any variation observed and it was therefore not included as a covariate in any 215 of the analyses. In consequence, analyses proceeded as follows. First, we determined whether 216 T_{pref} was influenced by experimental design. The median thermal preference for each 217 acclimation temperature on the c. $0-30^{\circ}$ C gradient was calculated using all individuals. To be 218 219 certain that individuals were not trapped at their CT_{min} temperatures, the median thermal preference was also calculated after excluding individuals that preferred temperatures below 220 0.2°C, since the CT_{min} range for P. marioni lies between -1.6°C and 0.1°C (Klok & Chown, 221 1997). For each treatment group (i.e. each acclimation temperature and field fresh individuals), 222 a Wilcoxon rank-sum test (because of non-normal data), as implemented in R.3.0.0 was used 223 to test whether there were any significant differences in thermal preference when individuals 224 with preferences close to or within the range of CT_{min} values were excluded. We found small, 225 but significant, differences with these two approaches. Thus, we present results from both the 226 conservative data set (preferred temperatures below 0.2°C excluded) and the full data set 227 (preferred temperatures below 0.2°C included) as a comparison for all further analyses (see 228 Results). 229

Next, to determine if T_{opt} and T_{pref} are indistinguishable (i.e. coadapted), the medians of T_{opt} and T_{pref} for each treatment group were compared using Wilcoxon rank-sum tests (because of non-normal data). In addition, to determine how asymmetric the performance curves were, the degree of asymmetry was calculated for each individual using the following equation from Martin and Huey (2008):

235

asymmetry =
$$\frac{2T \text{ opt} - T \text{ max} - T \text{ min}}{T \text{ max} - T \text{ min}}$$

(Equation 2)

10

237

where T_{opt} is the temperature at which an individual moved the fastest, and T_{max} and T_{min} are the upper and lower limiting temperatures for performance respectively (Martin and Huey 2008). We used data from our trials to represent T_{max} and T_{min} , and then also included data from Klok & Chown (1997) on CT_{min} and CT_{max} to estimate the degree of asymmetry. In the latter case we included combinations of data that used the minimum values for any individual of CT_{min} and CT_{max} to those which used the maximum values, and applied these to optimum temperature estimates for all acclimations examined in the current study.

To test the 'thermodynamic effect' hypothesis, ordered factorial ANOVAs (analysis of 246 variance) with orthogonal polynomial contrasts as in Huey et al. (1999) were used to 247 248 distinguish 'warmer is better' from the alternative acclimation hypotheses (see Deere and 249 Chown, 2006). These analyses compared T_{opt} , U_{max} and T_{br} between the constant acclimation temperatures of 0°C, 5°C, 10°C, and 15°C, as these temperatures were ordered. Orthogonal 250 251 polynomial contrast analyses require strict adherence to the assumptions of ANOVA, which are: normally distributed residuals, homogeneity of variance and a balanced design (Huey et 252 al., 1999). Shapiro-Wilk's tests showed instances of non-normality, but Levene's tests and 253 plots of the residuals indicated normality and homogeneity of variances (Table S2; Fig S3). 254

Finally, to examine the effects of the fluctuating acclimation temperature on performance, an ANOVA was used to compare performance traits between 5-15°C and 10°C (i.e. the closest comparable constant temperature). Similarly, field-fresh individuals were compared with those that were subjected to acclimation. The effect of acclimation on thermal preference was also examined, and this was done using a Kruskal-Wallis test of significance (because of non-normal data (Fig. S4)). Analyses were implemented in R3.0.0 (R core team, 2013).

263 **3. Results**

The distribution of caterpillars under a constant temperature of c. 10°C showed that caterpillars were unlikely to favour a particular end of the gradient because a similar number of individuals were found at either end, compared to the distribution of caterpillars on the c. 0-30°C gradient where more individuals were found at one end (Fig. S5).

Excluding preferred temperatures below the upper bound we set (0.2°C), increased the 268 median T_{pref} slightly, significantly so in 0°C acclimated individuals (from 4.8°C to 9.4°C; 269 Wilcoxon rank-sum test: W = 264.5, p = 0.028; Fig. 1). Thus, we used both the full data set 270 271 (individuals with preferences below 0.2°C included), as well as the conservative data set (individuals with preferences below 0.2°C excluded) for further analyses, the latter to account 272 for the possibility that caterpillars became trapped at low temperatures (cf. Dillon et al., 2012). 273 Overall, median thermal preference ranged from 4.2-4.6°C (at 5-15°C) to 4.8-9.4°C (at 0°C) 274 (Fig. 2; Table 1). Acclimation at 15°C and 5-15°C yielded the lowest T_{pref} (Table 1). 275

By contrast, median values for T_{opt} of locomotor performance were significantly higher 276 than the preferred temperatures, and ranged between 20°C and 25°C (Table 1, Fig. 3). Mean 277 optimum temperature (T_{opt}), maximum speed (U_{max}) and performance breadth (T_{br}) ranged 278 between 21.4-24.1°C, 4.7-5.4 mm.sec⁻¹, and 16.1-19.8°C, respectively (Table 2). Acclimation 279 to different temperatures did not have a significant effect on locomotor performance (Table 3). 280 Neither T_{opt} nor U_{max} differed significantly between the fluctuating temperature regime of 5-281 15°C and the constant acclimation temperature of 10°C (T_{opt} : F = 0.26, p = 0.61; U_{max} : F = 282 2.60, p = 0.113), but T_{br} was significantly narrower after the 5-15°C acclimation compared to 283 the 10°C treatment (F = 5.36, p = 0.024; Table 2). Acclimation also had no significant influence 284 on thermal preference both when data including preferences below 0.2° C were included (H = 285 4.381, d.f. = 5, p =0.496) and excluded (H = 10.925, d.f. = 5, p =0.053). The performance of 286 field fresh individuals also did not differ significantly from those acclimated ($T_{opt:}$ F = 0.87, p 287

288 = 0.503; U_{max} : F = 1.56, p = 0.174; T_{br} : F = 2.21, p = 0.056). Locomotor performance curves of 289 *P. marioni* were not strongly asymmetric (Figure 4), and this is supported by the low symmetry 290 values for the curves (Table 2), which remained low when including the critical thermal limits 291 data from Klok & Chown (1997) (varying between 0.08 and 0.30 among acclimations and 292 using data either on minimum or maximum critical thermal limit values).

293

294 4. Discussion

In this study, we simultaneously tested the hypothesis of coadaptation of optimal and preferred 295 296 body temperatures (Huey and Bennett, 1987; Angilletta et al., 2002a; Huey et al., 2003; Angilletta 2009), and several of its alternatives (Huey and Stevenson, 1979; Kingsolver and 297 Woods, 1997; Martin and Huey, 2008; Asbury and Angilletta, 2010). Before doing so, we first 298 299 took into account the possibility that animals may have been trapped at the low temperature 300 end of the thermal gradient, resulting in a misinterpretation of the actual preferred temperatures (Dillon et al., 2012). We found some support for immobility at low temperatures influencing 301 estimates of T_{pref} . In consequence, we used a truncated data set, excluding all preference values 302 below 0.2°C to account for potential bias. 303

Bearing this correction in mind, preferred temperatures of *P. marioni* were substantially 304 lower than the optimum temperatures, particularly so when data were not adjusted for the 305 likelihood of individuals being trapped at temperatures below their CT_{min} . These differences 306 were 17.3 for field-fresh caterpillars, and 20.2 following acclimation to 0°C, 14.8 after 5°C, 307 17.1 after 10°C, 20.6 after 15°C and 15.8 after 5-15°C (Table 1a). Thus, we reject the 308 coadaptation hypothesis (Huey and Bennett, 1987; Angilletta et al. 2006; Angilletta, 2009): 309 T_{pref} does not appear to have evolved to match T_{opt} in *P. marioni*. Such large discrepancies 310 between T_{opt} and T_{pref} have also been found in other species, e.g. 11°C in *Pterohelaeus* 311 darlingensis beetles (Allsopp et al., 1980; Allsopp, 1981), 17°C in intertidal snails (Clorostoma 312

funebralis) (Tepler et al., 2011); and 8°C in house geckos, *Hemidactylus turcicus* (Huey et al., 1989; Angilletta et al., 1999). Moreover, the locomotor performance curves of *P. marioni* are more-or-less symmetrical, further suggesting that the 'suboptimal is optimal' hypothesis, which assumes asymmetric performance curves (Martin & Huey 2008), can be rejected as a possible explanation for the large mismatch between T_{opt} and T_{pref} .

An alternative explanation for the current findings is that selection, driven by a 318 319 thermodynamic effect, could explain the large differences between preferred temperature and the thermal optimum (Asbury and Angilletta 2010). Acclimation had little effect on thermal 320 321 performance curves or preferred temperature, however, suggesting that the thermodynamic effect hypothesis can also be rejected. Previous studies have reported varying, but typically 322 small effects of phenotypic plasticity in response to temperature in terrestrial arthropods from 323 Marion Island (Deere and Chown, 2006; Deere et al., 2006; Slabber et al., 2007; Marais & 324 Chown, 2008). Pringleophaga marioni caterpillars show little phenotypic plasticity of 325 metabolic-rate temperature curves in response to acclimation, under both stable and fluctuating 326 acclimation conditions (Chown et al. 2016). Here, we found a similar effect for thermal 327 performance curves based on locomotion speed, and in particular for $T_{\rm opt}$ and $U_{\rm max}$. The 328 unpredictability of thermal cues may explain limited phenotypic plasticity in many species on 329 Marion Island (Deere et al., 2006), including P. marioni caterpillars. Nonetheless, after 330 exposure to fluctuating conditions, caterpillars had a significantly narrower performance 331 332 breadth compared to those held at a constant temperature of 10°C (i.e. closest comparable mean temperature). Performance breadth is expected to change significantly in fluctuating as 333 opposed to constant temperatures depending on whether variation is within or among 334 generations (Huey and Slatkin 1976; Huey and Stevenson 1979; Huey and Kingsolver 1993; 335 Gilchrist, 1995; Huey et al., 1999). Given that 15°C is detrimental to caterpillars within a 336 generation (Haupt et al. 2014a), the narrowing in performance breadth may well have been due 337

to this negative effect of prolonged high temperature, in keeping with theoretical considerations
(Gilchrist, 1995; see also discussion in Dowd et al., 2015; Kingsolver et al., 2015). Thus,
further consideration of the effects of stable versus fluctuating temperatures is warranted, even
when these effects may initially appear to be small. Such fluctuating temperatures, in
association with a symmetric performance curve may also mean that selection for preferred
temperatures matching the optimum may not be pronounced.

344 In the absence of support for the coadaptation, suboptimal is optimal and thermodynamic effect hypotheses, an alternative explanation for the differences we observed 345 between T_{pref} and T_{opt} is that T_{pref} may align with the thermal optimum for some other measure 346 of performance that may be more significant for a detritivorous caterpillar (Haupt et al., 2014a). 347 For example, if the optimum temperature for locomotion is higher than that for growth, then 348 animals may choose a high preference temperature only when the ability to move faster is of 349 350 more immediate importance than the ability to grow quickly (Huey and Stevenson, 1979; Anderson et al., 2011). Thus, T_{pref} will be driven by the T_{opt} only of physiological systems that 351 improve fitness (e.g. Miller et al., 2009; Coggan et al., 2011; Clissold et al., 2013). In the case 352 of P. marioni, caterpillar survival to pupation is higher at 5 to 10°C than at 15°C (Haupt et al., 353 2014a). Similarly, 10°C is the optimum temperature for caterpillar feeding, and low thermal 354 preferences may be linked to nutrient or digestive efficiency of caterpillars feeding on a diet of 355 detritus (Crafford 1990). Compared to the optimum temperature for locomotion (c. 23°C), 356 357 these temperatures more closely match the preferred temperatures of 4.6°C to 9.2°C. Thus, for P. marioni caterpillars on Marion Island, although locomotion may be important for locating 358 food resources and suitable microhabitats that minimise predation (Haupt et al., 2014a, b; 359 360 2016), caterpillars may prefer lower temperatures where survival and assimilation efficiency is maximal (Haupt et al., 2014a), or where costs associated with high temperatures are minimized. 361 Thus, the trait variation hypothesis may explain the large mismatch observed between T_{pref} and 362

363 T_{opt} . We suggest that this hypothesis, and the more general idea of differential effects of 364 temperature on individual traits and on overall fitness (Kingsolver and Woods, 1997; Darveau 365 et al., 2002; Woods and Harrison, 2002) deserve further consideration both for this species and 366 for others.

367

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373

374 Appendix A. Supplementary data

375 Supplementary data associated with this article can be found, in the online version, at xxx

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Table 1

- 582 Median values for thermal preference (T_{pref}) (c. 0-30°C gradient) ((a) = individuals with
- preferences below 0.2° C included, (b) = individuals with preferences below 0.2° C excluded),
- optimum temperature (T_{opt}), the difference between T_{pref} and T_{opt} , and results of the Wilcoxon
- 585 rank-sum test comparing T_{pref} and T_{opt} are shown for each treatment group.

Group	$T_{\rm pref}(^{\circ}{\rm C})$	$T_{\rm opt}(^{\circ}{\rm C})$	Difference (°C)	Wilcoxon rank-sum test
field-fresh	5.2 (n = 35)	22.5	17.3	W = 863, p < 0.0001
acclimation				
0°C	4.8 (n = 35)	25	20.2	W = 868, p < 0.0001
5°C	5.2 (n = 35)	20	14.8	W = 853, p < 0.0001
10°C	5.4 (n = 35)	22.5	17.1	W = 887, p < 0.0001
15°C	4.4 (n = 35)	25	20.6	W = 944, p < 0.0001
5-15°C	4.2 (n = 33)	20	15.8	W = 965, p < 0.0001
n = sample s	size			

586 (a) All individuals

Group	$T_{\rm pref}(^{\circ}{\rm C})$	Number of	$T_{\rm opt}(^{\circ}{\rm C})$	Difference (°C)	Wilcoxon rank-sum test
		individuals with			
		$T_{\rm pref} < 0.2^{\circ}{\rm C}$			
field-fresh	9.2 (n = 25)	10	22.5	13.3	W = 583, p < 0.0001
acclimation					
0°C	9.4 (n = 23)	12	25	15.6	W = 532, p < 0.0001
5°C	8.8 (n = 27)	8	20	11.2	W = 629, p < 0.0001
10°C	8.1 (n = 28)	7	22.5	14.4	W = 691, p < 0.0001
15°C	5.2 (n = 29)	6	25	19.8	W = 776, p < 0.0001
5-15°C	4.6 (n = 24)	11	20	15.4	W = 657, p < 0.0001
n = sample size					

596 (b) Individuals with preferences below 0.2°C excluded

Table 2

600 Summary statistics showing means and standard errors for the performance traits: optimum

	$T_{\rm opt}$	(°C)	$U_{\max}(\mathbf{n})$	m·sec ⁻¹)	$T_{\rm br}$	(°C)	Degree of
	Mean	s.e.	Mean	s.e.	Mean	s.e.	asymmetry
field-fresh	23.8	1.14	4.7	0.18	18.7	0.99	0.31
acclimation							
0°C	23.2	1.04	5	0.24	19.8	0.78	0.36
5°C	21.4	1.09	4.8	0.20	18.6	0.89	0.25
10°C	23.6	1.15	4.9	0.25	18.9	0.92	0.35
15°C	24.1	0.86	5.2	0.26	17.8	0.71	0.38
5-15°C	22.9	0.79	5.4	0.22	16.1	0.77	0.37

601 temperature (T_{opt}) , maximum speed (U_{max}) , and performance breadth (T_{br}) .

607 **Table 3**

608 Outcome of the orthogonal polynomial contrasts on the effects of acclimation on the optimum 609 temperature (T_{opt}) , maximum speed (U_{max}) , and the performance breadth (T_{br}) . In each case, the 610 main effects of acclimation, as well as the orthogonal polynomial contrasts (i.e. linear and 611 quadratic), together with the sign and value of their estimates are shown.

Topt					
Source	d.f.	SS	MS	F	Р
Acc	3	113	37.72	1.25	0.294
Contrast					
acc linear	1	33	32.54	1.08	0.301
acc quadratic	1	38	37.72	1.25	0.265
Parameter		Estimate	s.e.	t	Р
acc linear		1.08	1.04	1.04	0.301
acc quadratic		1.16	1.04	1.12	0.265
U _{max}					
Source	d.f.	SS	MS	F	Р
Acc	3	2.63	0.88	0.55	0.647
Contrast					
acc linear	1	0.89	0.89	0.56	0.455
acc quadratic	1	1.64	1.64	1.03	0.312
Parameter		Estimate	s.e.	t	Р
acc linear		0.18	0.24	0.75	0.455
acc quadratic		0.24	0.24	1.02	0.312

Source	d.f.	SS	MS	F	Р
Acc	3	58	19.34	1.01	0.391
Contrast					
acc linear	1	24.6	45.57	2.38	0.126
acc quadratic	1	0.3	0.26	0.01	0.908
Parameter		Estimate	s.e.	t	Р
acc linear		-1.28	0.83	-1.54	0.126
acc quadratic		0.10	0.83	0.12	0.908

acc = acclimation temperature

SS = sums of squares; MS = mean squares; s.e. = standard error

615 Figure legends

616

Fig. 1. Difference in the thermal preference (median) of *Pringleophaga marioni* caterpillars when CT_{min} values are excluded (excl. CT_{min}) and not (incl. CT_{min}). This is shown for caterpillars acclimated at 0°C, 5°C, 10°C, 15°C, and 5-15°C, as well as field-fresh individuals. Box plots show the median and interquartile range of thermal preference, and boxes in which notches (i.e. narrowing of the box around the median) overlap are unlikely to have significantly different medians under an appropriate test (Crawley 2007).

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Fig. 2. The thermal preference of *Pringleophaga marioni* caterpillars. In (a), individuals with
preferences below 0.2°C are included. In (b) they are excluded. Individuals acclimated at 0°C
(blue), 5°C (green), 10°C (orange), 15°C (red), and 5-15°C (grey), and field-fresh individuals
(black), as the number of counts on a gradient ranging from *c*. 0-30°C.

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Fig. 3. The difference between the optimum temperature (T_{opt}) and thermal preference (T_{pref}) of *Pringleophaga marioni* caterpillars. In (a), individuals with preferences below 0.2°C are included. In (b) they are excluded. Caterpillars acclimated at 0°C, 5°C, 10°C, 15°C, and 5-15°C, as well as field-fresh individuals are shown. Box plots show the median and interquartile range for both T_{opt} and T_{pref} and boxes in which notches (i.e. narrowing of the box around the median) do not overlap are likely to have significantly different medians under an appropriate test (Crawley 2007).

Fig. 4. The locomotor performance of *Pringleophaga marioni* caterpillars, i.e. speed (mm.sec⁻
¹) over test temperatures at 0°C to 35°C, at five acclimation treatments: 0°C (blue), 5°C (green),

- 639 10°C (purple), 15°C (red) and 5-15°C (grey dashed), and field-fresh (FF) individuals (black)
- 640 (Mean \pm SE)



646 Figure 2a





Figure 3a

field-fresh





































692 Appendix A. Supplementary data

- 694 Table S1
- ⁶⁹⁵ Thermal preference of *Pringleophaga marioni* caterpillars on a gradient of *c*. 0-15°C (medians

696	of thermal preference a	are shown for eacl	h acclimation	temperature).
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Acclimation temperature (°C)	Thermal pre	eference (°C)
	CT _{min} values included	CT _{min} values excluded
0°C	0.6	6.7
5°C	7	9.5
10°C	3.4	6.6
15°C	3.6	7
5-15°C	2.8	7.3

712 **Table S2**

Results from a Shapiro-Wilk's test for normality and Levene's test for homogeneity of variances for each test conducted on T_{opt} , U_{max} and T_{br} . These were: i) an ANOVA comparing all groups together, i.e. field fresh, 0°C, 5°C, 10°C, 15°C and 5-15°C, ii) orthogonal polynomial contrast analyses, which compared the equally spaced acclimation temperatures of 0°C, 5°C, 10°C and 15°C, and iii) an ANOVA in which the 5-15°C and 10°C acclimation temperatures were compared to examine the effects of fluctuating versus constant acclimation temperatures.

	Test	Shapiro-Wilk's	Levene's
	All groups		
	$T_{\rm opt}$	W = 0.89, p < 0.0000	F = 1.21, d.f. = 5,162, p = 0.3044
	$U_{ m max}$	W = 0.99, p = 0.5262	F = 0.64, d.f. = 5,166, p = 0.5664
	$T_{ m br}$	W = 0.93, p < 0.0000	F = 0.78, d.f. = 5,166, p = 0.5664
	0, 5, 10, and 15°C		
	$T_{\rm opt}$	W = 0.89, p < 0.0000	F = 0.96, d.f. = 3,108, p = 0.4127
	$U_{ m max}$	W = 0.99, p = 0.5262	F = 0.29, d.f. = 3,108, p = 0.8348
	$T_{ m br}$	W = 0.94, p < 0.0000	F = 0.61, d.f. = 3,108, p = 0.6120
	5-15 and 10°C		
	$T_{\rm opt}$	W = 0.89, p < 0.0000	F = 4.33, d.f. = 1,54, $p = 0.0423$
	U_{\max}	W = 0.99, p = 0.5262	F = 0.61, d.f. = 1,54, p = 0.4393
	$T_{ m br}$	W = 0.93, p < 0.0000	F = 1.37, d.f. = 1,54, p = 0.2467
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Fig. S1. The experimental set-up of the thermal preference gradient with inserts of the squirrel
data logger (A), plastic refuges (B), and the stage covered with a black plastic bag to eliminate
light (C).



Fig. S2. The walking stage used in locomotor performance trials (details are given in the text).



Fig. S3a. Model assumption plots (i.e. normal probability plots and residual versus fitted value plots) to test normality and equal variances for the ANOVA in which performance measures (i.e. T_{opt} , U_{max} and T_{br}) between all groups (i.e. field fresh, 0°C, 5°C, 10°C, 15°C and 5-15°C acclimation temperatures) were compared.







Fig. S4. Residual plots of thermal preference at all acclimation temperatures (0°C, 5°C, 10°C, 15°C and 5-15°C), as well as field fresh individuals on a gradient of *c*. 0-30°C showing (a) the residuals versus fitted values, and (b) a normal probability plot. A Shapiro-Wilk's test indicated that data were not normally distributed (W = 0.91, p < 0.0001), and a Levene's test showed that variances were not equal (F = 3.26, d.f. = 5,150, p = 0.008).



Fig. S5. The distribution of 10°C acclimated individuals on the gradient at a constant temperature of *c*. 10°C (n = 35, grey bars), compared to temperatures ranging from *c*. 0-30°C (n = 28, black bars).