Efficient and Virtualized Scheduling for OFDM-Based High Mobility Wireless Communications Objects

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A thesis submitted in partial fulfillment of the requirements for the degree in Doctor of Philosophy

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Abstract

Services providers (SPs) in the radio platform technology standard long term evolution (LTE) systems are enduring many challenges in order to accommodate the rapid expansion of mobile data usage. The modern technologies demonstrate new challenges to SPs, for example, reducing the cost of the capital and operating expenditures while supporting high data throughput per customer, extending battery life-per-charge of the cell phone devices, and supporting high mobility communications with fast and seamless handover (HO) networking architecture. In this thesis, a variety of optimized techniques aimed at providing innovative solutions for such challenges are explored.

The thesis is divided into three parts. The first part outlines the benefits and challenges of deploying virtualized resource sharing concept. Wherein, SPs achieving a different schedulers policy are sharing evolved network B, allowing SPs to customize their efforts and provide service requirements; as a promising solution for reducing operational and capital expenditures, leading to potential energy savings, and supporting higher peak rates. The second part, formulates the optimized power allocation problem in a virtualized scheme in LTE uplink systems, aiming to extend the mobile devices’ battery utilization time per charge. While, the third part extrapolates a proposed hybrid-HO (HY-HO) technique, that can enhance the system performance in terms of latency and HO reliability at cell boundary for high mobility objects (up to 350 km/hr; wherein, HO will occur more frequent).

The main contributions of this thesis are in designing optimal binary integer programming-based and suboptimal heuristic (with complexity reduction) scheduling algorithms subject to exclusive and contiguous allocation, maximum transmission power, and rate constraints. Moreover, designing the HY-HO based on the combination of soft and hard HO was able to enhance the system performance in term of latency, interruption time and reliability during HO. The results prove that the proposed solutions effectively contribute in addressing the challenges caused by the demand for high data rates and power transmission in mobile networks especially in virtualized resources sharing scenarios that can support high data rates with improving quality of services (QoSs).

Keywords: LTE, Virtualization, QoSs, SPs Schedulers’ Policy, Resources Sharing, LTE UL Scheduling, Efficient Power Allocation, Mobility, Handover.
Acknowledgments

All praise goes to ALLAH for the blessing of completing this thesis. Pursuing doctoral degree in The University of Western Ontario is a memorable experience for me. It is with pleasure that I write this page to express my joy and to acknowledge all those who have supported me in successfully completing this thesis. I have no doubt that I could not have been able to do it without the love, and support of my family, friends, and colleagues.

First and foremost, I would like to express my deepest gratitude and graciously appreciation to my supervisors; Professor Abdallah Shami and Professor Serguei Primak for all their encouragement, fruitful cooperation, precious guidance, and philosophy that I have received and learned from them at every stage of the research. The valuable discussions we had were always a source of inspiration to me.

It is a wonderful feeling to express my thanks to my colleagues for their help in conducting the research. I am grateful for their valuable advice which I implemented in my experiments. I am also glad to extend my thanks to the Department of Electrical and Computer Engineering at Western University for their assistance while conducting my studies in the lab.

I owe a special word of indebtedness to my mother, father, and brothers. Although, they are thousands of miles away from me during the days I studied in Canada, I can always get the strongest support from them. There are no words sufficient enough to express my full gratitude to my parents.

My heartfelt thanks go out to my beloved wife for her constant inspiration, encouragement, sacrifice, and tolerance during my research work; I am extremely thankful to her for taking care of our sweet sons during this journey. My family and wifes prayers during this period have helped tremendously in completing the research work successfully.

Thank you,

Mohamed Hussein Abdelwahab Ahmed
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<td>3GPP</td>
<td>Third Generation Partnership Project</td>
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<tr>
<td>4G</td>
<td>Fourth Generation Wireless Systems</td>
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<tr>
<td>ACK</td>
<td>Acknowledge or Acknowledgment</td>
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<tr>
<td>A/D</td>
<td>Analog-to-Digital</td>
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<tr>
<td>AF</td>
<td>Assured Forwarding</td>
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<td>AMC</td>
<td>Adaptive Modulation and Coding</td>
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<tr>
<td>Apps</td>
<td>Application Server</td>
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<td>ARQ</td>
<td>Automatic Repeat Request</td>
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<td>BE</td>
<td>Best Effort</td>
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<td>BER</td>
<td>Bit Error Rate</td>
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<td>BIP</td>
<td>Binary Integer Programming</td>
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<td>BLER</td>
<td>Block Error Rate</td>
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<td>BPSK</td>
<td>Binary Phase Shift Keying</td>
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<td>BS</td>
<td>Base Station</td>
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<td>BSR</td>
<td>Buffer Status Report</td>
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<td>BW</td>
<td>Bandwidth</td>
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<td>C-OFDM</td>
<td>Coded Orthogonal Frequency Division Multiplexing</td>
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<td>CAPEX</td>
<td>Capital Expenditure</td>
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<td>CBR</td>
<td>Constant Bit Rate</td>
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<td>CDMA</td>
<td>Code Division Multiple Access</td>
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<td>CP</td>
<td>Cyclic Prefix</td>
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<td>CQI</td>
<td>Channel Quality Indicator</td>
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<td>CRC</td>
<td>Cyclic Redundancy Check</td>
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<td>CSI</td>
<td>Channel State Information</td>
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<td>D2D</td>
<td>Device-to-Device</td>
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<td>DFT</td>
<td>Discrete Fourier Transform</td>
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<td>DL</td>
<td>Downlink</td>
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<td>Acronym</td>
<td>Description</td>
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<tr>
<td>DRA</td>
<td>Dynamic Resource Allocation</td>
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<td>DRX</td>
<td>Discontinuous Reception</td>
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<td>DS</td>
<td>Dynamic Sharing</td>
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<tr>
<td>DSL</td>
<td>digital Subscriber Line</td>
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<tr>
<td>DTX</td>
<td>Discontinuous Transmission</td>
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<td>DwPTS</td>
<td>Downlink Pilot Time Slot</td>
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<td>E-UTRA</td>
<td>Evolved UMTS Terrestrial Radio Access</td>
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<td>E-UTRAN</td>
<td>Evolved UMTS Terrestrial Radio Access Network</td>
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<td>EDGE</td>
<td>Enhanced Data Rates for GSM Evolution</td>
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<td>EF</td>
<td>Expedite Forwarding</td>
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<td>eNB</td>
<td>Evolved Node B</td>
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<td>EPC</td>
<td>Evolved Packet Core</td>
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<td>FDD</td>
<td>Frequency Division Duplex</td>
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<td>FDM</td>
<td>Frequency Division Multiplexing</td>
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<td>FDMA</td>
<td>Frequency Division Multiple Access</td>
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<td>FFT</td>
<td>Fast Fourier Transform</td>
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<tr>
<td>GBR</td>
<td>Guaranteed Bit Rate</td>
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<td>GP</td>
<td>Guard Period</td>
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<td>GPRS</td>
<td>General Packet Radio Service</td>
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<td>GSM</td>
<td>Global System for Mobile Communication</td>
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<tr>
<td>GW</td>
<td>Gateway</td>
</tr>
<tr>
<td>HARQ</td>
<td>Hybrid ARQ</td>
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<tr>
<td>HetNet</td>
<td>Heterogeneous Networks</td>
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<tr>
<td>HHO</td>
<td>Hard Handover</td>
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<tr>
<td>HO</td>
<td>Handover</td>
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<tr>
<td>HSPA</td>
<td>High Speed Packet Access</td>
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<tr>
<td>HSPA+</td>
<td>High Speed Packet Access Evolved</td>
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<tr>
<td>Abbreviation</td>
<td>Description</td>
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<tr>
<td>HY-HO</td>
<td>Hybrid Handover</td>
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<tr>
<td>ICI</td>
<td>Inter-Carrier Interference</td>
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<tr>
<td>IEEE</td>
<td>Institute of Electrical and Electronics Engineers</td>
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<tr>
<td>IFFT</td>
<td>Inverse Fast Fourier Transform</td>
</tr>
<tr>
<td>IMS</td>
<td>IP Multimedia Subsystem</td>
</tr>
<tr>
<td>IP</td>
<td>Internet Protocol</td>
</tr>
<tr>
<td>ISI</td>
<td>Inter-Symbol Interference</td>
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<tr>
<td>I.S.</td>
<td>Internal Scheduler</td>
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<tr>
<td>kbps</td>
<td>kilo-bits per second</td>
</tr>
<tr>
<td>KHz</td>
<td>Kilo Hertz</td>
</tr>
<tr>
<td>LBS</td>
<td>Level of Bearer Satisfaction</td>
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<tr>
<td>LP</td>
<td>Linear Programming</td>
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<td>LTE</td>
<td>Long Term Evolution</td>
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<tr>
<td>LWDF</td>
<td>Largest Weight Delay First</td>
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<tr>
<td>MAC</td>
<td>Medium Access Control</td>
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<td>MC-OFDMA</td>
<td>Multi-Carrier Orthogonal Frequency Division Multiple Access</td>
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<tr>
<td>MCS</td>
<td>Modulation and Coding Scheme</td>
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<td>MIMO</td>
<td>Multiple Input Multiple Output</td>
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<td>MME</td>
<td>Mobility Management Entity</td>
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<tr>
<td>MMF</td>
<td>Maximum-Minimum Fairness</td>
</tr>
<tr>
<td>MNO</td>
<td>Mobile Network Operator</td>
</tr>
<tr>
<td>MR</td>
<td>Maximum Rate</td>
</tr>
<tr>
<td>NGBR</td>
<td>Non-Guaranteed Bit Rate</td>
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<tr>
<td>OFDM</td>
<td>Orthogonal Frequency Division Multiplexing</td>
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<td>OFDMA</td>
<td>Orthogonal Frequency Division Multiple Access</td>
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<td>OPEX</td>
<td>Operating Expenditure</td>
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<tr>
<td>PAPR</td>
<td>Peak-to-Average Power Ratio</td>
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</table>
PC       Power Control
PDB      Packet Delay Budget
PDCP     Packet Data Convergence Protocol
PDU      Protocol Data Unit
PF       Proportional Fair
PGW      Packet Gateway
PHEVs    Plug-in Hybrid Vehicles
PHY      Physical Layer
PLER     Packet Loss Error Rate
PSK      Phase Shift Key
QAM      Quadrature Amplitude Modulation
QCI      QoS Class Identifiers
QoS      Quality of Service
QPSK     Quadrature Phase Shift Keying
RAN      Radio Access Network
RB       Resource Block
RE       Resource Element
RF       Radio Frequency
RLC      Radio Link Control
RN       Relay Node
RRC      Radio Resource Control
RRM      Radio Resource Management
RSRP     Reference Symbol Received Power
RSRQ     Reference Signal Received Quality
RSSI     Received Signal Strength Indicator
S-GW     Serving Gateway
S1-U     S1 - User Plane
<table>
<thead>
<tr>
<th>Abbreviation</th>
<th>Full Form</th>
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<tbody>
<tr>
<td>SC</td>
<td>Single Carrier</td>
</tr>
<tr>
<td>SC-FDMA</td>
<td>Single Carrier - Frequency Division Multiple Access</td>
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<tr>
<td>SFN</td>
<td>Single Frequency Network</td>
</tr>
<tr>
<td>SHO</td>
<td>Soft Handover</td>
</tr>
<tr>
<td>SIB</td>
<td>System Information Block</td>
</tr>
<tr>
<td>SLA</td>
<td>Service of Level Agreement</td>
</tr>
<tr>
<td>SNR</td>
<td>Signal-to-Noise Ratio</td>
</tr>
<tr>
<td>SPs</td>
<td>Services providers</td>
</tr>
<tr>
<td>SS</td>
<td>Static Sharing</td>
</tr>
<tr>
<td>S.P.</td>
<td>Strict Priority</td>
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<tr>
<td>TB</td>
<td>Transport Block</td>
</tr>
<tr>
<td>TDD</td>
<td>Time Division Duplex</td>
</tr>
<tr>
<td>TTI</td>
<td>Transmission Time Interval</td>
</tr>
<tr>
<td>UE</td>
<td>User Equipment</td>
</tr>
<tr>
<td>UL</td>
<td>Uplink</td>
</tr>
<tr>
<td>UMTS</td>
<td>Universal Mobile Telecommunications System</td>
</tr>
<tr>
<td>UPE</td>
<td>User Plane Entity</td>
</tr>
<tr>
<td>UpPTS</td>
<td>Uplink Pilot Time Slot</td>
</tr>
<tr>
<td>VBR</td>
<td>Variable Bit Rate</td>
</tr>
<tr>
<td>VoIP</td>
<td>Voice over Internet Protocol</td>
</tr>
<tr>
<td>VRB</td>
<td>Virtual Resource Blocks</td>
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<tr>
<td>WCDMA</td>
<td>Wideband Code Division Multiple Access</td>
</tr>
<tr>
<td>Wi-Fi</td>
<td>Wireless Fidelity</td>
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<tr>
<td>WiMAX</td>
<td>Worldwide Interoperability for Microwave Access</td>
</tr>
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Chapter 1

Introduction

Emerging broadband wireless access technologies nowadays face the long-term challenge of properly addressing air-link channel limitations and reconciling these limitations with the growing demand for services with fast mobility and widespread coverage. One of the most demanding and challenging scenarios is the high-mobility scenario [1, 2].

The Third Generation Partnership Program-Long Term Evolution (3GPP-LTE) system adopts the orthogonal frequency division multiplexing (OFDM) and multi-input multi-output (MIMO) techniques [3] in order to satisfy the fast-growing demand of wireless data, wherein services providers (SPs) revenues in LTE systems are not growing at the same rate as the traffic volume. In order to handle the rapid increase in mobile data traffic, more suitable business models with higher capacities should be deployed.

Coded orthogonal frequency division multiplexing (C-OFDM) which is a form of OFDM where error correction coding is incorporated into the signal, has been developed into a popular scheme for wideband digital communication, and is used in applications such as digital television and audio broadcasting, digital subscriber line (DSL) broadband internet access, wireless networks, and Fourth Generation (4G) mobile communications. The primary advantage of OFDM over single-carrier schemes is its ability to cope with severe channel conditions (for example, narrowband interference and frequency-selective fading due to multipath) without complex equalization filters [4].

Channel equalization is simplified because OFDM may be viewed as using many slowly
modulated narrow band signals rather than one rapidly modulated wideband signal [5]. The low symbol rate makes the use of a guard interval between symbols affordable, making it possible to eliminate intersymbol interference (ISI) and utilize echoes and time-spreading to achieve a diversity gain, i.e. an improvement in the signal-to-noise ratio (SNR).

Modern wireless communication systems strive to achieve two very contrasting objectives, namely increasing system performance while well as improving energy efficiency for green communications [6]. In fact, both these goals have been heavily focused on since the adoption of early wireless systems; while the definition of system performance has evolved over time.

### 1.1 Thesis Contributions

In our way to evolve towards the future, my main objective is to enhance the quality of services’ (QoS) parameters in wireless networks that can stand with the nowadays raising mobile data usage [7, 8]. In this thesis, a variety of optimized techniques that aim to provide innovative solutions for this objective are explored.

The first part outlines the benefits of deploying virtualization in terms of resource sharing concept. Wherein, SPs achieving different schedulers’ algorithms can share a single evolved network B (eNB). This part shows how the delay parameter can be improved. The second part, proposed the power allocation problem in a virtualized scheme in LTE uplink (UL) systems. That aims to prolong the mobile devices’ battery utilization time per charge. While, the third part proposes the hybrid-Handover (HY-HO) technique that can enhance the system performance in terms of latency and HO reliability for high mobility objects (up to 350 km/hr; wherein, HO will occur more frequent) [9].

The main contributions of this thesis are in proposing the optimal binary integer programming (BIP)-based and suboptimal heuristic (with less computational complexity) algorithms subject to exclusive and contiguous allocation, maximum transmission power, and rate constraints. Moreover, designing the HY-HO based on the combination of soft and hard HO was
able to enhance the system performance in term of latency, interruption time and reliability during HO. The results prove that the proposed solutions can effectively contribute in addressing the challenges caused by the demand for high data rates and power transmission in mobile networks and also in improving QoS parameters [10].

1.2 Thesis Organization

The thesis is organized into six chapters where the technical contributions of this thesis are contained in Chapters 3 to 5. Prior to introducing the technical contributions, in Chapter 2, I provide detailed background on the problem domain with an introduction to communication systems for high-mobility objects, introduce the main task for this thesis, and summarize some of the recent state-of-the-art advances in the area concentrated on in this thesis.

The technical contributions of this thesis begin in Chapter 3. I propose a novel design for a virtualized resources’ sharing technique with investigation that analyze and test the users performance in terms of delay QoSs parameter, wherein, SPs using different scheduling algorithms are sharing their physical radio resources blocks (RBs) in one eNB in a virtualized scheme as a promising solution for reducing operational and capital expenditures, leading to potential energy savings, and supporting higher peak rates. The proposed method makes use to schedule traffic with various delay and priority requirements.

The contributions of this chapter was partially presented in IEEE international conference on wireless communications and mobile computing [11], that evaluates the average packets jitter and delays for cases of non-sharing and sharing schemes, with the goal to close the growing gap between the capacities of backbone networks, that yields notable improvements in average packet delay.

In Chapter 4, I concentrate on detailing the focuses on the specification and analysis of a proposed technique for modeling an optimized solution for the simulated sharing scheme methodology used in Chapter 3. Wherein, I proposed a design for a dynamic scheduling pol-
icy framework for an arbitrary number of queues and channels for single-carrier frequency division multiple access (SC-FDMA) UL which meets exclusive and contiguous allocation, maximum transmission power, and rate constraints restrictions while minimizing the average applied transmission power for a time-invariant channel to achieve green communication.

Chapter 4 was partially presented in IEEE international conference on wireless and mobile computing, networking and communications [12]. The major contributions are proposing both optimal BIP-based and suboptimal lower complexity heuristic scheduling algorithms to minimize overall average applied power, and compared their performance in terms of average applied power and computational complexity.

In Chapter 5, I analyze the performance of UEs random-way mobility model and HO algorithms for high-mobility users within the sharing virtualized scenario in LTE systems. A HY-HO technique is proposed to address the shortcomings of the existing approaches and the challenges caused by the demand for high data rates. The HY-HO was able to enhance the system performance in term of interruption time, reliability and latency during HO at the cell boundary.

The contributions of this chapter appear in IEEE international Canadian conference on electrical and computer engineering [13], wherein, the HY-HO virtualized scheme is capable of achieving great improvements with respect to delay when compared to the non-sharing application. Overall, the results confirm that the HY-HO framework yields notable improvements in average packet delay, without degrading QoS.

Finally; Chapter 6 summarizes and draws the main conclusions in this thesis and propose some further research directions in this area.
Chapter 2

Background and Literature Review

This chapter provides an introduction to the main technologies that are related to the scope of this thesis. First, multi-carrier systems OFDM and orthogonal frequency division multiple access (OFDMA) are introduced as the basic technique used in the recent radio LTE networks in both UL/downlink (DL) transmissions. Later, LTE is presented, followed by the description of system architecture jointly with main features and characteristic. At the end of the chapter, a summary is approached as an introduction for the coming thesis’s contributions.

LTE is the standard cellular technology for wireless communication of high speed data for mobile phones and data terminals that is emerged as one of the most promising access network technologies, launched by the 3GPP to support diversity of traffic at potentially high rates [14, 15] with greater flexibility for heterogeneous networks and flatter networks. In this chapter, an overview on the state-of-the-art research related to this thesis is provided including background on the 3GPP-LTE systems technology.

2.1 Multicarrier Systems

OFDM, the method of encoding data on multi-carrier subcarriers. OFDM has developed widely for wide band digital communications, with many applicable approaches, for example, audio broadcasting, digital television, and DSL Internet access, power-line networks, wireless
networks, and 4G communications networks.

It is a frequency-division multiplexing (FDM) approach that is used as a digital multiple carriers method. Wherein, a large number of close spaced orthogonal sub-carrier signals are carrying data on multiple parallel data channels. Each subcarrier is modulated with a conventional modulation scheme (such as quadrature amplitude modulation (QAM) or phase-shift keying (PSK)) at a low symbol rate, maintaining total data rates similar to conventional single-carrier (SC) modulation schemes in the same bandwidth.

The main advantage of OFDM over SC techniques is the ability to work with severe channel conditions (like, high frequencies’ attenuation in a long copper wire, frequency-selective fading due to multi-path, and narrow band interference) with simple equalization filters. Moreover, the channel equalization is simplified since OFDM may be viewed as using multi-slow narrow band modulated signals instead of one rapid wide-band modulated signal. As a result, the low symbol rate takes the advantage of the guard interval between symbols. That makes it possible to cancel any ISI, utilize echoes and time-spreading to achieve higher diversity gain, i.e. a SNR improvement.

This mechanism facilitates the design of single frequency techniques, where several contiguous transmitters send the same signal at the same frequency, where signals from different distant transmitters can be combined constructively, instead of interfering that would typically occur in normal single-carrier system. OFDM and OFDMA are multi-carrier systems, a brief description of both is presented in this section.

### 2.1.1 OFDM and OFDMA

The main idea of a multi-carrier modulation is to divide the transmitted bit stream into different sub-streams and send these over many different channels. It is based on the principle of transmitting individually many narrow-band orthogonal frequencies, sub-carriers [16]. The number of sub-carriers is noted as $N_s$. These frequencies are orthogonal to each other, which cancels the interference between channels. If a data symbol is $N_s$ times longer, compared to
2.1. **MULTICARRIER SYSTEMS**

SC, it provides to OFDM a much better multi-path resistance, which together with orthogonal carriers allows a high spectral efficiency.

The basic premise of a multi-carrier modulation is to split this wide-band system into \( N_s \) linearly-modulated subsystem in parallel, each with Subchannel Bandwidth is:

\[
B_N = \frac{B}{N_s} \quad (2.1)
\]

where: \( B \) is the pass-band bandwidth.

The bandwidth sub-channel is lower than the coherence band \( (B_C) \) for \( N_s \) sufficiently large and ensures relatively flat fading on each sub-channel. Also, with \( N_s \) sufficiently large, the symbol time is much longer than the delay spread, so each sub-channel experiences low ISI degradation.

The input data stream is linearly-modulated, resulting in a complex symbol stream. This symbol stream is divided into \( N \) sub-streams via a serial-to-parallel converter, as shown in Figure 2.1.

**Figure 2.1:** OFDM with IFFT implementation (Tx).

OFDM theory shows that the inverse Fourier fast transform (IFFT) of magnitude \( N_s \), applied on \( N_s \) symbols, realizes one OFDM signal, where each symbol is transmitted on one of the \( N_s \) orthogonal frequencies. The IFFT operator realizes the reverse operation of the fast Fourier transform (FFT). The FFT is a matrix computation that allows the discrete Fourier transform (DFT) to be computed. When \( N_s \) is power of 2 the complexity of the FFT is reduced.

Since the channel output is a linear convolution instead a circular one (needed for IFFT/FFT),
a special prefix is added to the input called a cyclic prefix (CP), so the linear convolution between the input and impulse response can be turned into a circular convolution.

The CP can also serve to eliminate ISI between the data blocks, since CP samples are also the first samples (as guard interval) of the channel output which are affected by ISI. These samples can be discarded without any loss relative to the original sequence, since there is no new information.

At the receiver section, the ISI associated with the end of a the OFDM symbol is added again to the symbol, which re-creates the effect of a cyclic prefix. The zero cyclic prefix decreases the power transmitted relative to cyclic prefix by $N_s/(N_s + \mu)$, as the prefix does not need any transmit power. However, the received noise is added to the beginning of the symbol, which increases the noise power by $(N_s + \mu)/N_s$.

CP allows the receiver to absorb much more efficiently the delay spread due to the multipath and to maintain frequency orthogonality. This CP is a temporal redundancy that must be taken into account in data rates computations. The ratio $\mu/N_s$ is chosen taking some considerations into account. If the multipath effect is important, a high value of this ratio is needed, which increases the redundancy and then decreases the useful data rate. On the other hand if the multipath effect is lighter, a relatively smaller value of this ratio can be used.

OFDM transmission was originally conceived for a single user; therefore, it had to be associated to a multiple user access scheme so that several users could be served. OFDMA is the scheme to be used. OFDMA allows the access of multiple users on the available bandwidth. Each user is assigned a specific time-frequency resource.

OFDMA subcarriers are divided into subsets of subcarriers, each subset representing a subchannel, as shown in Figure 2.2).

In the DL, a sub-channel may be intended for different receivers or groups of receivers; in the UL a transmitter may be assigned one or more sub-channels. The subcarriers forming one sub-channel may be adjacent or not.

The multiple access has a new dimension with OFDMA. A DL or an UL user will have a
2.1. MULTICARRIER SYSTEMS

2.1.2 Key Challenges

The peak to average power ratio (PAPR) is a very important feature in any communication system. The low PAPR makes it possible for the transmit power amplifier to operate more efficiently, whereas the high PAPR makes the transmit power amplifier to have a high back-off for ensuring linear amplification for the signal.

The operation in the linear region of this response is totally required to eliminate the distortion of the signal, so this peak value is considered to be in that region. Having these peak and average values close together as possible, is preferable, to have the power amplifier operating with its the maximum efficiency.

For $N$ subcarriers, the maximum PAPR is $N$. In practice, the full coherent addition of all $N$ symbols is improbable, so the observed PAPR is less than $N$, usually many dB. Moreover, the PAPR increases linearly with the number of subcarriers. Although it is required to have $N$ as large as it can be to keep the over-head associated with the cyclic prefix down, the large PAPR is the expected penalty that must be paid for a large $N$.

A high PAPR requires high resolution for the receiver analog/digital (A/D) convertor, since the dynamic range of the signal is much larger for high PAPR signals. High resolution A/D
conversion places a complexity and power burden on the receiver front end.

2.2 Background of LTE Systems

LTE is part of the Global System for Mobile Communications (GSM) evolutionary path for mobile broadband, following General Packet Radio Service (GPRS), Enhanced Data rates for GSM Evolution (EDGE), Universal Mobile Telecommunications System (UMTS), HSPA, and its evolution (HSPA+) [17, 18] as shown in Figure 2.3. Although HSPA and HSPA+ are strongly positioned to be the dominant mobile data technology for the next decade, the 3GPP family of standards must evolve toward the future.

The need for LTE is to provide an extremely highly performance radio access technology that offers full vehicular speed mobility [11, 19], and that can readily coexist with HSPA and earlier networks. And, because of the scalable bandwidth, operators will be able to easily migrate their networks and users from HSPA to LTE over time.

2.2.1 LTE Objectives

The main overall objectives [20] for LTE are:

1. Reduced cost for the operator,
2. Efficient spectrum utilization,
3. Minimizing energy consumed per user,  
4. Improved spectral efficiency,  
5. Improved system capacity, and coverage,  
6. Increased DL and UL peak data rates with reduced latency,  
7. Scalable bandwidth with flexible spectrum allocation,  
8. All IP network,  
9. Support different traffic types,  
10. and, satisfying the service of level agreement (SLA) between users per SP, customers, and between SPs sharing the same eNB.

2.2.2 eNBs Main Functions

The following are the functions assigned to eNBs [5, 21] for radio resource management in the E-UTRAN:  
1. Radio bearer control,  
2. Radio admission control,  
3. Connection mobility management,  
4. Dynamic resource allocation (scheduling),  
5. Inter cell interference coordination,  
6. and, load balancing.

2.2.3 LTE Performance of Demands

The LTE performance demands [19] could be simplified as:  
1. Date rate: For 20 MHz spectrum, the target for peak data rate is 50 Mbps for UL, and 100 Mbps for DL,  
2. Bandwidth: flexible usage of spectrum from 1.4 MHz to 20 MHz,  
3. Peak spectral efficiency: for DL is of average 3.2 bps/Hz, and for UL is 1.05 bps/Hz,  
4. Spectral efficiency of cell edge: is 0.04-0.06 bps/Hz/user for DL and 0.02-0.03 bps/Hz/user for UL,  
5. Average cell spectral efficiency: for DL is 1.6-2.1 bps/Hz/cell and for UL it is 0.66-1.0 bps/Hz/cell,
6. Data type: All packet switched data (voice, video, and data),
7. Packet call throughput: DL avg. 256 Kbps, and for UL is 15 Kbps,
8. Average user throughput: DL is 3.6 Mbps, and for UL is 0.45 Mbps,
9. Latency: is less than 50 ms (for dormant to active). The user-plane latency is less than 5 ms from user equipment (UE) to server,
10. Call setup time: 50 ms,
11. Broadcast data rate: 3.072 Kbps,
12. Modulation types supported: BPSK, QPSK, 16QAM, 64QAM,
13. Access schemes: SC-FDMA has been chosen as the UL access scheme for its low peak-to-average power ratio (PAPR) properties compared to multi-carrier orthogonal frequency division multiple access (MC-OFDM) in DL,
14. Security: is used at good level with the earlier systems starting from GSM.

### 2.2.4 LTE Performance with Respect to Mobility

Table 2.1 summarizes the LTE performance versus various mobility speeds, and shows that the LTE is able support high mobility up to 350 km/h [9, 22], and is at good level compared to the earlier wireless systems shown in Figure 2.3.

<table>
<thead>
<tr>
<th>Mobile speed</th>
<th>Mobility</th>
<th>LTE performance</th>
</tr>
</thead>
<tbody>
<tr>
<td>Stationary</td>
<td>Low mobility</td>
<td>Optimized high performance</td>
</tr>
<tr>
<td>Walking</td>
<td>Low mobility</td>
<td>Optimized high performance</td>
</tr>
<tr>
<td>Race walkers</td>
<td>Low mobility</td>
<td>Optimized high performance</td>
</tr>
<tr>
<td>Vehicular</td>
<td>Medium mobility</td>
<td>Marginal degradation</td>
</tr>
<tr>
<td>High speed</td>
<td>High mobility</td>
<td>Maintain connection with QoS</td>
</tr>
<tr>
<td>Extremely high</td>
<td>Extremely high</td>
<td>Not supported</td>
</tr>
</tbody>
</table>

### 2.2.5 LTE Traffic Quality of Services

The QoSs’ requirements and recommendations differ according to the type of traffic [23, 24], such that the QoS for voice traffic include:

1. Loss \(\leq 1\) percent. (packet error loss \(\leq 10^{-2}\)),
2. One-way latency (mouth-to-ear) should be \(\leq 100\) ms,
3. Packet delay $\leq 20$ ms,

and, unlike voice, video uses a variety of packet sizes and packet rates to support a single video stream, and the QoS recommendations for video traffic include:

1. Packet delay $\leq 150$ ms,
2. Packet error loss : $\leq 10^{-3}$,
3. The average bit rate varies between of 64 kbps to 1.2 Mbit/s,

while, the QoS recommendations for data traffic include:

1. Packet delay $\leq 300$ ms,
2. Packet error loss : $\leq 10^{-3}$.

The LTE system architecture is shown in Figure 2.4, where the evolved-[UMTS] terrestrial radio access network (E-UTRAN) [25], uses a simplified single node architecture consisting of the eNB [26] to communicate with users’ equipments (UEs), while the eNB communicates with other eNB using X2-C and X2-U interfaces for control and user plane respectively, for example in mobile end UE HO situations. The eNB communicates with the evolved packet core (EPC) using the S1 interface; specifically with the mobile management entity (MME) and the user plane entity (UPE) identified as serving gateway (S-GW), using S1-C and S1-U interfaces for control plane and user plane respectively, that supports a many-to-many relation between MMEs/UPEs and eNBs, and by its turn is connected by the internet protocol (IP) Multimedia Subsystem (IMS), and the application server (Apps). The MME and the UPE are preferably implemented as separate network nodes so as to facilitate independent scaling of the control and user plane.

### 2.2.6 LTE Spectrum Flexibility

The most important value in the LTE requirements in terms of spectrum flexibility is the ability to use LTE based radio access in unpaired and paired spectrum [20]. Therefore, LTE
is able to support both frequency- and time-division-based duplex transmissions. Frequency division duplex (FDD) [27] as illustrated to the left in Figure 2.5 implies that DL and UL transmission take place in different, sufficiently separated, frequency bands. Time division duplex (TDD), as illustrated to the right in Figure 2.5, shows that DL and UL transmission can take place in non-overlapping, different time slots. Then, TDD can work in unpaired spectrum, whereas, FDD requires paired spectrum.

LTE also can support half-duplex FDD (illustrated in the middle of Figure 2.5). In half-duplex FDD, the transmission and reception at a certain terminal are separated in both frequency and time. The base station can still use full duplex as it may schedule different transmissions in UL and DL; that is the same case in the GSM operation.

The main advantage with half-duplex FDD is the reduced complexity as no duplex filter is required in the terminal, which is much beneficial in case of multi-band terminals that otherwise would require many sets of duplex filters.
2.2. Background of LTE Systems

Figure 2.5: Frequency and time division duplex.

2.2.7 LTE Frame Structure

The LTE frame structure is set for two types: type-1 LTE FDD, and type-2 LTE TDD mode systems. Type-1 frame structure that works on both half duplex and full duplex FDD modes [27]. That type of radio frame usually has duration of 10 ms and consists of 20 slots, each slot has the equal duration (0.5 ms). The sub-frame consists of two slots, one radio frame has 10 sub-frames. In the FDD mode, DL and UL transmission is divided in frequency domain, so half of all sub-frames can be used for DL and half for UL, in radio frame interval of 10 ms. Type-2 frame structure consists of two identical half frames of 5 ms duration each. Both half frames have 5 sub-frames with duration of 1 ms.

TDD mode uses frame structure type 2. In this structure, the slots, sub-frames and frames have the same duration, but each subframe can be allocated to either the UL or DL [20, 23, 24], using one of the TDD configurations as shown in Figure 2.6.

One sub-frame consists of two slots and each slot has duration of 0.5 ms. There are some special sub-frames which consist of three fields; guard period (GP), DL pilot time slot (Dw-PTS) and UL pilot time slot (UpPTS). These three fields are individually configurable, but each sub-frame shall have a total length of 1ms.
There are seven UL/DL configurations used for either 5 ms or 10 ms switch-point periodicities. Note that, a special sub-frame exists in half frames in case of 5 ms switch-point time-period whereas, for 10 ms switch-point time-period the special frame exists only in the first half-frame. Table 2.2 shows the UL/DL frame configuration for LTE TDD, and simplified in Figure 2.7.

<table>
<thead>
<tr>
<th>Configuration</th>
<th>DL to UL</th>
<th>SF0</th>
<th>SF1</th>
<th>SF2</th>
<th>SF3</th>
<th>SF4</th>
<th>SF5</th>
<th>SF6</th>
<th>SF7</th>
<th>SF8</th>
<th>SF9</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>5 ms</td>
<td>DL</td>
<td>SF</td>
<td>UL</td>
<td>UL</td>
<td>UL</td>
<td>DL</td>
<td>SF</td>
<td>UL</td>
<td>UL</td>
<td>UL</td>
</tr>
<tr>
<td>1</td>
<td>5 ms</td>
<td>DL</td>
<td>SF</td>
<td>UL</td>
<td>UL</td>
<td>DL</td>
<td>DL</td>
<td>SF</td>
<td>UL</td>
<td>UL</td>
<td>DL</td>
</tr>
<tr>
<td>2</td>
<td>5 ms</td>
<td>DL</td>
<td>SF</td>
<td>UL</td>
<td>DL</td>
<td>DL</td>
<td>DL</td>
<td>SF</td>
<td>UL</td>
<td>DL</td>
<td>DL</td>
</tr>
<tr>
<td>3</td>
<td>10 ms</td>
<td>DL</td>
<td>SF</td>
<td>UL</td>
<td>UL</td>
<td>UL</td>
<td>DL</td>
<td>DL</td>
<td>DL</td>
<td>DL</td>
<td>DL</td>
</tr>
<tr>
<td>4</td>
<td>10 ms</td>
<td>DL</td>
<td>SF</td>
<td>UL</td>
<td>UL</td>
<td>DL</td>
<td>DL</td>
<td>DL</td>
<td>DL</td>
<td>DL</td>
<td>DL</td>
</tr>
<tr>
<td>5</td>
<td>10 ms</td>
<td>DL</td>
<td>SF</td>
<td>UL</td>
<td>DL</td>
<td>DL</td>
<td>DL</td>
<td>DL</td>
<td>DL</td>
<td>DL</td>
<td>DL</td>
</tr>
<tr>
<td>6</td>
<td>5 ms</td>
<td>DL</td>
<td>SF</td>
<td>UL</td>
<td>UL</td>
<td>DL</td>
<td>SF</td>
<td>UL</td>
<td>UL</td>
<td>UL</td>
<td>DL</td>
</tr>
</tbody>
</table>

Where, SF is a subframe and it is used for guard time, DL is a subframe and it is used for DL transmission, and UL is a sub-frame and it is used for UL transmission.

Different cells can have different TDD configurations, which are advertised as part of the cells system information. Configuration 1 might be suitable if the data rates are similar on the UL and DL, for example, while configuration 5 might be used in cells that are dominated by DL transmissions. Nearby cells should generally use the same TDD configuration, to minimize
2.2. Background of LTE Systems

Figure 2.7: TDD configuration.
the interference between the UL and DL.

Special subframes are used at the transitions from DL to UL transmission. They contain three regions. The special DL region takes up most of the subframe and is used in the same way as any other DL region. The special uplink region is shorter, and is only used by the random access channel and the sounding reference signal. The two regions are separated by a guard period that supports the timing advance procedure described below. The cell can adjust the size of each region using a special subframe configuration, which again is advertised in the system information.

Figure 2.8 shows the relationship between a slot, symbols, and physical radio RBs. The sub-carriers are divided into RBs, which is the basic resource allocation unit for scheduling in 3GPP-LTE system. $N_{RB}$ is the symbol used to indicate the maximum number of RBs for a given bandwidth. This allows the system to split the sub-carriers into small parts, without mixing the data across the total number of sub-carriers for a given bandwidth. The basic unit is a resource element (RE), which spans one symbol by one sub-carrier. Each resource element usually carries two, four or six physical channel bits, depending on whether the modulation scheme is QPSK, 16-QAM or 64-QAM. Resource elements are grouped into RBs, each of which spans 0.5ms (one slot), by 180 kHz (12 sub-carriers). The base station uses RBs for frequency-dependent scheduling, by allocating the symbols and sub-carriers within each sub-frame in units of RBs.

The LTE signal can be represented in a two dimensional map. The horizontal axis is time domain and the vertical axis is frequency domain. The minimum unit on vertical axis is a sub-carrier and on horizontal axis is symbol [20].

In the frequency domain structure, any SC-FDMA/OFDMA band is made up of multiple small spaced channels, and each of these small channels is called as "sub-carrier". Space between the channel and the next channel is always same regardless of the system BW of the LTE band. So, if the system BW of the LTE channel changes, number of the channels (sub-carriers) change, but the space between channels does not change. In Figure 2.9, the rela-
2.2. **Background of LTE Systems**

The LTE system is designed to provide high-speed data rates and efficient spectrum usage. Key components include Resource Blocks (RBs), OFDM symbols, and subcarriers. The relationship between these elements is as follows:

- **Radio Frame**: 10 ms
- **Subframe (TTI)**: 1 ms
- **Slot**: 0.5 ms
- **Resource Block**: $N_{RB} \times N_{RB}^{SC}$
- **Subcarriers**: $N_{RB} \leq 100$

The bandwidth is typically 15 KHz, which can be scaled to support different frequency bands. The OFDM symbol (time) is 6 to 100, and the subcarrier (frequency) is 180 KHz $= 15$ KHz $\times 12$ subcarriers.

![Diagram of LTE system components](image)

**Figure 2.8**: The relationship between a slot, symbols, and RBs.

Moreover, the LTE system offers flexibility in terms of spectrum usage, ranging from 1.4 MHz to 20 MHz [28] as illustrated in Figure 2.10.

**2.2.8 UL/DL Information Exchange**

In UL transmission of LTE, there are additional signals such as reference signal, random access preamble, and control signal, etc. These signals are specified as a sequence signalling with constant amplitude and zero auto-correlation.

These signals are not part of SC-FDMA modulation scheme. The base stations scheduling algorithm decides the contents of every DL scheduling command and UL scheduling grant, based on all available information. Each bearer is associated with a buffer occupancy, priority, and prioritized bit rate.
Figure 2.9: The relationships between channel bandwidth, and transmission bandwidth configuration.

Figure 2.10: The transmission bandwidth configuration.
To support the scheduling function, the mobile returns hybrid automatic repeat request (H-ARQ) acknowledgments (Acks) [29], channel quality indicators and rank indications [30]. The eNB also knows the discontinuous reception (DRX) pattern for every UE in the cell and can receive load information from nearby cells about their own use of the sub-carriers. Figure 2.11 shows the most common of the main inputs and outputs commands and data exchange.

With the use of this information, the scheduler has to determine how much information in bits are required to send to each user, even to send a new transmission or a re-transmission and how to classify new transmissions through the available bearers. It also needs to determine the used modulation schemes and coding rates, spatial multiplexing, and the allocation of RBs to every mobile UE.

The UL scheduler usually follows the same concept, although some of the inputs and outputs are different. For example, the eNB does not have the full knowledge about the UL buffer occupancy and does not tell the UEs which channels they shall use for their transmissions. Moreover, the eNB calculate its channel quality data from the sounding procedure, instead of the UEs’ channel quality indicators (CQIs).

The UL scheduler follows the same principles, although some of the inputs and outputs are different. For example, the eNB does not have complete knowledge of the UL buffer occupancy and does not tell the UEs which logical channels they should use for their UL transmissions. In addition, the eNB derives its channel quality information from the sounding procedure, instead of from the UEs channel quality indicators.
The given example in Figure 2.12 introduces one SP, serving two users, the first user (UE-1) is considered to be the near user (1.2 Km far from the eNB), has high SNR ($SNR_h$), while UE-2 is the far user (1.8 Km far from the eNB), has low SNR ($SNR_l$). The figure shows an overview of the information exchange procedure in both UL and DL connection between an eNB, and UE-1, and 2, considering an already ongoing transfer data, noting that TDD is considered, using type Frame 2, with Configuration 2, where DL:UL = 3:2, functioning with packet data convergence protocol (PDCP), where the eNB scheduler takes its scheduling mapping decision every half frame, and one frame time period, where The UE transmits buffer status report (BSR) medium access control (MAC) control elements to tell the base station about how much data it has available for transmission.

Where, the UE sends the BSR in three situations:

1. if data is ready for transmission on the channel with high priority than the previously storing buffers were,
2. or if data is ready for transmission when the transmit buffers were empty,
3. or if the timer expires while data is waiting for transmission.

The mobile expects the base station to reply with a scheduling grant. Considering the CQI [30], which is the indicator that carries the information on how good or bad the communication channel quality is, as it is the information that UEs send to the network and practically it implies the following two indications:

1. Current communication channel quality,
2. Data transport block size,

that in turn can be directly translated into throughput, and the buffer status report include the QoS of each Bearer, sounding measurements, modulation schemes, and the transport block (TB) size.
2.2. Background of LTE Systems

Figure 2.12: The information exchange procedure in both UL and DL connection between an eNB, and two UEs.
2.3 Chapter Summary

In this chapter, an overview on the recent radio platform LTE technology that depends on the OFDM communication method is presented. LTE system use SC-FDMA for UL transmission and OFDMA for DL transmission. This system is capable of reaching a peak data-exchange rate of 50 Mbps for UL transmission and 100 Mbps for DL transmission; the main motivation for our research is to model our research problems in order to make an effective contribution.

Nevertheless, there has been a small amount of pioneering work in this area trying to enhance and contribute the wireless QoSs’ parameters. This has been accomplished by making various assumptions or simplifications to the system or simply by focusing on a subset of the overall scheduling problem. In the coming chapters, I propose several different approaches in this research domain.
Chapter 3

Sharing Resources in 3GPP-LTE Systems

Framework

Nowadays, much research and standardization efforts are evolving in order to withstand more capable facilities at high effective points. The purpose of this work is to address some of these issues by demonstrating several novel dynamic allocation sharing algorithms in LTE systems. This algorithm will help in increasing the performance over a broader range of subscriber access scenarios.

Specifically, this Chapter proposes a novel dynamic scheduling sharing algorithm that can support guaranteed QoS for multiple types of applications in the wireless networks. The proposed algorithm reduces the packet delay and jitter for delay-sensitive applications, such as narrow-band voice. This considerably enhance the related delay performance without degrading QoS parameters for all service types.

3.1 Introduction

Recently, network sharing has been proposed as an integral part of the next-generation networking architecture for vehicular communications, and is considered to be a promising solution to provide low-cost framework, and accommodate increased traffic demands [31, 32].
Sharing radio resources management in LTE systems leads to successful virtualization of the wireless access networks that have received much attention by network operators. Virtualizing the wireless resources enables MNOs to create multiple logical networks based on a single physical substrate. Recently, there has been a dramatic increase in the amount of network data traffic, primarily driven by the rising number of users demanding increased data rates. Moreover, a wide range of increasingly bandwidth-intensive services are continuing to emerge (e.g., storage extension/virtualization, grid computing, packet video teleconferencing, and so on) [11].

A mobile network operator (MNO), commonly known as a service provider, wireless carrier, cellular company, or mobile network carrier [33], is a provider of the wireless services communications that controls all the necessary elements to rent/sell and deliver services to the end UE including the spectrum allocation, network and back haul infrastructure, customer care, provisioning systems, billing, and marketing and repair organizations.

This chapter proposes a novel dynamic scheduling sharing resources algorithm for different types of applications in access networks. The framework scheme shares MNOs’ resources while maintaining different scheduling strategies. The proposed algorithm considerably improves related delay performance without degrading QoS. The research below offers detailed simulations to study the performance of the proposed algorithm and validate its effectiveness.

### 3.2 Related Work

During the latest basic literature, MNOs sharing RBs have gained significant attention. Jing et al. in [27] presented the resource sharing on the relay link according to the buffer state at the relay nodes (RNs) for urban scenarios without applying a power control (PC) optimization, and their results including the suburban scenarios are also provided in [34].

In latter approach, Zaki et al. in [35], proposed an LTE air interface virtualization scheme wherein a hypervisor is added on top of physical resources, that takes the responsibility of vir-
3.2. Related Work
tualizing the eNB into a number of virtual eNBs that are then used by different MNOs. As an extension to [36], the discussed some practical scenarios in [37]; where MNOs share multiple eNBs. The managed in the sharing process is controlled by the so-called hypervisor. Moreover, two traffic models (best effort model and the guaranteed bit rate model) have been considered for resource sharing.

Kokku et al. in [38] proposed and evaluated a flow-level virtualization scheme of wireless resources on base stations in worldwide interoperability for microwave access (WiMAX) cellular systems. The proposed solution enables customized flow scheduling per slice and takes into account the level of isolation and resource utilization trade-off. Each slice can be seen as a virtual MNO and contains a number of flows. The goal of achieving dynamic and efficient resource sharing is moved to the scheduler by Min et al. in [39]; which can instantaneously adapt to changes in system conditions, rather than relying on semi-static radio interface sub-frame allocation.

In addition, in [40], O. Bulakci et al. presented the relay-enhanced networks, where a combination of resource allocation on the relay link based on the number of attached UEs; and a throughput throttling scheme achieving max-min Fairness (MMF) in the end-to-end two-hop communication have been proposed.

Some advanced resource sharing mechanisms are discussed such as the schemes based on interference graph by Necker et al. in [41], or game theory by Menon et al. in [42]. Game theory based resource sharing models the resource allocation as the outcome of a game. In [43, 44], Bulakci and Kokku investigated the cooperative methods relying on information exchange between the cells that yield significant performance improvement comparing to non-cooperative solutions, but at the cost of high signaling overhead.

Roth et al. in [45], investigated the time-division and frequency-division multiplexing of relay and access link transmissions on the DL excluding the resource sharing within the links. Another framework for wireless network virtualization that separates SPs from network operator is reported by Fu et al. in [46]. Wherein, the SPs are in charge for QoS management, while
spectrum management is maintained by the network operator.

3.3 System Modeling Framework

In the LTE architecture, the eNB is the node between the UE and the core network. It is responsible for the radio resource management (RRM) functions (transmission power management, mobility management and radio resource scheduling) [47, 48, 49]. As the bandwidth of wireless communication system is scarce and very expensive, the RRM is workable with OFDMA. Then the radio resource scheduling is a significant process in which the available radio resources are assigned to all active UEs efficiently in terms of QoS requirements.

The LTE sharing framework is shown in Figure 3.1. Let $k$ denotes the number of MNOs sharing the eNB. Each MNO has various numbers of UEs, as well as its own associated EPC, RBs and scheduling algorithm. The eNB establishes multiple radio bearers per UE to support multiple traffic types.

In the considered frame work scenario, the eNBs scheduler algorithm explore the contents of every UL scheduling requested grant [50] and, reply to UEs with the decided scheduling mapping commands specifying the assigned RBs, power control entity, modulation and coding scheme (MCS) on the basis of all the information available to it at the time, FDD is considered, functioning with PDCP, where the eNB Scheduler takes its scheduling mapping decision every one sub-frame time period (1 ms), where The UE transmits BSR MAC control elements to inform the base station (eNB) about how much data available for transmission. Considering the CQI, and the BSR include the QoS of each Bearer, sounding measurements, modulation schemes, and the $TB$ size.

3.3.1 Data Transmission Sequence

The sequence of data transmission for $M$ UEs is shown in Figure 3.2. The UEs receive UL traffic from upper layers. Data from multiple logical channels are queued in the radio link
control (RLC) sub-layer buffers. Information about buffered data sizes is sent to the eNB over the UL control channel known as the BSR. The eNB’s scheduler performs allocation decisions according to the SPs’ scheduling policy. And based on the mapped decisions, the eNB sends the maps to the UEs over the the DL control channel. The UEs’ allocation map consists of the assigned RBs, power control entity and MCSs [30, 51].

The RBs chunk and MCS that is assigned to a user specifies the UL transport block (TB) size. Noting that, how the TB is shared between a user’s buffers is left to the UE policy [11]. In the UE’s MAC sub-layer, the MAC protocol data unit (PDU) is performed according to the received map. The MAC PDU extrapolates the data from all RLC PDUs and the MAC header. The MAC passes the MAC PDU to the physical layer (PHY), that adds the cyclic redundancy check (CRC) bits to the MAC PDU and transmits the whole packet as a TB over the UL channel to the eNB.
3.3.2 LTE Traffic Classes

The LTE sharing framework is shown in Figure 3.1. Let $k$ denotes the number of MNOs sharing the eNB. Each MNO has various numbers of UEs, as well as its own associated EPC, RBs and scheduling algorithm. The eNB establishes multiple radio bearers per UE to support multiple traffic types [52].

In order to support different classes of service with different packet jitter and delay requirements, three prioritized service classes are introduced: expedite forwarding (EF) [53] with the highest priority for strictly delay sensitive services typically constant bit rate (CBR) voice transmission, assured forwarding (AF) with medium priority for services of non-delay sensitive variable bit rate (VBR) services such as video stream, and best effort (BE) with the lowest priority for delay tolerable services, which include web browsing and background file transfer [11].

A key motivation was the inherently non-deterministic nature for AF and BE. Packets in dedicated bearers are generated at the application layer by 3 different traffic generators: Voice traffic, trace based, and infinite buffer.

The voice traffic application generates G.729 voice flows. In particular, the voice flow
has been modeled with an ON/OFF Markov chain, where the ON period is exponentially distributed with a mean value of 3 s, and the OFF period has a truncated exponential probability density function with an upper limit of 6.9 s and an average value of 3 s [54, 55]. During the ON period, the source sends 20 bytes-sized packets every 20 ms (i.e., the source data rate is 8 kb/s), while during the OFF period, the rate is zero because the presence of a voice activity detector is assumed. The trace-based application sends packets based on realistic video trace files, available in [56] using H-264 compression format. The BE application generates packets with VBR, assuming Packets arrive according to Poisson distribution, with an exponential inter-arrival mean time and size of 200 ms, and 2400 bits. Figure 3.3 shows a simplified explanation for the considered traffic classes.
Figure 3.3: EF, AF, and BE considered traffic classes.
### 3.3.3 Transmission Block Size and MCSs

In LTE, the subframe has a duration of 1 ms. The available spectrum is divided into RBs. The RB is defined in both frequency and time domains. It consists of a contiguous set of 12 subcarriers (180 kHz with subcarrier spacing of 15 KHz) from each OFDM symbol and has a duration of 0.5 ms.

The overall TB size is a function of the spectral efficiency ($\zeta_s$) of the selected MCS $s$ and the number of allocated RBs. The total RB bandwidth is $12 \times BW$, where $BW$ is the subcarrier bandwidth. The total TB size, that can be transmitted per subframe over $R$ RBs for UE$_m$, is given by:

$$T_{m,R,s}(t) = \left\lfloor 12(N_{sys} - N_{OH}) \times \zeta_c(t) \times ||R|| \right\rfloor$$  \hspace{1cm} (3.1)

where $N_{sym}$ is the number of symbols per subcarrier in a given subframe, while $N_{OH}$ is the number of overhead symbols per subcarrier (usually 3 symbols). The value $N_{OH} \geq 0$ allows any additional overhead per TB. When normal cyclic prefix is used ($N_{sym} = 14$ symbols); each subframe consists of 11 symbols per subcarrier, each with a duration of $T_s = 66.7 \mu s$.

The total number of symbols in one RB per subframe is $12 \times 11 = 132$ OFDM symbols. Therefore, the TB size can be calculated as:

$$T_{m,R,s}(t) = \left\lfloor 132 \times \zeta_c(t) \times ||R|| \right\rfloor,$$  \hspace{1cm} (3.2)

where, $\zeta_c$ is the spectral efficiency of the MCS $c$. The received SNR determines the MCS [57, 58, 59] that should be used to deliver TB with a 10% block error rate. The MCS selection scheme is enacted using a lookup table that maps the received SNR to MCS [30, 60]. Table 3.1 shows MCSs that are used in LTE and how they are mapped to the received SNR for BLER 10%. Figure 3.4 shows the spectral efficiency and TB size versus SNR investigated from Table 3.1.

The channel between eNB and UEs is modeled as a block Rayleigh fading, which is constant over each RB bandwidth, but changes independently over RBs and UEs. The channel is
Table 3.1: List of MCS which are used in LTE.

<table>
<thead>
<tr>
<th>Index</th>
<th>Modulation</th>
<th>Coding rate</th>
<th>$\xi_c$</th>
<th>SNR (dB)</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>-</td>
<td>-</td>
<td>0 bits</td>
<td>-6.7536</td>
</tr>
<tr>
<td>1</td>
<td>QPSK</td>
<td>78/1024</td>
<td>0.15237</td>
<td>-6.7536 : -4.9620</td>
</tr>
<tr>
<td>2</td>
<td>QPSK</td>
<td>120/1024</td>
<td>0.2344</td>
<td>-4.9620 : -2.9601</td>
</tr>
<tr>
<td>3</td>
<td>QPSK</td>
<td>193/1024</td>
<td>0.3770</td>
<td>-2.9601 : -1.0135</td>
</tr>
<tr>
<td>4</td>
<td>QPSK</td>
<td>308/1024</td>
<td>0.6016</td>
<td>-1.0135 : +0.9638</td>
</tr>
<tr>
<td>5</td>
<td>QPSK</td>
<td>449/1024</td>
<td>0.8770</td>
<td>+0.9638 : +2.8801</td>
</tr>
<tr>
<td>6</td>
<td>QPSK</td>
<td>602/1024</td>
<td>1.1758</td>
<td>+2.8801 : +4.9182</td>
</tr>
<tr>
<td>7</td>
<td>16QAM</td>
<td>378/1024</td>
<td>1.4766</td>
<td>+4.9182 : +6.7005</td>
</tr>
<tr>
<td>8</td>
<td>16QAM</td>
<td>490/1024</td>
<td>1.9141</td>
<td>+6.7005 : +8.7198</td>
</tr>
<tr>
<td>9</td>
<td>16QAM</td>
<td>616/1024</td>
<td>2.4063</td>
<td>+8.7198 : +10.515</td>
</tr>
<tr>
<td>10</td>
<td>64QAM</td>
<td>466/1024</td>
<td>2.7305</td>
<td>+10.515 : +12.450</td>
</tr>
<tr>
<td>11</td>
<td>64QAM</td>
<td>567/1024</td>
<td>3.3223</td>
<td>+12.450 : +14.348</td>
</tr>
<tr>
<td>12</td>
<td>64QAM</td>
<td>666/1024</td>
<td>3.9023</td>
<td>+14.348 : +16.074</td>
</tr>
<tr>
<td>13</td>
<td>64QAM</td>
<td>772/1024</td>
<td>4.5234</td>
<td>+16.074 : +17.877</td>
</tr>
<tr>
<td>14</td>
<td>64QAM</td>
<td>873/1024</td>
<td>5.1152</td>
<td>+17.877 : +19.968</td>
</tr>
<tr>
<td>15</td>
<td>64QAM</td>
<td>948/1024</td>
<td>5.5547</td>
<td>+19.968</td>
</tr>
</tbody>
</table>

assumed to be frequency non-selective, constant over each RB bandwidth, but changes independently over RBs and users.

3.3.4 LTE Frame work Scenario

The flowchart of the LTE frame work is illustrated in Figure 3.5, assuming $M$ MNOs, each with $N$ users, and UE is expected to send various types of traffic classes, the internal scheduler per user sends its BSR (in its long format that stands on more than one bearer, and up to four bearers), and the CQI. The BSR is assumed to include how much data is available for transmission, QoS, sounding references measurements, modulation schemes, etc.

Each MNO work with its associated EPC, and its own radio physical RBs. The eNB establishes multi-radio bearers for each user to support multi-traffic types. Each bearer is only assigned to a UE. The number of the working bearers is controlled by an admission control procedure. Each MNO owns a set of RBs $R$, and there are no intersection between the MNOs RBs.
3.4. The Considered Scheduling Algorithms

Packet scheduling revenues in radio platform technology standard LTE systems are the charge of allocating resources to active flows in both frequency and time domain. Many schedulers have been discussed in [7, 11, 51, 61, 62, 63], comparing their data throughput, delay, fairness, etc; trying to reach the most effective performance among the schedulers resources allocation algorithms, as resource allocation for each UE is usually based on the comparison of per-RB metrics: the k-th RB allocated to the j-th user. Its metric $m_{j,k}$ is verified, i.e., if it satisfies the equation:

$$m_{j,k} = \max_i \{m_{i,k}\} \quad (3.3)$$

Herein, the presented framework is for 2 MNOs: MNO-1 cares about fairness between users, but with priority appliance among traffic classes, so; it will apply strict priority (S.P.) scheduling; However, MNO-2 cares more about achieving revenues by transmitting the maximum weight of packets delay; largest weight delay first (LWDF) scheduling could be applied,
Figure 3.5: LTE flowchart for $M$ MNOs, $N$ UEs, and various Traffic Classes considered.
3.4. The Considered Scheduling Algorithms

Table 3.2: Defined necessary parameters.

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Definition</th>
</tr>
</thead>
<tbody>
<tr>
<td>$av_{RBs}$</td>
<td>Number of available RBs at definite $TTI$</td>
</tr>
<tr>
<td>$D_{HOL,i,j}$</td>
<td>Head of line delay for traffic class $i$ for $UE_j$</td>
</tr>
<tr>
<td>$N$</td>
<td>Total number of RBs</td>
</tr>
<tr>
<td>$N_{cl}$</td>
<td>Number of Traffic Classes</td>
</tr>
<tr>
<td>$n_{i,RB,j}$</td>
<td>Number of RBs allocated to $UE_j$ for Traffic Class $i$</td>
</tr>
<tr>
<td>$n_{i,j}$</td>
<td>Number of needed RBs to satisfy traffic $i$ for $UE_j$</td>
</tr>
<tr>
<td>$n_{RB,j}$</td>
<td>Number of RBs allocated to $UE_j$</td>
</tr>
<tr>
<td>$RB_{BW}$</td>
<td>Size of available RB that could be allocated to $UE_j$</td>
</tr>
<tr>
<td>$RBS_i$</td>
<td>RBs BW allocated to $UE_j$</td>
</tr>
<tr>
<td>$S_i$</td>
<td>Needed BW to satisfy traffic $i$ (in bits) by all UEs</td>
</tr>
<tr>
<td>$T_i$</td>
<td>Delay threshold for traffic class $i$</td>
</tr>
<tr>
<td>$TTI$</td>
<td>Transmission Time Interval</td>
</tr>
<tr>
<td>$U$</td>
<td>Total number of UEs</td>
</tr>
<tr>
<td>$V_{ij}$</td>
<td>BSR size of queue $i$ for UE $j$, where $i = 1$ for EF $i = 2$ for AF $i = 3$ for BE</td>
</tr>
<tr>
<td>$W_{ij}$</td>
<td>Weight factor of delay for traffic class $i$ for $UE_j$</td>
</tr>
<tr>
<td>$\delta_i$</td>
<td>Acceptable packet loss rate for traffic class $i$</td>
</tr>
<tr>
<td>$[.]^*$</td>
<td>The new value of $[.]$</td>
</tr>
</tbody>
</table>

followed by internal scheduler (I.S.) per UE, that distribute RBs among the traffic classes‘ queues. In order to formularize the considered schedulers policies, it is helpful to consider some necessary parameter definitions as shown in Table 3.2.

3.4.1 The Strict Priority Scheduling Algorithm

The S.P. scheduling algorithm allocate RBs according to the priority of the considered traffic class, while maintaining fairness between UEs. The pseudo-code for the S.P. scheduler is shown in Figure 3.6.

3.4.2 The LWDF Scheduling Algorithm

The guaranteed delay services, in particular, need that all packets have to be received within a specific deadline to avoid packet drops. This aim can be ensured by considering into the metric data about the exact packet timing, that is both the time when the packet was sent
Figure 3.6: Pseudo-code for the strict priority scheduler.

1: For each simulated TTI do
2:   \( a_{RB} = N_{RB} \) // Total available RBs
3:   // phase i: RBs Allocation for traffic Class i (Priority-i)
4:   For \( i = 1 \) to \( N_{cl} \) do
5:     If \( a_{RB} > 0 \) Then
6:       For \( j = 1 \) to \( N_{UE} \) do
7:         // Requested RBs to satisfy traffic i for UEj
8:           \( n_{ij} = \left\lceil \frac{v_{ij}}{s_{RB}} \right\rceil \)
9:       End For
10:     \( S = \sum_{j=1}^{N_{UE}} n_{ij} \) // total requested RBs by traffic i for UEj
11:     For \( j = 1 \) to \( N_{UE} \) do
12:       // Allocated RBs for Traffic Class i for UEj
13:       \( n_{i, RBj} = \min \left( n_{ij}, \text{floor} \left( \frac{n_{ij} \times s_{RB}}{s} \right) \right) \)
14:     End For
15:     \( a_{RB} = N_{RB} - \sum_{j=1}^{N_{UE}} n_{i, RBj} \) // Available RBs
16:   End If
17:   Repeat
18:     For \( j = 1 \) to \( N_{UE} \) do
19:       Sort UEj by \( \frac{n_{ij}}{n_{i, RBj}} > 1 \) Descending
20:     If \( a_{RB} > 0 \) Then
21:       \( n_{i, RBj}^* = n_{i, RBj} + 1 \)
22:     \( a_{RB}^* = a_{RB} - 1 \)
23:   End If
24:   // Satisfy either allocation request or vanished available RBs
25:   Until \( \frac{n_{ij}}{n_{i, RBj}} \leq 1 \) or \( a_{RB} = 0 \)
26: \( a_{RB} = N_{RB} - \sum_{i=1}^{N_{cl}} \sum_{j=1}^{N_{UE}} n_{i, RBj} \) // Total available RBs after allocation to traffic i for UEj
27: End For // End of Simulation
28: \( n_{RBj} = \sum_{i=1}^{N_{cl}} n_{i, RBj} \) // Number of RBs allocated to UEj
and its deadline. LWDF policy is defined mostly for real-time operating system and wired networks [64], that aim at avoiding deadline expiration. Intuitively, the more the head of line delay approaches the expiration time, the more the user metric increases. LWDF metric is based on the system parameter $\delta_i$, representing the acceptable probability for the $j^{th}$ user that a packet is dropped due to deadline expiration, that could be expressed by:

$$W_{ij} = \alpha_{ij} \times D_{\text{HOL},ij} \quad (3.4)$$

$$\alpha_i = -\log(\delta_i)/T_i \quad (3.5)$$

where: $W_{ij}$ is the weight factor of delay for traffic class $i$ for $UE_j$, $T_i$ is the Delay threshold for traffic class $i$, $\delta_i$ is the acceptable packet loss rate for traffic class $i$, $D_{\text{HOL},ij}$ is the head of line delay for traffic class $i$ for $UE_j$.

In fact, $\alpha_i$ weights the metric so that the user with strongest requirements in terms of acceptable loss rate and deadline expiration will be preferred for allocation. The pseudo-code for the LWDF scheduler is shown in Figure 3.7.

To reduce control signalling overhead, the LTE standard recommends that, for each sub-frame, only one MCS should be used for all allocated users RBs [11, 12, 30]. The RBs chunk and MCS that is assigned to a user determine the UL TB size. However, how the TB is shared between users buffers is left to the user; As distributing the TB into a different users bearers is
Figure 3.7: Pseudo-code for the largest weight delay first scheduler.
3.4.3 The UE’s Internal Scheduler

The UE’s I.S. targeting to perform scheduling between its traffic classes, where the scheduler distributes the received grant among the different active RBs according to the priority of their highest flow based on latest buffer status information (which may have changed since the buffer status was reported) taking into account the cell load, priority of other UEs data, etc. The block diagram of the I.S. working procedure is shown in Figure 3.8. The pseudo-code for the UE’s I.S. is shown in Figure 3.9.

3.5 Sharing Radio Resources Strategy

Nowadays, the networks’ resources sharing has been considered to be as an important part of the next-generation networking architectural. The total RBs R set is assumed to be fully pooled and accessible to the MNOs [11, 32]. RBs are assigned in accordance to the following agreement:

1. Each bearer per MNO should receive at least the level of bearer satisfaction (LBS). In
1: For each simulated TTI do
2:     For j = 1 to N_{UE,j} do
3:         n_{RB,j} = n_{RB,j} x RB_{gw}
4:         If n_{RB,j} > 0 Then
5:             // phase i: mapping RBs for traffic i (Priority-i)
6:                 For i = 1 to N_{ci} do
7:                     If n_{RB,i} > 0 Then
8:                         V_{ij} = n_{RB,i}
9:                         Else
10:                             U_{ij} = n_{RB,i}
11:                             // Buffer size at definite TTI
12:                             V_{ij}^* = V_{ij} - n_{RB,i}
13:                             n_{RB,i}^* = n_{RB,i} - U_{ij}
14:                     End If
15:                 End For
16:             End If
17:         End For
18:     End For
19: End For // End of Simulation

Figure 3.9: The pseudo-code for the UE’s internal scheduler.
3.5. Sharing Radio Resources Strategy

In this case, the LBS is typically defined in terms of throughput, jitter, minimum delay, or a combination of two or more of them. This condition ensures isolation among users, and between MNOs on the bearer-level. And also, it protects their LBS from other MNOs traffic fluctuations.

2. MNOs should be able to perform their own preferred scheduling algorithms to achieve their SLA. MNOs have various QoS requirements to satisfy their own billing and charging models. To meet each MNO’s SLA while maximizing their revenues, MNOs can apply various scheduling algorithms.

Now, let’s consider the system modeling using the two MNOs, and with resources sharing. The MNOs share $R$ radio RBs in a single eNB as seen in Figure 3.10. The shared radio access network connects MNOs, and manages the radio resources allocation between them according to the MNOs sharing agreement conditions.

And as mentioned before that; each MNO owns a set of RBs $\{R_i\}$ such that

$$R_i \cap R_j = \emptyset, \text{ and } R = R_i \cup R_j.$$  \hspace{1cm} (3.9)

Here, another parameter which is the blocking rate ($B_r$) should be defined, that is the ratio between the number of blocked requests and the total number of requests in long interval simulation time TTI. For example, consider two MNOs with 10 RBs each, and TTI for 3 frames with RBs allocation per frame (10 ms), as in Figure 3.11.

From Figure 3.11, and considering non sharing resources scenario, $B_r$ can be calculated as $3/57 \approx 5\%$, but in case of resources sharing, $B_r$ is calculated to be $1/57 \approx 1.7\%$ since there is only 1 blocked request in the third frame (considering 100 weight of sharing between MNOs), also the gain which is how much free RBs used to cover MNOs request in the TTI per frame, is calculated to be $(2/57)/3 \approx 1.2\%$ per frame. Later on, the weight of sharing between MNOs will be illustrated.

And in addition for the previous considerations, it is assumed that each bearer per MNO
Figure 3.10: MNOs, achieving different schedulers policy, and sharing radio RBs in a single eNB.

<table>
<thead>
<tr>
<th>MNO</th>
<th>Frame #1</th>
<th>Frame #2</th>
<th>Frame #3</th>
</tr>
</thead>
<tbody>
<tr>
<td>MNO-1</td>
<td>request 8 RBs (2 RBs free)</td>
<td>request 11 RBs (1 RBs blocked)</td>
<td>request 9 RBs (1 RBs free)</td>
</tr>
<tr>
<td>MNO-2</td>
<td>request 9 RBs (1 RBs free)</td>
<td>request 8 RBs (2 RBs free)</td>
<td>request 12 RBs (2 RBs blocked)</td>
</tr>
</tbody>
</table>

Figure 3.11: Two MNOs with 10 RBs each, and TTI for 3 frames scenario.
should receive at least the LBS, which it would otherwise receive in the case of a non-RB sharing scenario. For example, when one of the MNO has a high traffic load, the other MNO bearers still receive LBS that is the same as in the case of a non-RB sharing scenario.

MNOs can share an eNB, allowing MNOs to customize their scheduling, taking into consideration the importance of satisfying the user SLA per MNO, minimizing energy consumed per user, and applying scheduling policy per users and traffic classes. This resources sharing can help deliver various benefits as:

1. Sharing the high-cost mobile network hardware deployment among multiple MNOs reduces the operating expenditure (OPEX) and capital expenditure (CAPEX), as sharing can save as much as 60 billion over a period of 5 years worldwide [11, 32, 59].

2. Networks sharing of one common infrastructure between multiple MNOs would reduce the network physical components (for example antenna masts) which minimizes their environmental impact leading to potential energy savings.

3. Facilitating a new business models in the wireless market (For example, operators without LTE licenses, spectrum, or network resources would be able to provide LTE services by renting parts of the LTE radio resources form the MNOs).

4. Efficient utilization of the existing radio resources.

5. Introducing the multi-MNOs multiplexing gain that would support higher peak rates owing to radio resource aggregation.

6. Facilitates a new business models, and contributes to better resource utilization.

The scheduling algorithm that aims to maximize the total aggregate utility. The scheduler objective is to optimally allocate RBs to each bearer such that the total bearer utilities are maximized. It is considered that, each bearer is associated with a utility function. Also, I assume all utility functions are linear. Let the utility function of bearer \( m \) be \( U_m \). If bearer \( m \) is assigned the RB \( r \), the bearer utility is \( U_m(r) \). At every TTI, the optimization problem can be expressed as:

\[
\max \sum_{r=1}^{R} \left( \sum_{m=1}^{M} U_m(r) \beta_{m,r} \right) \quad (3.10)
\]

subject to:

\[
\sum_{m=1}^{M} \beta_{m,r} \leq 1, \forall \ r \in R \quad (3.11)
\]
where, $\beta_{(m,r)}$ is a binary number indicator that is equal to 1 if the RB $r$ is assigned to bearer $m$, and 0 otherwise.

A framework of sharing resources of network consolidation in the context is proposed, where MNOs have different spectrum band licenses. MNOs combine their spectrum bands on a single physical eNB. The optimization problem in Equation (3.10) can be modified to be:

$$\max \sum_{r=1}^{R} \left( \sum_{m=1}^{M} U'_m(r) \beta_{m,r} \right)$$  \hspace{1cm} (3.12)

subject to:

$$\sum_{m=1}^{M} \beta_{m,r} \leq 1, \ \forall \ r \in R$$  \hspace{1cm} (3.13)

where, $U'_m = w \times U_m$ if $m \in M_1$ and $U'_m = U_m$ if $m \in M_2$. $w$ is defined to be the weight of sharing in resources such that $0 \leq w \leq 1$, for example, if $w = 0$, this implies that there is no sharing in resources between MNO-1, and -2, while if $w = 1$, this makes 100% sharing in MNOs resources.

$$s(r,m) = \arg \max_{i \in M} U'^i_i,$$  \hspace{1cm} (3.14)

where, $s(r,m)$ represents RB $r$ to be assigned to bearer $m$, that is much higher than non-sharing by factor $w$.

### 3.6 Simulation Results

Detailed simulation studies are conducted in order to test the performance of the proposed protocol. The scheme is tested using a discrete event simulator developed in MATLAB [65], and the key simulation parameters are summarized in Table I. To emulate the self-similar characteristics of AF and BE traffic, self-similar traffic models for all UEs are generated.

Furthermore, in order to overcome the extreme uncertainty of self-similar traces and simulate conclusive results, the outputs of multiple iterative simulation runs are averaged for each result. Thus, all results are averaged over $10^4$ Monte-carlotrails of fading channels. Noting
3.6. Simulation Results

Table 3.3: Simulation default Parameters.

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Value</th>
<th>Parameter</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>UEs/MNO-1 (M₁)</td>
<td>2 (UE-1, 2)</td>
<td>UEs/MNO-2 (M₂)</td>
<td>2 (UE-3, 4)</td>
</tr>
<tr>
<td>RBs/MNO-1</td>
<td>10</td>
<td>RBs/MNO-2</td>
<td>10</td>
</tr>
<tr>
<td>MNO-1 scheduler</td>
<td>S.P.</td>
<td>MNO-2 scheduler</td>
<td>LWDF</td>
</tr>
<tr>
<td>Fading</td>
<td>Rayleigh</td>
<td>Simulation time</td>
<td>80 s</td>
</tr>
<tr>
<td>SNRₗ(UE – 1, 3)</td>
<td>10 dB</td>
<td>SNRₗ(UE – 2, 4)</td>
<td>15 dB</td>
</tr>
<tr>
<td>δ</td>
<td>0.1</td>
<td>P</td>
<td>27 dBm</td>
</tr>
<tr>
<td>Channel Estimation</td>
<td>Perfect dB</td>
<td>σ²</td>
<td>1 dB</td>
</tr>
</tbody>
</table>

Figure 3.12: UEs per MNOs are distributed as near and far user from the eNB.

that, these classes are extended from the Application class that provides methods and parameters common to all of them, such as starting/stopping time instants. The simulation default parameters are shown in Table 3.3.

It is considered two users for each MNO, one UE is close to eNB and has average SNR of $SNR_h$ dB, while the other UE is far from the eNB and has average SNR of $SNR_l$ as shown in Figure 3.12. Also, it is considered that each user has only one bearer.

To simplify the simulations, it is also assumed that the total network load is evenly distributed amongst all UEs (the UEs are equally weighted). Figure 3.13 compares the throughput between the S.P. and LWDF schedulers, that shows throughput improvement in LWDF over S.P. scheduler; while Figure 3.14 shows the average packet delay for different traffic classes among the 2 MNOs. The delay of the AF class is noticed to be higher than BE within the first active 15 UEs, that is because of the higher arrival rate, but over 15 UEs, it start to proceed as the AF has an over priority on the BE traffic class. Moreover, EF traffic in MNO-2 cannot
support over 18 UEs as it will not satisfy its QoS, which could be handled by MNO-1 that can go over 60 UEs as it has strict priority to EF traffic class.

However, users with the same channel quality are treated differently. This is because the MNOs apply different scheduling policies. As a result, the proposed scheme allows MNOs to run custom bearer scheduler on the same eNB. To reiterate, user-1 and user-3 have the same low channel quality ($SNR_l$), and user-2 and user-4 have the same high channel quality ($SNR_h$). In Figure 3.15, the average packet delay per different traffic classes for MNOs -1, and -2 in case of non-sharing scheme.

### 3.6.1 Case Study and Results Analysis

It is considered that according to the SLA there is only fair weight of sharing between the MNOs. For example, if $w=0.7$, this means that each MNO is sharing 70 of its resources with the other MNO. Then, in the considered example, each MNO is allowing 7 from its 10 RBs,
3.6. Simulation Results

Figure 3.14: The average packet delay for different traffic classes with the S.P. and LWDF schedulers.

Figure 3.15: The average packet delay per different traffic classes for MNOs -1, and -2 with non-sharing scenario.
and then each MNO can use 17 RBs among its two users (depending on how much RBs are free in the MNO).

Figure 3.16 shows another assumption, considering the SLA between two MNOs is with different weight of sharing resources per each. That might happen among MNO with varied budgets sharing the same eNB. The considered model assumes that the weight of sharing resources for MNO-1 $w_1 = 0.2$, that means that $2/10$ from the RB1 (10 RBs) are allowed to be shared for MNO-2; similarly, the weight of sharing resources for MNO-2 $w_2 = 0.4$, that means that $4/10$ from the RB2 (10 RBs) are allowed to be shared for MNO-1; hereby, MNO-1 can use 14 RBs, and MNO-2 can use 12 RBs among there users.

Figure 3.17 shows another example for the previous concept; where the weight of sharing resources for MNO-1 $w_1 = 0.8$, indicate that $8/10$ from RB1 (10 RBs) are allowed to be shared for MNO-2; similarly, the weight of sharing resources for MNO-2 $w_2 = 0.3$, indicate that $3/10$ from RB2 (10 RBs) are allowed to be shared for MNO-1; hereby, MNO-1 can use 13 RBs, and MNO-2 can use 18 RBs among there users. Both Figures show how the delay has been improved with the sharing scheme, noting that mostly EF class has 1ms delay which is the minimum delay could be satisfied.

Figures 3.18, and 3.19 show the queue length in the buffer before and after sharing the radio RBs, and how the delay has been improved with the sharing scheme. Hereby; I simulate the results showing how the parameter $w$ affects the sharing between the MNOs. As $w$ increases, the scheduler allocates more resource in favour of MNO-1’s users which results in the averaged data rate. The considered model is as described before in Table 3.4, and 3.5; But here the sharing is varied by 10 each time of simulation, starting from 0 sharing till it reach 100.

Figures 3.20, and 3.21 present the average AF, and BE packets’ delay variation with respect to different weight definitions, that clarify the effect of the weight of sharing on transmission time enhancement. The comparison can be seen between SPs (as they are performing with different schedulers’ algorithm) or between UEs (within the same SP).
3.6. Simulation Results

Figure 3.16: Average packet delay with sharing scenario \((w_1 = 0.2, \text{RB1} = 14, \text{and } w_2 = 0.4, \text{RB2} = 12)\).

Figure 3.17: Average packet delay with sharing scenario \((w_1 = 0.8, \text{RB1} = 13, \text{and } w_2 = 0.3, \text{RB2} = 18)\).
Figure 3.18: Queue length in the UE-1’s buffer before sharing radio RBs.

Figure 3.19: Queue length in the UE-1’s buffer after sharing radio RBs.
3.6. Simulation Results

Figure 3.20: Average AF packet delay with respect to variation of weight of sharing.

Figure 3.21: Average BE packet delay with respect to variation of weight of sharing.
Table 3.4: Groups’ map.

<table>
<thead>
<tr>
<th>Group</th>
<th># Users</th>
<th>MNO</th>
<th>Average SNR</th>
</tr>
</thead>
<tbody>
<tr>
<td>Group-1</td>
<td>10</td>
<td>MNO-1</td>
<td>$SNR_i$</td>
</tr>
<tr>
<td>Group-2</td>
<td>10</td>
<td>MNO-1</td>
<td>$SNR_h$</td>
</tr>
<tr>
<td>Group-3</td>
<td>10</td>
<td>MNO-2</td>
<td>$SNR_i$</td>
</tr>
<tr>
<td>Group-4</td>
<td>10</td>
<td>MNO-2</td>
<td>$SNR_h$</td>
</tr>
</tbody>
</table>

### 3.6.2 Larger Scale Scenario

As an extension for the previous results, the sharing approach performance for a larger scale scenario is presented here, where each MNO has 20 users grouped into four groups as seen in Table 3.4. The same simulation parameters are chosen as in the previous section.

The result for the large scale scenario is similar to that for the small scale scenario. Different groups with equal average SNR are treated differently as a result of different customized schedulers for different MNOs. Interestingly, the MNOs have the same number of users, number of RBs, average channel SNRs. Figure 3.22 shows the average packet delay per different traffic classes for MNOs -1, and -2 in case of non-sharing scenario, while Figures 3.23 and 3.24 show the average packet delay per different traffic classes for the sharing scenario with various weights.

### 3.7 Virtualization and Resources Sharing in Two-Tier Cellular Networks

Enhancement of QoSs parameters is a challenging requirement in the Fifth Generation (5G) networks. Delay sensitive applications such as voice traffic, online gaming, and live video are easily affected especially in high data traffic with limited available resources. In this Section, I aim to enhance the delay performance of such applications by utilizing the extra resources available in two-tier cellular network architecture with macro- and micro-cells. Virtualization
3.7. Virtualization and Resources Sharing in Two-Tier Cellular Networks

Figure 3.22: Average packet delay per different traffic classes for MNOs -1, and -2.

Figure 3.23: Average packet delay with sharing scenario ($w_1 = 0.2$, and $w_2 = 0.4$).
3.7.1 Recent Relevant Research Work

A solution to meet the increase mobile data demand is the deployment of two-tier networks. Such networks comprise of a regular cellular network overlaid with shorter range hotspots such as micro-cells and offer an economically efficient solution to increase cellular system capacity [66].

Moreover, two-tier networks can also increase spectrum efficiency due to the ability to reuse frequency spectrum assigned to macro-cells using a universal frequency reuse fashion [67]. However, cross-tier interference needs to be maintained below a specific threshold to ensure QoS parameters are satisfied in both tiers. This can be overcome by employing different...
frequency spectrum in the tiers and using 2 radio frequency (RF) antennas in UEs.

Several works in recent literature tackled the issue of resource allocation in two-tier networks [66, 67, 68, 69, 70, 71]. Chandrasekhar et al. presented an optimal decentralized spectrum allocation policy for two-tier networks that employ OFDMA subject to a sensible QoS requirement in [66]. Also in [68], Li et al. proposed an efficient resource allocation scheme that includes the macro eNBs adopting soft frequency reuse strategy to mitigate cross-tier interference while guaranteeing a minimum data rate for UEs of both networks.

On the other hand, Abdelnasser et al. suggest a hierarchical interference management scheme based on joint clustering and resource allocation for femtocells in [67]. They formulate the problem as a mixed integer non-linear problem (MINLP) that is solved by dividing it into two sub-problems. Furthermore, Chen et al. study the resource allocation problem in two-tier networks in the DL scenario [71]. The problem is formulated as an MINLP that aims to maximize the capacity of the clustered femtocell network subject to delay constraints of flows with different priorities. The problem is solved by applying stochastic network calculus to transform the delay constraints into alternative minimum capacity requirements [71].

A game-based approach for cell selection and resource allocation in two-tier networks is presented by Gao et al. in [69] in which an inter-cell game is performed to optimally choose the cell which an intra-cell game is performed to allocate resources. Marshoud et al. propose a genetic algorithm to perform joint power and resource allocation in [70]. The proposed algorithm maximizes the overall system throughput and determines the appropriate serving base station as well as the power and bandwidth allocated to each user.

### 3.7.2 System Model

Consider a DL scenario, wherein, a two-tier cellular network is deployed as shown in Figure 3.25. Denote the macro-cell SP by SP$_M$ and the micro-cell SP by SP$_m$. Each SP is assumed to serve active UEs, where UE$_M$ refers to UEs in SP$_M$, and UE$_m$ refers to UEs in SP$_m$. Both SPs’ eNBs employ different scheduling policies.
Each SP has access to a number of channels (available RBs). Denote $K_M$ to be the total number of available RBs in SP$_M$, and $K_m$ to be the total number of available RBs in SP$_m$. Communications and data exchange between SP$_M$ and SP$_m$ eNBs is assumed using X2 interface, and that the MME and S-GW are unchanged.

**Semi-Soft Allocation Technique**

The message sequence for RBs allocation for UE$_M$ before, during and after cutting SP$_m$ area of coverage is shown in Figure 3.26 The radio resources control (RRC) is considered between UE$_M$ and SP$_M$. The UL/DL between the UE, SP$_M$’s eNB, and the core network, specifically with the S-GW, is also assumed.

The core network (specifically MME) detects the UE location. During the passage of UE$_M$ in the micro-eNB’s footprint, UE$_M$ performs RRC configuration and synchronization with the micro-eNB, while the UL/DL is performed through both macro- and micro-eNBs using different RF transceiver modules due to LTE being an OFDM-based system. When UE$_M$ reaches SP$_m$’s end, the core network (MME) detects the left of UE$_M$ and RRC connection is re-established between UE$_M$ and SP$_M$. 

Figure 3.25: Two-tier cellular network topology.
Figure 3.26: Allocation message sequence between the two-tier cellular networks.
To foster customizable schedulers in the evolution, SPs with different utility functions \((Ut)\) are considered. In what follows, the presented framework is for 2 SPs: \(SP_M\) is applying S.P. scheduling. On the other hand, \(SP_m\) is applying LWDF scheduling, while distributing the allocated RBs among traffic classes’ queues is performed by the UE’s I.S. according to the priority of their highest flow [11].

The total set of RBs is assumed to be fully pooled. Each SP owns a set of RBs \(\{K\}\) with no intersection between the different SPs’ RBs, such that:

\[
K_M \cap K_m = \phi
\]  

In this work, two scenarios are considered: non-sharing and virtualized sharing radio resources schemes. In non-sharing scheme, SPs allocate their available RBs to their active UEs performing their own scheduling policies, while in the virtualized sharing scheme, \(SP_m\) can allocate its available un-allocated RBs \((K_m)\) to UE\(_M\) located in its area of coverage and still connected to \(SP_M\) due to their speed recognition.

**Non-sharing Allocation Scenario**

In this algorithm, each SP performs its scheduling individually. The resource allocation problem can be expressed as:

\[
\max \sum \sum \sum U_{i,j,r}(t) \psi_{j,r}(t)
\]

subject to

\[
\sum \sum \sum \psi_{j,r}(t) = 1, \forall t, k \in K_i
\]

\[
\psi_{j,r}(t) \in \{0, 1\}, \forall j, r, t
\]  

Equation (3.16a) represents the objective function that aims to maximize the overall \(Ut\) function for all UEs, where \(Ut\) and \(\psi\) are the decision variables. \(U_{i,j,r}\) is the utility function of UE\(_j\) assigned by the set of RBs \(k\), and \(\psi_{j,k}\) is a binary indicator used to denote whether the UE\(_j\)
is assigned by the set of RBs $k$ or not. $i$ refers to the SP, where $i = 1$ denotes $\text{SP}_m$, while $i = 2$ denotes $\text{SP}_M$. Equation (3.16b) represents the exclusive allocation constraint [12], that ensures that at a definite time $t$, only this set of RBs $k$ is assigned to UE $j$. Equation (3.16c) shows the bounded values for the binary indicator $\psi_{j,r}$ that is equal 1 if RB $r$ is assigned to UE $j$ and equal 0 otherwise.

**Virtualized Sharing Allocation**

A virtualized sharing scheme is considered and could be achieved by $\text{UE}_M$; wherein, the total RBs $K_{\text{tot}}$ ($K_M$+ un-allocated RBs in $K_m$) set is assumed to be accessible to the $\text{SP}_M$. The resource allocation problem can be expressed as:

$$
\max \sum_{t=1}^{UE_M} \sum_{j=1}^{UE_M} \sum_{r \in k} U_t j,r(t) \psi_{j,r}(t) 
$$

subject to

$$
\sum_{j=1}^{UE_M} \sum_{r \in k} \psi_{j,r}(t) = 1, \forall t, k \in K_{\text{tot}}
$$

$$
\psi_{j,r}(t) \in \{0, 1\}, \forall j, r, t
$$

Similarly, Equation (3.17a) represents the objective function. $\psi_{j,r}$ is a binary indicator used to denote whether the UE$_j$ is assigned the set of RBs $k$ or not. Equation (3.17b) represents the exclusive allocation constraint. While, Equation (3.17c) shows the bounded values for the binary indicator $\psi_{j,r}$.

**3.7.3 Simulation Results**

The scheme is tested using a discrete event simulator developed in MATLAB. The outcomes of multi-repeated simulation runs are averaged for each result. Table 3.5 summarizes the list of simulation parameters and their default values.

All UEs are processing EF traffic with rate 4 Kbit/s, and non-EF (AF, and BE) traffic with
Table 3.5: Simulation Default Parameters and Values.

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>Spectrum allocation (UL, DL)</td>
<td>20 MHz</td>
</tr>
<tr>
<td>Number of subcarriers per RB</td>
<td>12 subcarriers</td>
</tr>
<tr>
<td>Neighboring subcarrier spacing</td>
<td>15 KHz</td>
</tr>
<tr>
<td>RB bandwidth</td>
<td>180 KHz</td>
</tr>
<tr>
<td>Macrocell radius</td>
<td>5 Km</td>
</tr>
<tr>
<td>Microcell radius</td>
<td>1 Km</td>
</tr>
<tr>
<td>UEs/RBs in $SP_M$ (macrocell)</td>
<td>1 UE/1 RB</td>
</tr>
<tr>
<td>UEs/RBs in $SP_m$ (microcell)</td>
<td>2 UEs/3 RBs</td>
</tr>
<tr>
<td>$SP_M$ scheduler</td>
<td>S.P. scheduling algorithm</td>
</tr>
<tr>
<td>$SP_m$ scheduler</td>
<td>LWDF scheduling algorithm</td>
</tr>
<tr>
<td>Channel fading</td>
<td>Rayleigh</td>
</tr>
<tr>
<td>Iteration #</td>
<td>1e4</td>
</tr>
<tr>
<td>$SP_M$ eNB Tx power</td>
<td>46 dBm</td>
</tr>
<tr>
<td>$SP_m$ eNB Tx power</td>
<td>13 dBm</td>
</tr>
<tr>
<td>Fading</td>
<td>Rayleigh</td>
</tr>
<tr>
<td>Coherence time</td>
<td>1 ms</td>
</tr>
<tr>
<td>Simulation time</td>
<td>80 s</td>
</tr>
<tr>
<td>Cells interference</td>
<td>Avoidance</td>
</tr>
</tbody>
</table>

Rate 268 Kbit/s. $UE_M$ is assumed to be moving with a constant speed of 60 Km/hr, and is cutting a distance of 400 m chord in $SP_m$’s footprint. In this scenario, I consider $UE_M$ can be allocated with RBs ($R_m$) if $SP_m$ has free RBs to assign and $UE_M$ is in $SP_m$’s range of coverage.

Figure 3.27 shows the average packet delay (EF and non-EF traffic) for mobile $UE_M$ versus time. The UE’s speed is assumed to be constant over the simulation. The Vir. DS scenario ensures less average delays for EF and non-EF traffic than SS. This is due to UEs having access to a larger number of RBs, and thus they can be allocated better channels.

Noting that, mostly the EF class has 1 ms delay, which is the minimum delay that could be satisfied (mapping time period). As in the sharing resources scheme, the scheduler allocates more resources for the immigrant $UE_M$. Because of the higher arrival rate, the delay of the non-EF classes is noticed to be higher than EF within the entire network. The simulation results show that the sharing virtualized scheme is capable of achieving some improvements with respect to delay when compared to the non-sharing application.
Figure 3.27: The average packets delay (EF and non-EF traffic) for UE\(_M\) before, during, and after passing through the micro-cell footprint.
3.8 Chapter Summary

In this Chapter, the framework model is for sharing resources scenario in LTE systems. An overview for the LTE resources allocation, and a comparison between strict priority and LWDF scheduler algorithms strategies in terms of delay and throughput are discussed. I evaluate the average packets jitter and delays for cases of non-sharing and sharing schemes, aiming to enclose the growing gap between the capacities of backbone networks.

From simulation results, it is clear that RBs sharing scheme is capable to achieve much delay improvement as compared to the non-sharing one, allowing MNOs to customize their efforts, schedulers, and control the sharing of multi-MNO resources between them. Overall, the results confirm that sharing framework yields to notable improvements in average packet delay, without degrading QoS support for EF, AF, and BE services. Nonetheless, the performances of AF and BE services are yet to be further improved and QoS to be better delivered.

In the coming chapters, the problem of optimized UL power allocation with different dynamic traffic models, and full resources sharing is consider. Later on, the HO strategy is investigated for various traffic models in a virtualized scheme of sharing SPs’ radio resources.
Chapter 4

Efficient Power Allocation in Virtualized 3GPP-LTE Systems

In order to accommodate mobile users’ consumed power with the rapid increase of multimedia-rich mobile data, additional network capacities with optimized power allocation scheduling algorithms should be deployed [12, 72]. Motivated by the fundamental requirement of extending the mobile devices’ battery utilization time per charge, this work formulates the optimized power allocation problem in a virtualized scheme considered in the 3GPP-LTE UL systems. The proposed framework efficiently shares the eNB’s dedicated physical radio RBs of SPs having different requirements under dynamic channel conditions. The target is to reduce the total transmission power for all UEs subject to exclusive and contiguous allocation, maximum transmission power, and rate constraints.

Two algorithms are developed. A BIP-based algorithm is used to solve a simplified version of the problem. A heuristic algorithm is also presented that approaches the BIP-based algorithm’s performance. Simulation results show that the proposed framework offers a noticeable transmission power reduction in the virtualized scenario as compared to the non-sharing one.
4.1 Introduction

Over the years, the growth in data usage per UE has driven an unprecedented increase in UE’s power consumption [73]. Moreover, with more demanding user-driven applications, the LTE is expected to reach high data rates, low latency, and packet optimized radio access technology [74, 75, 76]. All of these features directly affect the UE’s battery and its lifespan per charge [30].

Most of the previous work [11, 32, 37, 59, 77, 78, 79] focuses on developing scheduling algorithms for the LTE DL transmission. This aims to maximize the total utility of the system in terms of data rate and delay without considering the UE’s UL consumed power. In this work, the focus is on finding an optimal solution [80, 81, 82] for resource allocation among users who subscribe to different SPs but are located at the same site (eNB) in UL as shown in Figure 4.1.

The power control entity specifies the UL transmission power for each UE. In order to provide an end-to-end QoS support [83, 84], LTE provides QoS based on each flow’s requirements. These flows are organized into logical traffic pipes named bearer services. A set of QoS
attributes are associated with each bearer (depending on the type of traffic), as shown in Table 4.1.

LTE classifies flows into the QoS class identifier (QCI) [85] which is a scalar number that defines the management of bearer packet transmission, GBR flows for real-time applications and non-GBR flows that are established for non-real-time applications (e.g., buffered video streaming) [25, 86], packet delay budget (PDB) which is the maximum allowable packet delay, and packet loss error rate (PLER) which is the maximum tolerable number of corrupted or lost packets.

The modulation method and multiple access scheme that LTE currently specifies have some disadvantages with regards to power efficiency.

The modulation schemes used in LTE are QPSK, 16QAM and 64QAM [11, 30, 59, 86]. The phase discontinuity in these methods gives rise to out-of-band radiation, which leads to poor power efficiency and higher bandwidth requirement.

LTE has adopted the OFDM based radio interface due to its higher spectral efficiency and resilience against multi-path delay spread (frequency selectivity). In UL transmission, SC-FDMA has been adopted as a transmission technology by the 3GPP community (which enables frequency selective scheduling gains and has the benefit of reduced PAPR) rather than the OFDMA technology used for DL transmission [51].

SC-FDMA's low PAPR allows the power amplifier at the transmitter to operate close to the

<table>
<thead>
<tr>
<th>QCI</th>
<th>Bearer Type</th>
<th>PDB</th>
<th>PLER</th>
<th>Application</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>GBR</td>
<td>100 ms</td>
<td>$10^{-2}$</td>
<td>VoIP</td>
</tr>
<tr>
<td>2</td>
<td>GBR</td>
<td>150 ms</td>
<td>$10^{-3}$</td>
<td>Video call</td>
</tr>
<tr>
<td>3</td>
<td>GBR</td>
<td>50 ms</td>
<td>$10^{-3}$</td>
<td>Real time gaming</td>
</tr>
<tr>
<td>4</td>
<td>GBR</td>
<td>300 ms</td>
<td>$10^{-6}$</td>
<td>Buffered streaming</td>
</tr>
<tr>
<td>5</td>
<td>non-GBR</td>
<td>100 ms</td>
<td>$10^{-6}$</td>
<td>IMS signaling</td>
</tr>
<tr>
<td>6</td>
<td>non-GBR</td>
<td>300 ms</td>
<td>$10^{-6}$</td>
<td>Video (buffered streaming)</td>
</tr>
<tr>
<td>7</td>
<td>non-GBR</td>
<td>100 ms</td>
<td>$10^{-3}$</td>
<td>Voice, Video (live streaming)</td>
</tr>
<tr>
<td>8</td>
<td>non-GBR</td>
<td>300 ms</td>
<td>$10^{-6}$</td>
<td>Voice, Video (buffered streaming)</td>
</tr>
</tbody>
</table>
saturation point which improves its efficiency. The physical properties of SC-FDMA require that the physical RBs allocated to a single user to be contiguous in frequency.

Power control is a crucial radio network function in cellular systems [30, 77]. It refers to setting output power levels of transmitters, base stations in DL and mobile stations in UL, with an objective to improve system capacity, coverage and user quality, and to reduce power consumption.

In UL, power consumption often acts as a limiting factor to the functionality offered by the mobile devices’ batteries. However, batteries’ technology is not progressing at the same rate as mobile demand growth and devices’ miniaturization. Therefore, there is a primary need to minimize power consumption at UEs as poor power efficiency that leads to shorter battery life.

Also, UL power control has to adapt the radio channel conditions, including path loss, shadowing and fast fading changes. Furthermore, power control has to limit the interference effects from other users within the cell and from neighboring cells.

The orthogonal LTE UL allows multiplexing of terminals with different received UL power within the same cell. However, the high speed data links offered by LTE systems increase the power consumption of the UEs. Thus, it is imperative to develop energy-efficient scheduling algorithms that prolong the UE’s battery life per charge.

4.2 Recent Relevant Research Work

In order to assess the current state of the art, the recent approaches to the above energy-optimal problem are reviewed. In general, there are few works found in the literature that attempt to address the above problem directly.

There are however a number of works that focus on addressing subsets of the entire problem. I review these and relevant research here.

Most of the work on power and channel allocation for multi-user multi-channel systems typically focused on OFDMA [77, 87]. In these works, a user can be assigned multiple channels
from any of the available channels by using water filling-based power allocation algorithms. Goodman in [88, 89], proposed the greedy algorithms for the proportional fair scheduling of SC-FDMA systems using utility functions, which is a similar approach to the one proposed in [87] by Song et al. for OFDMA proportional fair scheduling. Unfortunately, the proposed algorithms can not guarantee optimality, and does not consider the channel contiguity restriction.

Wong et al. in [90] investigated the maximization of the total user-weighted system capacity that depends on maximum allowable transmission and peak power constraint. They used BIP to solve the scheduling problem, disregarding the QoS requirements and the dynamic traffic behavior of UEs.

Dechene and Shami considered power-efficient resource allocation subject to rate and synchronous hybrid automatic repeat request (HARQ) constraints in [91, 92]. The objective was to minimize the weighted sum of the transmission power. Also, the authors assumed fixed data rate to be scheduled every transmission time interval (TTI) without considering maximum power limit constraint. However, practical LTE UL systems limit the maximum transmission power to 23 dBm by Toufik in [21].

In general, MCSs are less power-efficient at higher transmission rates [12]. Thus, transmitting at lower rates with less power can reduce the energy required to transmit the data. However, lower data rates compromise the QoS requirements [93, 94] because that would require to split the data and transmit at lower rates over more subframes to reduce the total transmission power.

The main contribution in this chapter is a novel dynamic scheduling resource sharing algorithm that aims to save power for users in the access network. The objective is to allocate the pooled radio resources to UEs based on the SPs’ requirements in high time-frequency resolution that minimizes the total power consumption of the UEs. The framework scheme shares SPs’ resources while maintaining different service requirements. The research below offers detailed simulations to study the performance of the considered framework and validate its effectiveness. A BIP-based solution is compared with a heuristic algorithm in terms of transmis-
Table 4.2: Frequently Used Notations

<table>
<thead>
<tr>
<th>Notation</th>
<th>Definition</th>
</tr>
</thead>
<tbody>
<tr>
<td>$C_m$</td>
<td>All possible RBs allocation for UE $m$</td>
</tr>
<tr>
<td>$c_{lm}$</td>
<td>Column $c_l$ with set of RBs allocated for UE $m_n$</td>
</tr>
<tr>
<td>$F_t$</td>
<td>Finite time length of TTI s</td>
</tr>
<tr>
<td>$k$</td>
<td>RB</td>
</tr>
<tr>
<td>$K_n$</td>
<td>Total number of RBs in SP $n$</td>
</tr>
<tr>
<td>$K_{tot}$</td>
<td>Total number of RBs in all SPs</td>
</tr>
<tr>
<td>$m$</td>
<td>UE</td>
</tr>
<tr>
<td>$m_n$</td>
<td>UE $m$ in SP $n$</td>
</tr>
<tr>
<td>$M_n$</td>
<td>Total number of UEs in SP $n$</td>
</tr>
<tr>
<td>$M_{tot}$</td>
<td>Total number of UEs in all SPs</td>
</tr>
<tr>
<td>$n$</td>
<td>SP</td>
</tr>
<tr>
<td>$N$</td>
<td>Total number of SPs</td>
</tr>
<tr>
<td>$s$</td>
<td>MCS</td>
</tr>
<tr>
<td>$s_{m}$</td>
<td>MCS selected for UE $m_n$</td>
</tr>
<tr>
<td>$S$</td>
<td>Total number of MCSs</td>
</tr>
<tr>
<td>$t$</td>
<td>Definite TTI</td>
</tr>
<tr>
<td>$T_{GBR_n}$</td>
<td>GBR specified for any UE in SP $n$</td>
</tr>
<tr>
<td>$T_{m_n}$</td>
<td>TB of UE $m$ in SP $n$</td>
</tr>
</tbody>
</table>

...ision power and complexity. Simulation results show that the BIP-based algorithm considerably reduces the UE’s average transmission power without degrading QoS performance and that the heuristic one achieves comparable performance.

### 4.3 System Model

Consider a single cell employing SC-FDMA for a multiuser wireless communications, wherein, $N$ SPs share an eNB. The set of SPs is denoted as $\mathcal{N} = \{1, 2, \ldots, N\}$. Each SP $n$ is assumed to serve $M_n$ active UEs, where $n \in \mathcal{N}$ and the set $\mathcal{M}_n = \{1, 2, \ldots, M_n\}$. Denote UE $m_n$ to be the UE $m$ belonging to SP $n$. Each SP has access to a number of channels (available RBs), adjacent and located at different frequencies. Denote $K_n$ to be the total number of available RBs in SP $n$. It is helpful to define some frequently used notations as shown in Table 4.2.
4.3.1 Exclusive and Contiguous Allocation

The main idea of the exclusive and contiguous constraints can be described in the following example. Assume SP \( n \) with \( K_n = 4 \) RBs and \( M_n = 2 \) UEs. For a particular UE, there are a number of feasible channel allocations available. Here, I denote to a channel allocated to a UE by 1, and 0 otherwise, and form the channel allocation pattern matrix \( C_{m_n} \) for UE \( m_n \). The rows of this matrix represent the channel index (RB), and the columns reflect the feasible channel allocation set as follows:

\[
C_{m_n} = \begin{bmatrix}
1 & 0 & 0 & 0 & 1 & 0 & 0 & 1 & 0 & 1 \\
0 & 1 & 0 & 0 & 1 & 1 & 0 & 1 & 1 & 1 \\
0 & 0 & 1 & 0 & 0 & 1 & 1 & 1 & 1 & 1 \\
0 & 0 & 0 & 1 & 0 & 0 & 1 & 0 & 1 & 1
\end{bmatrix}, \forall m_n
\]

When multiple RBs are assigned to a user (columns 5 to 10), these RBs should be adjacent to each other. Therefore, the column \([1 \ 0 \ 1 \ 0]^T\) and its similar non-contiguous allocations are not considered.

To better understand the exclusivity constraint, assume that UE\(_{1_n}\) is assigned the best feasible set of RBs found in column 6 (RBs #2 and #3). Then UE\(_{2_n}\) in turn has only 2 RBs (RB #1 or #4) to be allocated as follows:

\[
C_{2_n} = \begin{bmatrix}
1 & 0 \\
0 & 0 \\
0 & 0 \\
0 & 1
\end{bmatrix}.
\]

Thus, the allocation matrix can be represented as \( C_{m_n} = [c_1 \ c_2 \ ... \ c_{L_n}] \) where the total number of columns in \( C_{m_n} \) is

\[
L_n = \frac{K_n}{2}(K_n + 1)
\]

Define \( c_i \) to be the column containing the selected set of RBs allocated to UE\(_{m_n}\), while \( ||c_i|| \) is the hamming weight that represents the number of RBs in \( c_i \).
4.3.2 Transmission Block Size

The overall TB size that can be transmitted per subframe over $\|c_t\|$ RBs for UE$_{m_n}$ is given by:

$$T_{m_n,c_t,s}(t) = \lfloor 132 \times \zeta_s(t) \times \|c_t\| \rfloor,$$

(4.2)

and thus, the number of RBs can be represented as:

$$\|c_t\| = \frac{T_{m_n,c_t,s} + \epsilon}{132 \zeta_s(t)},$$

(4.3)

where $0 \leq \epsilon < 1$. The received SNR determines the MCS that should be used to deliver TB with a 10% Block Error Rate. The MCS selection scheme is enacted using a lookup table that maps the received SNR to the MCSs [11, 51, 59, 86].

From Figure 3.3, it is clear that transmitting TB over multiple lower level MCSs can be equivalent to transmitting at one higher MCS. Then, I can conclude that the UL transmission power for any UE can be reduced by:

1. increasing the effective SNR by assigning RBs that have less fading [95] (that can not be guaranteed for all TTIs)

2. and/or transmitting TB over longer period of TTIs (more subframes) (but that might affect the GBR traffic and QoS).

4.3.3 Transmission Power Calculation

In SC-FDMA, for adapted continuous-rate with low bit error rate during the $t^{th}$ subframe, an approximation of the instantaneous received effective SNR for an allocated set of RBs $c_t$ for UE $m_n$ over MCS $s$ in TTI $t$ is given by:

$$\gamma_{m_n,c_t,s}(t) = \frac{1}{\|c_t\|} \sum_{j \in c_t} \frac{\sigma_{\text{sig}}^2 |h_{m_n,j}(t)|^2 \xi_{m_n}(t) P_{m_n,j,s}(t)}{\sigma_n^2}$$

(4.4)
where, $|h_{mn,j}(t)|$ is the channel frequency response of RB $j$ at TTI $t$ seen by UE $m_n$. The shadowing (long term fading) parameter $\xi_{mn}(t) = D/d_{mn}(t)^\alpha$ [96], where $D$ is a normalization constant which accounts for system losses, $d_{mn}(t)$ is the distance between UE $m_n$ and the eNB at TTI $t$, and $\alpha$ is the path loss exponent (usually between 2 for open space and 5 for highly built up areas). $\sigma^2_{sig}$ and $\sigma^2_n$ are the signal and noise variance respectively. Consider $\Omega_{mn,j}(t)$ to denote $|h_{mn,j}(t)|^2 \xi_{mn}(t)$, and $\sigma^2_{sig} = 1$, then I have

$$\gamma_{mn,cl,s}(t) = \frac{1}{||c_l||} \sum_{j \in c_l} \Omega_{mn,j}(t) P_{mn,j,s}(t)$$ (4.5)

To reduce signal overhead, LTE specifies that one power level should be transmitted over the assigned RBs for the same UE [97]. Then it can assumed that $P_{mn,1} = P_{mn,2} = ... = P_{mn,x} = ... = P_{mn,||c_l||}$. Thus, the total transmission power for the UE $m_n,c_l$ is given by:

$$\sum_{j \in c_l} P_{mn,j}(t) = ||c_l|| \times P_{mn,x}(t), \forall x \in c_l$$ (4.6)

By substituting in equations (4.4) and (4.5), the UE transmission power can be represented as:

$$\sum_{j \in c_l} P_{mn,j,s}(t) = \left( \frac{T_{mn,cl,s}(t) + \epsilon}{132 \xi_s(t)} \right)^2 \cdot \gamma_{mn,cl,s}(t) \left( \sum_{j \in c_l} \Omega_{mn,j}(t) \right)^{-1}$$ (4.7)

### 4.4 Problem Formulation

The resource allocation in LTE UL requires the following constraints to maintain the physical layer restrictions and the QoS requirements:

1. Power constraint: the LTE standard specifies $P_{max}$ (23 dBm) [30] to be the maximum threshold transmission power that a UE can not exceed.

2. Exclusive allocation constraint: a single RB can only be allocated to one UE at most
within the same TTI to avoid overlapping allocation of available RBs.

3. Contiguous allocation constraint: RBs should be strictly contiguous when multiple RBs are assigned to a single UE.

4. Rate constraint: a minimum GBR must be maintained for all UEs according to each SP’s service requirements.

In this work, two scenarios are considered: static sharing (SS) and dynamic sharing (DS) within the efficient power allocation scheduling. In SS, SPs are sharing only the common physical infra-structure eNB without sharing the channels among them; while in DS, the sharing agreement includes the SPs’ spectrum. Thus, SPs share their physical RBs (noting that, I consider SPs of adjacent BW spectrum).

### 4.4.1 Static Sharing Allocation Problem

The radio access network connects multiple SPs and manages the resources allocation between them according to their SLA. Each SP owns a set of RBs $K_n$ with no intersection between the different SPs’ RBs, such that:

$$K_n \cap K_v = \phi, \ \forall \ n, v \in N$$  \hspace{1cm} (4.8)

The SC-FDMA resource allocation problem involves determining the RB and power allocation that maximizes the total system-utility and minimize the UEs’ transmission power, subject to each user’s total power constraint.

Assuming an admission control scheme is applied, the resource allocation problem considering SS scenario between SPs can be expressed as:

$$\min_{t=1}^{F_t} \sum_{n=1}^{N} \sum_{m_n=1}^{M_n} \sum_{j \in \xi_t} \sum_{s=1}^{S} P_{m_n,j,s}(t) \psi_{m_n,j,s}(t)$$  \hspace{1cm} (4.9a)
subject to

\[ \sum_{j \in c} P_{m_n,j,s}(t) \leq 23 \text{ dBm}, \ \forall \ m_n, \ s, \ t \quad (4.9b) \]

\[ \frac{1}{F_t} \sum_{i=1}^{F_t} T_{m_n,c_i,s}(t) \geq T_{GBR_n}, \ \forall \ m_n \quad (4.9c) \]

\[ \sum_{n=1}^{N} \sum_{m_n=1}^{M_n} \sum_{s=1}^{S} \psi_{m_n,j,s}(t) = 1, \ \forall \ t \quad (4.9d) \]

\[ \bigcap_{n=1}^{N} \bigcap_{m_n=1}^{M_n} c_i \psi_{m_n,j,s}(t) = \phi, \ \forall \ j, \ s, \ t \quad (4.9e) \]

\[ \psi_{m_n,j,s}(t) \in \{0, 1\}, \ \forall \ m_n, \ j, \ s, \ t \quad (4.9f) \]

Equation (4.9a) represents the objective function that aims to minimize the overall transmission power for all UEs, where \( P \) and \( \psi \) are the decision variables. \( P_{m_n,c_i,s} \) is the UL transmission power of UE \( m_n \) assigned by the set of RBs \( c_i \) over MCS \( s \), and \( \psi_{m_n,c_i,s} \) is a binary indicator used to denote whether the UE \( m_n \) is assigned by the set of RBs \( c_i \) over MCS \( s \) or not.

Equation (4.9b) represents the power constraint as each UE’s power can not exceed \( P_{\text{max}} \). \( T_{m_n,c_i,s} \) in equation (4.9c) is the TB of UE \( m_n \) that assures the rate constraint is satisfied over the finite length \( F_t \) of 10 TTIs (10 ms frame). Note that UE \( m_n \) has to transmit \( T_{m_n} \) bits (target GBR to satisfy the rate constraint). Equation (4.9d) ensures that a UE is allocated only one RB allocation map and uses one MCS.

Equation (4.9e) represents the exclusivity and contiguous allocation constraints. The exclusivity constraint ensures that at most one UE can occupy a given RB during any subframe [77, 97], while the contiguity constraint ensures that RBs for a single transmission are allocated contiguously in frequency for each UE.
4.4.2 Dynamic Sharing Allocation Problem

Assuming an admission control scheme is applied beforehand, the resource allocation problem considering DS scenario between SPs can be expressed as:

\[
\min_{t=1}^{F_t} \sum_{m=1}^{M_{tot}} \sum_{j \in c_l} \sum_{s=1}^{S} P_{m,j,s}(t) \psi_{m,j,s}(t) \tag{4.10a}
\]

subject to

\[
\sum_{j \in c_l} P_{m,j,s}(t) \leq 23 \text{ dBm}, \forall m, s, t \tag{4.10b}
\]

\[
\frac{1}{F_t} \sum_{t=1}^{F_t} T_{m,c_l,s}(t) \geq T_{GBR_m}, \forall m \tag{4.10c}
\]

\[
\sum_{m=1}^{M_{tot}} \sum_{j \in c_l} \sum_{s=1}^{S} \psi_{m,j,s}(t) = 1, \forall t \tag{4.10d}
\]

\[
\bigcap_{m=1}^{M_{tot}} c_l \psi_{m,j,s}(t) = \phi, \forall j, s, t \tag{4.10e}
\]

\[
\psi_{m,j,s}(t) \in \{0, 1\}, \forall m, j, s, t \tag{4.10f}
\]

Similar to equation (4.9a), equation (4.10a) represents the objective function that aims to minimize the overall transmission power for all UEs, where \( P \) and \( \psi \) are the decision variables. \( P_{m,c_l,s} \) is the UL transmission power of UE \( m \) assigned the set of RBs \( c_l \) using MCS \( s \), and \( \psi_{m,c_l,s} \) is a binary indicator used to denote whether the UE \( m \) is assigned the set of RBs \( c_l \) using MCS \( s \) or not.

Equation (4.10b) restricts the transmission power of each UE to a maximum of 23 dBm. Similarly, \( T_{m,c_l,s} \) in equation (4.11c) is the TB of UE \( m \) that guarantees that the rate constraint is satisfied over the finite length of TTIs time. Note that UE \( m \) has to transmit \( T_m \) bits (target GBR to satisfy the rate constraint).

As discussed previously in equations (4.9d) and (4.9e), equation (4.10d) ensures that a UE is allocated only one RB allocation map and uses one MCS while equation (4.10e) represents
the exclusivity and contiguous allocation constraints.

Both problems presented above can not be solved to optimality because they are both dependent on future values that are not available to the eNB. Therefore, the problems need to be simplified in order to solve them.

4.5 Scheduling Framework

Although, it is much desirable to work with the optimal solution for its higher performance, but the computational complexity price in solving encourage us to look for much less complexity algorithms.

To simplify the problems presented in the previous section, a single time slot is considered. Thus, the time index is dropped in both scenarios. In our work, two schemes are considered to solve the problems, a linear BIP based algorithm and a heuristic scheduling algorithm.

4.5.1 The BIP-based Resource Allocation Algorithm

Note that equation (4.9a) forms a combinatorial optimization problem. In order to show how the search space is huge, I first assume that \( l \) users are to share the \( K \) sub-channels. Due to the sub-channel contiguity constraint, it requires the \( K \) sub-channels to be partitioned into exactly \( l \) sets, wherein each set has \( k_i \) adjacent sub-channels, such that \( K = k_1 + \ldots + k_l \). To express how complex this is, I assume that the considered case of \( K = 24 \) subchannels and \( M = 10 \) users, this would require searching through \( 5.26 \times 10^{12} \) possible sub-channel allocations.

This approach indicates reformulating the problem as a pure BIP called the set partitioning problem. A built-in MATLAB function named \textit{bintprog} that performs branch-and-bound search procedure with a linear programming (LP) relaxation per iteration. This problem has the following general form:

\[
\min_x c^T x
\]  

(4.11)
subject to
\[ Ax \leq b, \quad A_{eq} x = b_{eq} \] (4.12)

where \( c \) represent the cost \( P_{m_n,j,s} \), and \( x \) is the binary decision variable that minimize the objective function in equation (4.10a) (represented by \( \psi_{m_n,j,s} \)). Constraints in equation (4.12) are maintained by linear equality and inequality constrains. Wherein, \( A \) and \( A_{eq} \) are matrices containing the coefficients of the inequality and equality constraints, while \( b \) and \( b_{eq} \) are vectors that fulfill these constrains.

The matrices \( A \) and \( A_{eq} \) are defined as follows. Define the matrix \( A_{m_n} \) to be the matrix containing all possible contiguous allocations for all the \( S \) different MCSs. Thus, it can be expressed as:

\[
A_{m_n} = [C_{m_n}, C_{m_n}, \ldots, C_{m_n}]_S
\] (4.13)

To ensure that the GBR constraint and the maximum power constraint are respected, \( A^{th}_{m_n} \) is defined to be the matrix that has all the columns in \( A_{m_n} \) that achieve a transmission power less than \( P_{max} \) and a TB size greater than \( T_{GBR_n} \). Therefore matrix \( A \) is defined as:

\[
A = [A^{th}_{1_n}, A^{th}_{2_n}, \ldots, A^{th}_{M_n}]
\] (4.14)

The vector \( b = 1_{K_n} \) (vector of all ones) is the upper bound of the inequality constraint. The equality matrix \( A_{eq} \) is defined to be:

\[
A_{eq} = \begin{bmatrix}
1^T_{|A^{th}_{1_n}|} & \ldots & 0^T_{|A^{th}_{M_n}|} \\
\vdots & \ddots & \vdots \\
0^T_{|A^{th}_{1_n}|} & \ldots & 1^T_{|A^{th}_{M_n}|}
\end{bmatrix}
\] (4.15)

where \( |A^{th}_{m_n}| \) is the number of columns in \( A^{th}_{m_n} \) (number of potential allocation choices for UE\( m_n \)).

\( 1^T_x \) is a row vector of length \( x \) of ones while \( 0^T_x \) is a row vector of length \( x \) of zeros. The vector \( b_{eq} = 1_{M_n} \) guarantees that only one of the possible allocations is assigned for UE\( m_n \).
BIP Complexity

Exploring the wide array of available BIP-based algorithms and evaluating their applicability to our problem instance is beyond the scope of this paper. However, it is an interesting area for future research [90]. For the BIP-based algorithm, the worst case scenario is when all the columns of $C_{mn}$ achieve a power less than $P_{max}$.

This results in a search space of $\frac{S}{2} K(K + 1)$ for each user. Therefore, for $M$ UEs, the maximum search space can be $\frac{S}{2} K(K + 1)^M$. For example, assume a system of one SP that has the following parameters: $K = 10$ RBs, $S = 15$ MCSs, and $M = 5$ UEs. The worst case search space size is $382.18 \times 10^{12}$. Such a problem is not practical and clearly hard to solve within fast scheduling periods. Thus, it is important to develop a low-complexity heuristic algorithm that can solve the problem faster.

4.5.2 The Heuristic Allocation Algorithm

Although it is much desirable to work with the optimal solution for its higher performance (as shown in Chapter 3), but the computational complexity price in solving encourages us to look for much less complexity algorithms. In this section, suboptimal iterative heuristic algorithm is proposed to solve the BIP with lower computational time and less complexity. Its objective is to minimize the total users summation costs by assigning RBs to the UEs iteratively. The algorithm needs a maximum of $KM$ iterations to assign all the RBs to all UEs. For each iteration, the algorithm finds the best RB for each UE.

The suitable RB for UE$_{mn}$ is defined as the RB which has the highest instantaneous $\Omega_{mn,k}$ and satisfies the contiguous constraint of UE$_{mn}$. Then, the change in the user’s cost value after assigning the best RB is calculated for each user. That leads to decreasing the power by increasing the UE’s BW of transmission that efficiently satisfies its constraints.

The heuristic algorithm proposed belongs to the greedy allocation algorithm family, based on a “steepest ascent” in the objective function. It can be explained simply as follows: first, the algorithm is initialized by defining the number of SPs, their corresponding UEs (with their
queue’s size indicated in the UEs’ BSR at a definite TTI), and their RBs. Each SP performs its target scheduling algorithm. It is assumed that the bits are stored one by one in the queue and that the queue is infinitely long.

Two scenarios are considered (static/dynamic sharing). Figure 4.2 illustrates the flowchart for the heuristic algorithm in SS and DS scenarios.
4.5. Scheduling Framework

Define $N$ SPs: $n \in \{1, 2, \ldots, N\}$

Mn UEs: $m_n \in \{1, 2, \ldots, M_n\}$

Kn RBs: $k_n \in \{1, 2, \ldots, K_n\}$

check queues’ size for all UEs
determine TB for all UEs

set $P_{mn} = 23$ dBm, update UE $m_n$’s queue for TTI = $t + 1$

SS scenario
Assign the best feasible RB for each active UE $m_n$: $\arg \max \{\Omega_{m_n, k}\}$

for each TTI $t$
for each SP $n$

Check $\# RBs > 0$

Calculate $P_{mn}$ for each $m_n$

Find UE $m_n$ with max power
Skip this user

UE $m_n$ has contiguous RB

Assign the best feasible contiguous RB

Calculate $P_{mn}$ for each $m_n$

set $P_{mn} = 23$ dBm, update UE $m_n$’s queue for TTI = $t + 1$

DS scenario
Assign the best feasible RB for each UE $m_n$: $\arg \max \{\Omega_{m_n, k}, \forall K_n\}$

for each TTI $t$
for each SP $n$

Check $\# RBs > 0$

Calculate $P_{mn}$ for each $m_n$

Find UE $m_n$ with max power
Skip this user

UE $m_n$ has contiguous RB

assign one feasible contiguous RB

Calculate $P_{mn}$ for each $m_n$

set $P_{mn} = 23$ dBm, update UE $m_n$’s queue for TTI = $t + 1$

Figure 4.2: The flowchart of the heuristic allocation algorithm in SS and DS scenarios.
Static Sharing Scenario

In this algorithm, each SP performs its scheduling individually with its own available RBs (\textit{av} \_RBs). The algorithm first initiates and defines all the needed sets, checks the content of all UEs’ queues, and determines the TB size for all UEs. Then it moves to the RB allocation part as follows: the best feasible RB for each UE\textsubscript{m}, is assigned, and the free \textit{av} \_RBs are calculated. Then the transmission power for all UEs is calculated, and the UE with maximum power is assigned with the best feasible contiguous RB. This is repeated until all the RBs are assigned. After assigning all RBs (\textit{av} \_RBs = 0), all UEs’ transmission power are calculated, and are limited to \(P_{\text{max}}\) (power constraint).

In case of \(P_{m} > 23\) dBm, \(P_{m}\) is set to \(P_{\text{max}}\) and the UE’s queue is updated for the next TTI \((t + 1)\). The update will affect the TB that should be satisfied in the next TTI (e.g. if the TB for the considered UE is 400 bits/TTI, it will be recalculated to be 400 + the amount of unsent bits from previous interval bits/TTI).

Dynamic Sharing Scenario

The same steps used in the SS scenario are used in the DS scenario. The only difference is that each SP assigns the best feasible RB to its UEs from the set \(K_{\text{tot}}\) that contains all RBs from all the different SPs.

In the special case where SPs have different number of users, fairness between UEs (in terms of number of allocated RBs) can only be considered if SLA (between SPs) indicates specific weights of sharing among them [11, 12]. In this case, SPs with fewer UEs can only share a limited number of adjacent RBs (if available) with other SPs.

Heuristic Complexity

When considering the heuristic scheduling algorithm, the order of complexity is \(O(KM)\). This is because the algorithm needs \(K\) iterations to assign all the RBs. In each iteration, at most 2 operations are needed for each user due to the contiguity constraint. Substituting with
the previous example parameters, the worst case complexity is in the order of 200 operations, which is significantly less than the BIP-based algorithm complexity.

### 4.6 Simulation results

The scheme is tested using a discrete event simulator developed in MATLAB [65]. Furthermore, in order to combat the extreme uncertainty of self-similar traces and deliver conclusive results, the outcomes of multiple repeated simulation runs are averaged for each result. The solvers and the MATLAB simulator run on i7 core 3400 MHz with 12 GB of memory. Table 4.3 summarizes the list of simulation parameters and their default values.

In this work, 2 SPs performing DS are considered, leading it to allocate more RBs than the SS scenario. It is assumed that the total network load is evenly distributed amongst all UEs, i.e., that the UEs are equally weighted. Each mobile or UE is equipped with a single transmit antenna with 0 dB gain. UEs are assumed to be uniformly distributed over the entire network and are all moving at a pedestrian speed of 3 km/hr.

SP-1’s scheduler is considered to assure $\text{GBR} = 400 \text{ kb/s}$ (implying that UEs/SP-1 are able to transmit $\text{TB size} \geq 400 \text{ bits per TTI}$), while SP-2’s scheduler assures $\text{GBR} = 200 \text{ kb/s}$ ($\text{TB size} \geq 200 \text{ bits per TTI}$). An urban environment is assumed with path-loss exponent of 4.5. All existing UEs are assumed to be active.

The average BIP and heuristic transmit power in SP1 is depicted in Figure 4.3. The results show that the DS scenario ensures less UL power consumption than the SS. This is because users have access to a larger number of channels, and thus they can be allocated better channels.

In Figure 4.4, the average BIP transmit power versus the average channel gain is plotted. Three main points are observed. The first is that the DS scenario ensures less UL transmission power than SS. This is due to UEs having access to a larger number of RBs, and thus they can be allocated better channels. The second is that the average transmission power decreases as
### Table 4.3: Simulation Default Parameters and Values.

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>Spectrum allocation (UL, DL)</td>
<td>20 MHz</td>
</tr>
<tr>
<td>Carrier frequency</td>
<td>2 GHz</td>
</tr>
<tr>
<td>Number of subcarriers per RB</td>
<td>12 subcarriers</td>
</tr>
<tr>
<td>Neighboring subcarrier spacing</td>
<td>15 KHz</td>
</tr>
<tr>
<td>RB bandwidth</td>
<td>180 KHz</td>
</tr>
<tr>
<td>Slot duration</td>
<td>0.5 ms</td>
</tr>
<tr>
<td>Cell radius</td>
<td>1 Km</td>
</tr>
<tr>
<td>MCS</td>
<td>QPSK, 16QAM, 64QAM</td>
</tr>
<tr>
<td>UEs in SP1</td>
<td>5 UEs</td>
</tr>
<tr>
<td>UEs in SP2</td>
<td>5 UEs</td>
</tr>
<tr>
<td>RBs available in SP1</td>
<td>10 RBs</td>
</tr>
<tr>
<td>RBs available in SP2</td>
<td>10 RBs</td>
</tr>
<tr>
<td>GBR should be satisfied by SP1</td>
<td>400 bits/TTI</td>
</tr>
<tr>
<td>GBR should be satisfied by SP2</td>
<td>200 bits/TTI</td>
</tr>
<tr>
<td>Channel fading</td>
<td>Rayleigh</td>
</tr>
<tr>
<td>Iteration #</td>
<td>1e4</td>
</tr>
<tr>
<td>$P_{\text{max}}$</td>
<td>23 dBM</td>
</tr>
<tr>
<td>Channel Estimation</td>
<td>Perfect</td>
</tr>
<tr>
<td>$\sigma_{\text{sig}}^2$</td>
<td>1</td>
</tr>
<tr>
<td>$\sigma_n^2$</td>
<td>1</td>
</tr>
<tr>
<td>$\epsilon$</td>
<td>0</td>
</tr>
<tr>
<td>Coherence time</td>
<td>1 ms</td>
</tr>
<tr>
<td>Cells interference</td>
<td>Avoidance</td>
</tr>
<tr>
<td>path-loss exponent</td>
<td>4.5</td>
</tr>
</tbody>
</table>
4.6. Simulation results

Average UE power with BIP and heuristic solutions

SP1 in SS and DS scenarios

Average transmit power per UE (Watt)

<table>
<thead>
<tr>
<th>SS</th>
<th>DS</th>
</tr>
</thead>
<tbody>
<tr>
<td>BIP</td>
<td>Heuristic</td>
</tr>
<tr>
<td>0.1</td>
<td>0.11</td>
</tr>
<tr>
<td>0.12</td>
<td>0.13</td>
</tr>
<tr>
<td>0.14</td>
<td>0.15</td>
</tr>
<tr>
<td>0.16</td>
<td>0.17</td>
</tr>
<tr>
<td>0.18</td>
<td>0.19</td>
</tr>
<tr>
<td>0.20</td>
<td>0.21</td>
</tr>
</tbody>
</table>

Figure 4.3: The average BIP and heuristic transmit power in SP1.
Figure 4.4: The average BIP transmit power versus the average channel gain.

the average channel gain increases. This is expected since the channel improves as the average gain increases, allowing the users to be allocated better channels. The third observation is that the lower the GBR requirement, the lower the average transmitted power. This is due to the fact that a smaller TB size needs fewer number of RBs to be satisfied and thus lower transmission power can be used.

Figure 4.5 shows the average BIP transmit power versus the number of active UEs. Due to the higher competition for RBs, which results in less number of RBs being allocated to each user, it is observed that the average transmission power increases as the number of users increases.

Figures 4.6 and 4.7 present the average BIP and heuristic transmit power in SP1 versus the average channel gain and the number of active UEs. The same observations as in Figures 4.5 and 4.6 are evident here. Furthermore, these figures show that the heuristic achieves comparable performance to the BIP-based scheme.

Figure 4.8 shows the average UL transmission rate per TTI in SPs-1, and 2, and it ensures
### 4.6 Simulation Results

**Figure 4.5:** The average BIP transmit power versus the number of active UEs.

**Figure 4.6:** The average BIP and heuristic transmit power in SP1 versus the average channel gain.
that, the GBR is equal to 200 Kbit/s in SP2 and 400 Kbit/s in SP1. The figure shows the efficiency of both the BIP-based solution as well as the heuristic, as both were able to satisfy the rate requirement of both SPs.

To better visualize the efficiency of this framework, it is assumed that UEs transmit data until the total energy consumption reaches 80 Watt (that is equivalent to transmitting at maximum power threshold (200 mW) for 400 TTIs) [30]. The normalized battery life comparison between the considered SS and DS scenarios in SP1 is illustrated in Figure 4.9. It is clear that the proposed schemes prolong the battery life by around 20 % to 53 % for the BIP-based scheme and 14 % to 30 % for the heuristic one.

Figures 4.10 and 4.11 plot the normalized running time (computed using the MATLAB functions \texttt{tic} and \texttt{toc}) versus the average channel gain and the number of active UEs respectively. As discussed before, the complexity of both schemes is dependent on the number of RBs and the number of users. Moreover, the heuristic has a smaller computational complexity.

Figure 4.7: The average BIP and heuristic transmit power in SP1 versus the number of active UEs.
4.6. Simulation results

Figure 4.8: The average UL transmission rate per TTI in SPs–1, and 2.

Figure 4.9: The normalized battery life versus the average channel gain.
Figure 4.10: The normalized running time versus the average channel gain.

compared to the BIP-based scheme.

4.7 Chapter Summary and Conclusion

The represented work pertains to power-efficient scheduling in a virtualized UL LTE systems to achieve green communication. Both the QoS requirements and the channel fading parameters were considered. The average SPs’ transmission power for all UEs in both SS and DS scenarios was evaluated. This improvement allowed SPs to customize their efforts, schedulers, and control the sharing of their resources among them.

A BIP-based scheduling algorithm with high computational complexity was developed. A lower complexity heuristic algorithm was also presented. Although, both algorithms are implementable, however, the heuristic is more reasonable for its less complexity and less computational time with affordable and guaranteed QoSs. Simulation results confirmed that sharing a framework yields notable improvements in terms of power saving without degrading QoS
Figure 4.11: The normalized running time versus the number of active UEs in SP1.

performance under different practical realistic scenarios.

Furthermore, it was shown that the DS scenario outperforms the SS scenario due to the larger pool of RBs available for users. Moreover, it was observed that the heuristic algorithm achieved comparable performance with the BIP-based algorithm while having a lower complexity.
Chapter 5

Intra-MME/S-GW Handover in Virtualized 3GPP-LTE Systems

As it is expected that mobility speeds to support can reach up to 350 km/h, the HO will occur more frequent. As a result, the system performance in terms of delay shall be degraded. So, more efficient radio resource management with enhanced HO techniques, and load balancing is required to support fast and seamless HO.

Many applications are appearing every day, specially with the expected evolution in mobility and wireless communications. The most popular high mobility applications are the high-speed rail that are significantly higher in speed than regular rail traffic. Thus, UEs operating their smart applications need to be satisfied with their provided QoSs assigned.

The presented framework to follow pertains to the SPs’ resources dynamic sharing scenario, wherein SPs achieving a different schedulers’ policy are sharing eNB. This allows SPs to customize their efforts and provide service requirements.
5.1 Introduction

One of the important aims of LTE, and any wireless technology, is to provide fast and seamless HO from one cell to another.

Accessing services with high mobility speed will degrade the efficiency and reliability of the wireless system especially during frequent HO.

Figure 5.1 shows the LTE system topology architecture. The E-UTRAN uses a simplified node architecture consisting of the eNB to communicate with UEs, while the eNB communicates with other eNB using X2-C and X2-U interfaces for control and user plane respectively.

The eNB communicates with the EPC using the S1 interface; specifically with the MME and the UPE identified as S-GW, using S1-C and S1-U interfaces for control plane and user
plane respectively, that supports a many-to-many relation between MMEs/UPEs and eNBs, and by its turn is connected by the IMS, and Apps.

The MME and UPE are preferably implemented as separate network nodes so as to facilitate independent scaling of the control and user plane. Intra E-UTRAN HO is used to hand over a UE from a source eNB to a target eNB using X2 interface when MME is unchanged. I assume that S-GW is also unchanged.

5.2 Recent Relevant Research Work

Until now, the existing HO techniques have some flaws such as inter-cell interference coordination, interference mitigation technologies, latency, unreliability and some data loss. Therefore, a new HO technique is essentially required to improve the HO performance.

In [98], the design and evaluation of an LTE test suite encompassing various mobility scenarios was reported. In [9, 99, 100], a fractional soft handover scheme based on the carrier aggregation is applied with single frequency reuse, without discussing the issues of the ignorance of LTE for soft HO (SHO) technique.

Kim et al. in [2], considered the state-of-the-art HO schemes with various deployment scenarios in WiMAX networks and 3GPP LTE-advanced candidate systems. They focused on IEEE 802.16m based.

Chen et al. in [101], proposed a framework of HO decision in LTE networks under high-speed mobility scenario. Tom et al. in [102] analyzed a fixed-point and classical A3 event HO algorithms in the LTE high-speed rail network without discussing the existing challenges in LTE HO operation. Han et al. in [103], HO delay and interruption time performance of LTE networks are measured without considering solutions to decrease that delay.

The main contribution in this chapter is proposing a HY-HO technique as feature work based on the combination of hard [HO] (HHO) and SHO techniques. The combination is expected to enhance the system performance in term of latency. Also, reducing the transmission
overhead on the serving cell results in a balanced network traffic.

To the best of my knowledge, there are no previous works that investigate and analyze the HO techniques in DS-virtualized (Vir.) scheme for LTE systems. This chapter considers DS resources Vir. scheduling algorithm for different types of traffic applications in access networks. The framework scheme shares SPs RBs while maintaining different scheduling strategies.

The research below offers detailed simulations to study the performance of the considered work and validate its effectiveness during and after the HO operation.

5.3 Users Mobility

Mobility models usually represent the motion of mobile UEs, and clarify how their position, speed and acceleration change with time [64, 104]. These models are frequently used for simulation purposes when investigating new communications techniques. Mobility management schemes for mobile communication systems use these mobility models in order to predict future user positions [49, 105].

The trade-off of improving the QoSs parameters, in turn improved error performance and would inherently require increased cost expenditures. In mobility modeling, it is important to simulate the system and evaluate its performance. The simulation has several key parameters, including the mobility model used and the pattern of communications traffic. Mobility models characterize user movement patterns, i.e. the different behaviours of subscribers. Traffic models describe the condition of mobile services.

The action of a UE’s motion can be described using both analytical and simulation models. The input for analytical mobility models makes simplifying assumptions regarding users movement behaviour. Such models can easily provide the performance parameters for simple cases using mathematical calculations.

Random way-point model is considered. In random-based mobility simulation models, the mobile UEs move randomly without restrictions. The destination, speed and direction are
chosen independently of other nodes. This kind of model has been used in many simulation studies. Two variants, the random walk model and the random direction model are variants of the random way-point model.

When the random direction model is used, the UE randomly chooses the speed direction, that remains constant during the time, and moves toward the simulation boundary area. Once the simulation boundary area is reached, the UE chooses a new speed direction.

When the random walk is used, the UE randomly chooses the speed direction and moves for a given distance which depends on the user velocity. The UE changes its speed direction after covering this distance.

In the mobility model class, the speed and direction variables are used to define the speed and the travel direction of the UE, respectively.

A mobile starts its motion through the system at call initiation with the above initial conditions. If the total call duration is long enough, the mobile will go through its first change of direction, and a new time until its next change of direction will be drawn at that point. The process is repeated until call termination, with the mobile possibly going through several handoffs in the mean time. An example is provided in Figure 5.2 where a mobile goes through two handoffs and two changes of direction before call termination.

Each call contributes a certain number of channel occupancy time samples, according to the number of handoffs it went through. In the example illustrated in Figure 5.2 three samples have been generated; one between call initiation and handoff 1, the second between handoff 1 and handoff 2, and the third one between handoff 2 and call termination. Once a sufficient number of samples have been generated, statistics for the channel occupancy time distribution can be obtained.

Let the position of a UE at time t be denoted by \( X_t(x, y) \in \mathbb{R}^2 \), where \( \mathbb{R}^2 = \{(x, y) : x, y \in \mathbb{R}\} \). Assuming that, the UE changes its position according to:
Figure 5.2: UE’s path of a mobile going through two handoffs and two changes of direction before cell termination.

$$\begin{bmatrix} x_{i+1} \\ y_{i+1} \end{bmatrix} = \begin{bmatrix} x_i \\ y_i \end{bmatrix} + v \begin{bmatrix} \cos(\theta) \\ \sin(\theta) \end{bmatrix} \cdot \Delta t \quad (5.1)$$

Figure 5.3 shows the pseudo-code investigating the rate of HO for different mobility speeds, using both the random way mobility model.

```
1: For each UE’s speed
2:   For each UE’s call
3:     Locate (x_o, y_o)
4:     Define s_l, where \( \sum_{l=1}^{5} s_l = D_m \)
5:     Assign each step s direction angle \( \theta \)
6:     Calculate boundary collision that counts for HO
7:   End For
8: Rate of HO = no. of HO / no. of UEs’ calls
9: End For // end of simulation
```

Figure 5.3: The pseudo-code for the rate of HO for different mobility speeds.
The user mobility is managed by the network manager that every TTI updates the user position according to the selected mobility model and parameters and verifies, through the Network Manager HO Procedure function, if the handover procedure is necessary.

5.4 Handover in Wireless Systems

In a wireless networks’ technologies, the term HO is defined as the process of establishing a target wireless link connection from the source to target base stations (BSs). This HO could be vertical or horizontal.

A vertical HO often occurs between different wireless technologies such as a HO for UE from LTE network to WiMAX mobile network. On the other hand, a horizontal HO occurs in the same wireless technology such as the HO of UE from one cell to other [98].

5.4.1 Handover Algorithm and Message Sequence

Figure 5.4 shows the HO algorithm. An arrow is demonstrating UE movement controlled by the same MME. In this procedure every bearer set between UE and MME will be moved to the target eNB (assuming that, the target eNB is able to handle the UE).

The presence of IP connectivity between the S-GW and the source eNB, as well as between the S-GW and the target eNB is assumed. During the simulation, each eNB maintains the list of UEs active with it, storing their ID and the latest reference signal received power (RSRP) feedbacks. Furthermore, eNBs and UEs have the information of the LTE cell they belong to. In fact, each UE keeps up to date the ID of the cell to which it belongs to and the ID of the active serving eNB.

Figure 5.5 presents the LTE HHO message sequence wherein, before the HO, the UE and the source eNB are in radio resource control (RRC) connection state. The DL and UL data are flowing between the S-GW and the UE via the source eNB. The network sets the measurement thresholds for sending measurement reports. The RRC uses the latest measurement to decide
Figure 5.4: Handover algorithm.
Figure 5.5: LTE handover message sequence.
if a HO is needed to another cell. The RRC measurement reports includes signal strength of serving and neighboring cells and the decision whether the HO is needed to be performed or not. If so; the target cell is selected. The eNB for the target cell is identified.

The source eNB initiates the HO with HO request message. S1 bearer is established between the target eNB and the S-GW. The target eNB allocates radio RBs for the UE that will be handed in. The target eNB responds back to the source eNB with a HO request acknowledge message. This message carries the HO command message (RRC connection reconfiguration request).

An X2 bearer is established between the source and the target eNBs. This channel will carry the UEs data during the HO. At this point, the UE is ready to buffer DL data that will be received during the HO. The source eNB sends a HO command to the UE. Meanwhile, the UE has received the HO command and it is switching to the new target cell. At this point, the UE has detached from the source eNB but is still not communicating with the target eNB. The UE is in the RRC-Idle state.

The UE sends a preamble request assigned in the HO command to start synchronizing with the target eNB. The target eNB accepts the request and responds back with a timing adjustment and an UL resource grant. The UE uses the assigned resources to transmit the HO confirm message (RRC connection reconfiguration complete).

The UE is not connected to the target eNB. Thus it transitions to the RRC-Connected state. The target eNB requests the MME to switch the path from the source eNB to the target eNB. MME requests the S-GW to switch the path to the target eNB. The S-GW asks the PGW to switch the path.

The S-GW responds back to the MME signaling the completion of the path switch. The target eNB will buffer data directly received from the SGW until all the data received via the source eNB has been transmitted. This is needed to maintain the transmission order. S-GW is now sending the data using the target eNB. MME responds back to signal the completion of the path switch. The end marker has been received at the target eNB. At this point the target

5.4. Handover in Wireless Systems

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asks the source eNB to release resources for the UE.

Although the HO in LTE systems is purely based on HHO [9, 106], I would present SHO as well.

### 5.4.2 Hard Handover Technique

The basic idea of HHO is to break-before-make. This means that, the previous wireless connection is broken from the source eNB before a new connection is activated to the target eNB. The UE will be able to communicate with one eNB during HHO. After releasing the connection from source eNB, a new connection is established and activated with the target eNB. Whereas, after the signal strength from a target eNB exceeds the signal strength from the source eNB the HO start the execution sequence as shown in Figure 5.5.

### 5.4.3 Soft Handover Technique

The SHO technique in generality is to make-before-break method. In other words, a new link connection to the target eNB should be established while the old connection with source eNB is still active. The UE simultaneously receive all services data from several active eNBs. Under this technique, there are two main SHO techniques in wireless mobile communication system. The first technique is called macro diversity HO (MDHO) and the second technique is called fast base station (BS) switching (FBSS) [99].

**Macro Diversity Handover**

In MDHO, a list of BSs is set by the UE and BS. This set of BSs is usually called the active or diversity Set. Under this technique, UE has the ability to communicate with all BSs in the active set as shown in Figure 5.6. For DL, UE receives and performs data from all the Diversity Set BSs. In the UL, all diversity set BSs receive and perform information from UE.

The neighboring BSs can still receive the signal from the UE, but the strength is not sufficient to allow neighboring BS to be considered from the diversity set. MDHO supports fast
and seamless HO. In addition, MDHO is more stable and gives better performance in term of fast and seamless handover. MDHO is more complex in its design and during HO procedure than HHO. Therefore, assuming MDHO will increase system complexity and many resources will be wasted.

**Fast Base Station Switching**

In FBSS technique, UE and BS make a list of the available BSs called a diversity set and also communicate with BS in each frame (just like MDHO). The UE monitors the base stations in the active set and defines only one BS as an anchor BS based on the received signal strength. This anchor BS is the only BS of the diversity set that UE can communicate with for UL and DL messages with all management and traffic exchange as shown in Figure 5.7 [99].

This type of HO is much smoother in transition from the source to target eNBs and much less overhead than MDHO. In other side, FBSS has high data lost latency and outage.
probability comparable to MDHO.

5.5 System Model

Consider a DL scenario, wherein, a UE belongs to SP1 is moving from a source eNB to a target eNB. The target eNB consists of multiple SPs employing different scheduling policies, such that, $N$ SPs share an eNB.

The set of SPs is denoted as $\mathcal{N} = \{1, 2, ..., N\}$. Each SP $n$ is assumed to serve $M_n$ active UEs, where $n \in \mathcal{N}$ and the set $\mathcal{M}_n = \{1, 2, ..., M_n\}$. Denote $\text{UE}_{m,n}$ to be the UE $m$ belonging to SP $n$. Each SP has access to a number of channels (available RBs).

Intra-MME/S-GW HO using the X2 interface is considered in the HO for the UE from a source eNB to a target eNB using the X2 interface when the MME and S-GW are unchanged. This scenario is possible only when there is a direct connection exists between source eNB and target eNB with the X2 interface. Denote $K_n$ to be the total number of available RBs in SP $n$. It is helpful to define some frequently used notations as shown in Table 5.1.

5.5.1 Transmission Block Size

In LTE, the subframe has a duration of 1 ms. The available spectrum is divided into RBs defined in both frequency and time domains. It consists of a contiguous set of 12 subcarriers (180 kHz with subcarrier spacing of 15 KHz) from each OFDM symbol and has a duration of 0.5 ms [51].

The overall TB size is a function of the spectral efficiency ($\zeta_s$) of the selected MCS $s$ and the number of allocated RBs. The total RB bandwidth is $12 \times BW$ [12, 51], where $BW$ is the subcarrier bandwidth. The total TB size, that can be transmitted per subframe over $k$ RBs for $\text{UE}_{m,n}$ is given by:

$$T_{m_n,k,s}(t) = \lfloor 132 \times \zeta_s(t) \times \|k\| \rfloor,$$

(5.2)
5.5. System Model

Table 5.1: Frequently Used Notations

<table>
<thead>
<tr>
<th>Notation</th>
<th>Definition</th>
</tr>
</thead>
<tbody>
<tr>
<td>$av_{RB}$</td>
<td>Number of available RBs at definite TTI</td>
</tr>
<tr>
<td>$k$</td>
<td>Set of RBs allocated for UE$_{m_n}$</td>
</tr>
<tr>
<td>$K_n$</td>
<td>Total number of RBs in SP $n$</td>
</tr>
<tr>
<td>$K_{tot}$</td>
<td>Total number of RBs in all SPs</td>
</tr>
<tr>
<td>$m$</td>
<td>UE</td>
</tr>
<tr>
<td>$m_n$</td>
<td>UE $m$ in SP $n$</td>
</tr>
<tr>
<td>$M_n$</td>
<td>Total number of UEs in SP $n$</td>
</tr>
<tr>
<td>$M_{tot}$</td>
<td>Total number of UEs in all SPs</td>
</tr>
<tr>
<td>$n$</td>
<td>SP</td>
</tr>
<tr>
<td>$N$</td>
<td>Total number of SPs</td>
</tr>
<tr>
<td>$n_{RB_j}$</td>
<td>Number of RBs allocated to UE $j$ for traffic class $i$</td>
</tr>
<tr>
<td>$n_{ij}$</td>
<td>Number of needed RBs to satisfy traffic $i$ for UE $j$</td>
</tr>
<tr>
<td>$n_{RB_j}$</td>
<td>Number of RBs allocated to UE $j$</td>
</tr>
<tr>
<td>$P_{tx}$</td>
<td>eNB’s transmitting power</td>
</tr>
<tr>
<td>$P_{rx}$</td>
<td>UE’s received power</td>
</tr>
<tr>
<td>$RB_{BW}$</td>
<td>Size of available RB that could be allocated to UE $j$</td>
</tr>
<tr>
<td>$s$</td>
<td>MCS</td>
</tr>
<tr>
<td>$S_i$</td>
<td>Needed BW to satisfy traffic $i$ (in bits) by all UEs</td>
</tr>
<tr>
<td>$t$</td>
<td>Definite TTI</td>
</tr>
<tr>
<td>$T_{m_n}$</td>
<td>TB of UE $m$ in SP $n$</td>
</tr>
<tr>
<td>$TTI$</td>
<td>Transmission time interval</td>
</tr>
<tr>
<td>$U_{HO}$</td>
<td>Total number of UEs performing HO</td>
</tr>
<tr>
<td>$V_{ij}$</td>
<td>BSR size of queue $i$ for UE $j$, where $i = 1$ for EF $i = 2$ for non-EF</td>
</tr>
<tr>
<td>$[.]^*$</td>
<td>The new value of $[.]$</td>
</tr>
</tbody>
</table>
and thus, the number of RBs can be represented as:

$$\|k\| = \frac{T_{m,k,s} + \epsilon}{132 \ z_s(t)}$$

(5.3)

where $0 \leq \epsilon < 1$.

Fast HO is a network procedure with minimum HO delay without any interest in packet loss [107, 108] or interruption time. While, seamless HO are a network re-entry procedure with the capability for UE to contact with the target eNB before initiating a network re-entry control message transaction.

Generally, fast and seamless HO depends on the type of the traffic services. For example, A real-time applications require high data rate. Thus, there is degrading connection in these real-time applications (i.e. video conferencing and streaming media), that will be noted to the UEs while HO from the source to the target eNB.

However, browsing a website/transferring a file do not require a high data rate, so the UE will not notice any drop in the HO process. Thus, the most factors for fast and seamless HO are the latency and packet loss [109].

### 5.5.2 LTE RSRP Measurement Report

In LTE-systems technology, the measurement is done usually at two stages. One is the measurement in an idle mode, while the other is in connected mode. The idle mode is for the cell selection/re-selection process and this criteria is measured by the system information block (SIB) messages. While, the connected mode measurement is for the HO and the measurement criteria and is determined by the RRC messages for a specific UE.

In cellular networks, when a mobile moves from cell to another and performs cell selection/re-selection and HO, it needs to measure the signal strength and quality of the neighboring cells. Generally, in the LTE network, a UE measures RSRP.

The received signal strength indicator (RSSI) carrier measures the average total received
power in the OFDM symbols in the channel serving and non-serving cells, adjacent channel interference, thermal noise, etc. measured over all the 12 subcarriers [4, 21].

The reference signal received quality (RSRQ) considers also RSSI and the number of used RBs $k$. RSRP/RSSI measured over the same BW. It indicates the quality of the received reference signal. The RSRQ measurement provides additional information when RSRP is not sufficient to make a reliable HO or cell reselection decision.

While, the RSRP is the average power received by UE from a single cell spread over the full bandwidth and narrow band. It is calculated by UE for cell selection, HO, cell reselection and for path loss calculation for power control. The power measurement is the energy of the OFDMA symbol excluding the energy of the cyclic prefix.

The range of RSRP reported by UE is between -140 dBm to -44 dBm as shown in Figure 5.8. For each 1 dBm difference from -140 dBm, UE report an integer value (ranging 0 to 97) to the eNB. For example: value 0 is reported when UE measure RSRP < -140 dBm, value 1
is reported when UE measure \(-140 \text{ dBm} \leq \text{RSRP} < -139 \text{ dBm}\), and value 97 is reported when UE measure RSRP \(-44 \text{ dBm}\).

One of the most important step for Handover is Measurement Report from UE before the handover. Network make a decision on whether it will let UE HO or not, based on the measurement value from UE.

During HO, LTE uses measurement gap technique. It has the same procedure as the compressed mode in UMTS. It creates a small gap during which there is no transmission and reception. UE can then switch to the target eNB and perform the signal quality measurement and then comes back to the current cell.

Ideally, a network lets UE reports the RSRP of the serving eNB and neighbor eNBs and set the arbitrary rule for HO. The network builds up its decision on multiple consecutive measurements instead of using only a single or a couple RSRP value.

As a solution, 3GPP defines several sets of pre-defined mechanisms to be done by the UEs. These pre-defined measurements are called events.

This work usually goes seamlessly, as there should be a well established agreement between UE and network about the gap definition (e.g., starting position of the gap, gap length, number of gaps, ... etc.).

Due to the impact of large scale fading, it is possible by measuring the RSRP to determine the UE’s real-time position, with the received power is being the most important criterion for HO decision [96, 110]. Received power is calculated as follows:

\[
\frac{P_{rx}}{P_{tx}} dB = 10 \log_{10} X - 10 \gamma \log_{10} \frac{d}{D} - \varphi dB
\]  

(5.4)

wherein, \(P_{rx}\) is the UE’s received power, \(P_{tx}\) is the eNB’s transmitting power, \(X\) is the path loss factor (by an average of channel attenuation, the value is generally between 0 and 1, during simulation \(10 \log_{10} X = -140.72 dB\)), \(\alpha\) is a path loss exponent, \(D\) is a reference distance (usually set to 1), \(d\) is the distance between the UE and the measured eNB, \(\varphi dB\) is a mean of 0
and standard deviation of 8 dB of lognormal shadowing value.

At first, when the UE enters the location where HO should be triggered, the UE receives the measurement volumes including: the UE terminal UE latitude and longitude information, the source eNB and the target eNB RSRP values (denoted as $RSR_P^{source}$ and $RSR_P^{target}$).

When the UE receives the returned measurement data, the obtained data is processed and the speed of movement of the UE is determined. If the UE’s $RSR_P^{source} \leq RSR_P^{target}$ then the UE triggers the classic A3 event HO algorithm.

### 5.5.3 Traffic in Wireless System

UE’s data packets are transported by dedicated radio bearers, generated with different packet jitter and delay requirements introduced as EF, AF, and BE traffic services.

Packets in dedicated bearers are generated at the application layer by 3 different traffic generators: voice traffic, trace based, and infinite buffer. The voice traffic EF application generates G.729 voice flows [55], modeled with an ON/OFF Markov chain, while the trace-based AF application sends packets based on realistic video trace files, and the BE application generates packets with CBR (as modeled in Chapter 3).

### 5.6 Hybrid-Handover Technique

Before HO, UE normally measures the RSRP of the target cell and report it to the eNB so that the network can make its decision whether or not to allow the UE to HO to the target cell.

SHO is possible in code division multiple access (CDMA) because adjacent cells can operate on the same frequencies as long as they use various scrambling codes. So, a UE can listen to two different cells by decoding the received signals twice, using a scrambling code from each cell on each for each decoded signal. This allows a UE to communicate with both eNBs during HO.

LTE is generally based on OFDMA, that is a frequency division technique. This means
that, a UE has to resynchronize with a different set of frequency when it hands over among cells, removing the possibility of SHO.

Just in terms of logical solution, the simplest way for inter-frequency measurement would be to implement multiple RF transceivers on UE. However, there are some issues with this solution. First is the cost issue, as it will require more cost to design and implement the additional transceiver.

Second can be the probability of interference between the current frequency and target frequency especially if the current frequency and target frequency are close. The third one would be the increase in UEs power consumption in UL and DL. These issues could be treated with by mass productivity, designing enhanced sharp RF filters, and activating the second RF transceiver only in HO operation to overcome the UL power consumption.

Also, by using HHO technique, it is hard to maintain the QoS requirement due to the delay in HO that occurs during eNB migration [111]. Meanwhile, providing fast and seamless access to multimedia services and broadband internet application with minimum delay requirements is one of the main goals that should be achieved in LTE system.

The limitation of the HHO technique in LTE system in term of high data loss, disruption time, outage probability and interferences may cause un-reliable HO [99], especially for delay sensitive applications. From this point, I was motivated to highlight HY-HO technique as a solution to enhance the QoS parameters in LTE systems.

The main concept of HY-HO technique is to partially perform SHO for EF services and HHO for non-EF services. During the HO procedure, EF services are transmitted from both source and target eNBs, while non-EF services are transmitted by source or target eNBs. Figure 5.9 shows the concept of HY-HO, while Figure 5.10 shows the pseudo-code HY-HO scheduling algorithm, respectively.

From the theoretical analysis, the proposed HY-HO scheme reduces the HO latency and traffic delay compared with HHO. Furthermore, the proposed HY-HO technique enhances the QoS of EF services and improves the spectrum efficiency. Finally, the proposed HY-HO proce-
5.7. The Allocation Scheduling Algorithms

Scheduling revenues are the charge of allocating RBs to active flows in both frequency and time domain. Many schedulers have been discussed in [11, 30, 32, 59], comparing data throughput, delay, fairness, and so on.

In this work full-buffer traffic model is considered. To foster customizable schedulers in the evolution, SPs with different utility functions ($U_t$) are investigated. It is assumed that SP-1 and SP-2 in the target cell foot-print share one eNB, and apply proportional fair (PF) scheduling and maximum-rate (MR) scheduling, respectively.

5.7.1 Proportional Fair Scheduling Algorithm

PF is the channel-aware scheduling algorithm that targets to increase the total throughput of the system and maintains fairness among UEs at the same time [89, 112, 113, 114]. In PF
For each simulated TTI do

\[ \text{av}_{RBs} = N \]  // Total available RBs in source and target SPs

// phase i: RBs allocation for traffic class i=1 (EF traffic)
If \( \text{av}_{RBs} > 0 \) Then

\[ n_{ij} = \text{Ceil} \left( \frac{v_{ij}}{RB_{BW}} \right) \]  // Needed RBs to satisfy traffic i for UE_j

End If
// Needed RBs by traffic i for UEs performing HO
\[ S_i = \sum_{j=1}^{U_HO} n_{ij} \]

// Allocated RBs for traffic class i for UE_j
\[ n_{iRB_j} = \min \left( n_{ij}, \text{floor} \left( \frac{n_{ij} \times \text{av}_{RBs}}{s_i} \right) \right) \]

// Total available RBs after allocation to traffic i for UE_j
\[ \text{av}_{RBs} = N - \sum_{j=1}^{U_HO} n_{iRB_j} \]

End For  // End of Simulation

Figure 5.10: The pseudo-code for HY-HO scheduling algorithm.
scheduling, data bearers are assigned the following utility function:

\[ Ut_{mn}(r) = \frac{T_{mn}(r)}{\bar{T}_{mn}} \] (5.5)

where \( T_{mn}(r) \) is the TB size that can be transmitted by assigning the RB \( r \) to UE \( m \) in SP \( n \), which is computed from Equation (5.2), and \( \bar{T}_{mn} \) is the UE’s historical average transmit data.

PF scheduler targets to maximize the sum of the utility functions as follows:

\[
\max_{K_n} \sum_{r=1}^{K_n} \sum_{m=1}^{M_n} \frac{T_{mn}(r)}{\bar{T}_{mn}} \beta_{mn,r}, \quad \forall \ n
\] (5.6)

subject to:

\[
\sum_{m=1}^{M_n} \beta_{mn,r} = 1, \quad \forall \ r \in K_n, \ n
\] (5.7)

To maximize the utility function, PF scheduler assigns RBs to UEs who have low historical average rates \( \bar{T}_{mn} \), which gives them more chances of using the resources and imposes fairness between UEs, or to UEs who have good channel quality \( T_{mn}(r) \) to increase the overall throughput of the system.

### 5.7.2 Maximum Rate Scheduling Algorithm

While, MR scheduling aims to increase the overall throughput of the system [115, 116] that can be achieved by assigning the following utility function to UEs:

\[ Ut_{mn}(r) = T_{mn}(r), \quad \forall \ n \] (5.8)

MR scheduler maximizes the sum of the utility functions

\[
\max_{K_n} \sum_{r=1}^{K_n} \sum_{m=1}^{M_n} T_{mn}(r) \beta_{mn,r}, \quad \forall \ n
\] (5.9)
subject to:

\[ \sum_{m_n=1}^{M_n} \beta_{m_n,r} = 1, \quad \forall \ r \in K_n, \ n \]  

(5.10)

wherein, maximizing the objective function by assigning each RB to UEs who can transmit the largest data block over it.

To reduce control signalling overhead, the LTE standard recommends that, for each subframe, only one MCS should be used for all allocated UEs RBs [11, 12]. The RBs chunk and MCS that is assigned to UE determine the TB size. However, how the TB is shared between UEs’ buffers is left to the UE’s I.S.. In other words, distributing TB into a different UEs bearers is assumed to be handled by UE.

The I.S. distributes the received RBs grant among the different active traffic bearers, While taking into account the buffer load, priority of other UEs classes, etc.. This distribution is executed according to S.P. algorithm (discussed in Chapter 3) according to their highest flow and based on the latest buffer status information which may have changed since the buffer status was reported.

### 5.8 The Static and Virtualized Sharing Algorithm

The radio access network in the target cell connects multiple SPs and manages the resources allocation between them according to their SLA. Each SP owns a set of RBs \( K_n \) with no intersection between the different SPs’ RBs, such that:

\[ K_n \cap K_v = \phi, \quad \forall \ n, v \in N \]  

(5.11)

Before the HO operation, the UE performs the source SP’s scheduler. During the HO; (I have three discussed cases) in case of HHO scheduling, the UE will be in Idle state (no allocation scheduling exist); in case of HY-HO scheduling, the UE perform HY-HO (HHO on the non-EF services (no allocation exist), and SHO on EF services (RBs allocated from the source
5.8. The Static and Virtualized Sharing Algorithm

SP and target SP (SP-1)); in case of Vir. HY-HO scheduling, the UE perform Vir. HY-HO (HHO on the non-EF services (no allocation exist), and Vir. SHO on EF services (RBs allocated from the source SP and target SPs (SPs-1,2))).

While after the HO execution; in case of HHO and HY-HO scheduling; the UE performs the target SP’s scheduling algorithm (SP-1); and in case of Vir. HY-HO scheduling; the UE allocates RBs from the target SPs (SPs-1,2)).

In this work, two scenarios are considered: static sharing (SS) and Vir. DS allocation scheduling. In SS, SPs are sharing only the common physical infra-structure eNB without sharing the channels among them; while in DS, LTE Vir. scheme the sharing agreement includes the SPs spectrum. Thus, SPs share their physical RBs.

5.8.1 Static Sharing Allocation

In this algorithm, each SP performs its allocation scheduling individually. Assuming an admission control scheme is applied, the resource allocation problem considering SS scenario between SPs can be expressed as:

$$\max \sum_{t} \sum_{n=1}^{N} \sum_{m_n=1}^{M_n} \sum_{r \in k} U_{t_{m_n,r}}(t) \psi_{m_n,r}(t)$$

subject to

$$\sum_{n=1}^{N} \sum_{m_n=1}^{M_n} \sum_{r \in k} \psi_{m_n,r}(t) = 1, \forall t, k \in K_n$$

$$\psi_{m_n,r}(t) \in \{0, 1\}, \forall m_n, r, t$$

Equation (5.12a) represents the objective function that aims to maximize the overall $U_t$ function for all UEs, where $U_t$ and $\psi$ are the decision variables. $U_{t_{m_n,r}}$ is the utility function of UE$_{m_n}$ assigned by the set of RBs $k$, and $\psi_{m_n,k}$ is a binary indicator used to denote whether the UE$_{m_n}$ is assigned by the set of RBs $k$ or not.

Equation (5.12b) represents the exclusive allocation constraint [12], that ensures that at a
definite time \( t \), only this set of RBs \( k \) is assigned to UE \( m_n \). Equation (5.12c) shows the bounded values for the binary indicator \( \psi_{m,n,k} \) that is equal 1 if RB \( r \) is assigned to UE \( m \) in SP \( n \), and equal 0 otherwise.

### 5.8.2 Virtualized Dynamic Sharing Allocation

The same steps used in the SS scenario are used in the DS scenario. The only difference is that each SP assigns the best feasible RB to its UEs from the set \( K_{tot} \) that contains all RBs from all the different SPs.

In DS scheduling algorithm, a Vir. scheme is considered; wherein, the total RBs \( K_{tot} \) set is assumed to be fully pooled and accessible to the SPs [59]. RBs are assigned in accordance that SPs should be able to implement different scheduling policies. It is assumed that each UE per SP should receive at least its LBS, which it would otherwise receive in the case of a non-sharing scenario.

The resource allocation problem considering DS scenario between SPs can be expressed as:

\[
\max \sum_{t=1}^{M_{tot}} \sum_{m=1}^{M_{tot}} \sum_{r \in K} U_{m,r}(t) \psi_{m,r}(t) \tag{5.13a}
\]

subject to

\[
\sum_{m=1}^{M_{tot}} \sum_{r \in K} \psi_{m,r}(t) = 1, \forall \ t, k \in K_{tot} \tag{5.13b}
\]

\[
\psi_{m,r}(t) \in \{0, 1\}, \forall \ m, r, t \tag{5.13c}
\]

Similarly, equation (5.13a) represents the objective function that aims to maximize the overall utility function for all UEs, where \( U_t \) and \( \psi \) are the decision variables. Similarly, \( \psi_{m,r} \) is a binary indicator used to denote whether the UE \( m \) is assigned the set of RBs \( k \) or not. Equations (5.13b and 5.13c) represents the exclusive allocation constraint [12], that ensures that at a definite time \( t \), only this set of RBs \( k \) is assigned to UE \( m \) and the bounded values for the binary indicator \( \psi_{m,r} \) respectively.
5.9 Simulation results

After the HO execution, the Vir. DS scheduling algorithm operates between the target cell
SPs sharing their RBs. Wherein; $M_{tot}$ and $K_{tot}$ represent the total number of UEs and RBs
respectively, in the target cell (SPs 1, and 2).

5.9 Simulation results

The scheme is tested using a discrete event simulator developed in MATLAB [65]. Further-
more, in order to combat the extreme uncertainty of self-similar traces and deliver conclusive
results, the outcomes of multiple repeated simulation runs are averaged for each result. The
solvers and the MATLAB simulator run on i7 core 3400 MHz with 12 GB of memory.

In this work, All UEs are processing EF traffic with rate 4 Kbit/s, and non-EF traffic with
rate 268 Kbit/s. During the HO, the UE perform switching to a detached state for a certain
time period such that there is no flows to and from the UE. This time interval is a simulator
parameter (the default value is 30 ms) [64].

An urban environment is assumed with path-loss exponent of 4.5. All existing UEs are
assumed to be active. Table 5.2 summarizes the list of simulation parameters and their default
values.

The rate of HO versus various mobility speeds up to 350 Km/hr is plotted in Figure 5.11
investigated from the traveling pattern presented earlier in this chapter. Wherein, each mobile
or UE is equipped with a single transmit antenna with 0 dB gain.

Level of 10000 calls is considered, each of uniform distribution time of average 80 s. The
uniform distribution used for the spatial location of call initiations and steps’ size with unifor-
mally random distribution were chosen.

Similarly, the uniform distribution of mobiles directions over $[0, 2\pi]$ was chosen both for
its simplicity and because it provides a rather general and realistic representation of real-life
systems. Throughout a cellular system the relative orientation of streets and cells might vary
somewhat randomly, giving on the average an approximately uniform distribution of possible
Table 5.2: Simulation Default Parameters and Values.

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>Spectrum allocation (UL, DL)</td>
<td>20 MHz</td>
</tr>
<tr>
<td>Carrier frequency</td>
<td>2 GHz</td>
</tr>
<tr>
<td>Number of subcarriers per RB</td>
<td>12 subcarriers</td>
</tr>
<tr>
<td>Neighboring subcarrier spacing</td>
<td>15 KHz</td>
</tr>
<tr>
<td>RB bandwidth</td>
<td>180 KHz</td>
</tr>
<tr>
<td>Slot duration</td>
<td>0.5 ms</td>
</tr>
<tr>
<td>Cell radius</td>
<td>1 Km</td>
</tr>
<tr>
<td>MCS</td>
<td>QPSK, 16QAM, 64QAM</td>
</tr>
<tr>
<td>UEs in SP1</td>
<td>5 UEs</td>
</tr>
<tr>
<td>UEs in SP2</td>
<td>5 UEs</td>
</tr>
<tr>
<td>RBs available in SP1</td>
<td>10 RBs</td>
</tr>
<tr>
<td>RBs available in SP2</td>
<td>10 RBs</td>
</tr>
<tr>
<td>SP1 scheduler</td>
<td>PF scheduling algorithm</td>
</tr>
<tr>
<td>SP2 scheduler</td>
<td>MR scheduling algorithm</td>
</tr>
<tr>
<td>Channel fading</td>
<td>Rayleigh</td>
</tr>
<tr>
<td>$w$</td>
<td>1</td>
</tr>
<tr>
<td>Iteration #</td>
<td>1e4</td>
</tr>
<tr>
<td>Mobility model</td>
<td>Random way model</td>
</tr>
<tr>
<td>Gap length</td>
<td>6 ms</td>
</tr>
<tr>
<td>Gap repetition</td>
<td>80 ms</td>
</tr>
<tr>
<td>gaps averaged</td>
<td>200 ms</td>
</tr>
<tr>
<td>eNB Tx power</td>
<td>46 dBm</td>
</tr>
<tr>
<td>UE Tx power</td>
<td>23 dBm</td>
</tr>
<tr>
<td>HO event model</td>
<td>A3 event model</td>
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<tr>
<td>Fading</td>
<td>Rayleigh</td>
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<tr>
<td>$\sigma_n^2$</td>
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</tr>
<tr>
<td>$\epsilon$</td>
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</tr>
<tr>
<td>Coherence time</td>
<td>1 ms</td>
</tr>
<tr>
<td>Simulation time</td>
<td>80 s</td>
</tr>
<tr>
<td>Cells interference</td>
<td>Avoidance</td>
</tr>
<tr>
<td>path-loss exponent</td>
<td>4.5</td>
</tr>
</tbody>
</table>
5.9. Simulation results

Figure 5.11: The rate of handover versus mobility speeds for cell radius of 1 Km.

directions.

The performance of high mobility UE is analyzed, that can be considered as a high mobility railway scenario with previous known information about the source and target eNBs, speed, direction of movement, and departure/arrival time of operation (disregarding the probability of ping pong effect). It is assumed that the UE moves with constant speed over the simulation, and the departure starts from the source eNB center, entering the target cell with $90^\circ$ directional angle. Both eNBs have a radius of 1 Km, with 100 m overlap distance, wherein the RSRP starts to indicate the HO request.

Figures 5.12 and 5.13 show the average packets delay (EF and non-EF traffic) for mobility speed 150 Km/hr and 350 Km/hr receptively versus distance from eNB. The Vir. DS scenario ensures less average delays for EF and non-EF traffic than SS. This is due to UEs having access to a larger number of RBs, and thus they can be allocated better channels. The average packet delay for the non-EF overlaps for the HHO and HY-HO scheduling algorithm. This is because the HY-HO perform pure HHO on the non-EF traffic.

Noting that, mostly the EF class has 1 ms jitter, which is the minimum delay that could
be satisfied (mapping time period). As in DS, the scheduler allocates more resources for the immigrant UE. Because of the higher arrival rate, the delay of the non-EF classes is noticed to be higher than EF within the entire network, moreover the I.S. gives the EF services higher priority access than non-EF.

The average packets delay (EF and non-EF traffic) for mobility speed 150 Km/hr and 350 Km/hr versus time (s) is plotted in Figure 5.14. It is clear that the UE moving with speed 350 Km/hr reaches the cell boundary and performs HO prior to the mobility speed 150 Km/hr.

The simulation results conclude that HY-HO Vir. DS scheme is capable of achieving great improvements with respect to delay when compared to the non-sharing application, improving the performances of EF during the UE’s HO operation, and AF and BE traffic services after HO execution, leading to better QoS to be delivered.

In order to ensure the validity of the proposed algorithm, it is considered a mobile UE emigrant from source eNB to target eNB, exposed to high dense EF traffic with rate 40 Kbps
5.10 Conclusion

In this chapter, the framework model represented pertains to analyze the performance of UE’s HO algorithm in LTE systems. A HY-HO technique is proposed to cover the short comings of the existing approaches. The HY-HO scheme is based on the combination of SHO and

Figure 5.13: The average packets delay (EF and non-EF traffic) for mobility speed 350 Km/hr versus distance from eNB.

of CBR. Figures 5.15 and 5.16 show the average packet delay for mobility speeds 150 Km/hr and 350 Km/hr versus the distance from the source eNB. While, Figure 5.17 plots the average packet delay for mobility speeds 150 Km/hr and 350 Km/hr versus the time.

The simulation results was able to prove that HY-HO Vir. DS scheme is capable to handle the high dense EF traffic services and achieve great improvements with respect to delay when compared to the non-sharing application, improving the performances of EF during the UE’s HO operation and enhance the QoSs’ parameters for the next wireless network generation.
Figure 5.14: The average packets delay (EF and non-EF traffic) for mobility speeds 150 and 350 Km/hr versus time.

Figure 5.15: The average packets delay (high dense EF traffic) for mobility speed 150 Km/hr versus distance.
5.10. Conclusion

Figure 5.16: The average packets delay (high dense EF traffic) for mobility speed 350 Km/hr versus distance.

Figure 5.17: The average packets delay (high dense EF traffic) for mobility speeds 150 and 350 Km/hr versus time.
HHO. The combination was able to enhance the system performance in term of latency, interruption time and reliability during handover especially at cell boundary.

Also, the combination reduces the transmission overhead on the serving cell, which balances the traffic load within the system cells in LTE. I also evaluated the average packets delays for cases of SS and DS schemes, with the goal to close the growing gap between the capacities of backbone networks.

According to the simulation results, HY-HO virtualized DS scheme is capable of achieving great improvements with respect to delay when compared to the non-sharing application. This improvement allows SPs to customize their efforts, schedulers, and control the sharing of multi-SP resources between them.

Overall, the results confirm that the HY-HO framework yields notable improvements in average packet delay, without degrading QoS support for EF, AF, and BE services. Nonetheless, the performances of AF and BE as non-EF services are yet to be further improved, and QoS to be better delivered.
Chapter 6

Thesis Summary and Future Work

As time goes on, the need for enhancing QoSs’ parameters in order to reach a future technology becomes more and more paramount. Interestingly enough, while the penetration rate for mobile users and breadth of device features continues to increase, the need for more research improvement in wireless communication networks is still of importance.

6.1 Thesis Summary

In this thesis designs are proposed for both scheduling and resource allocation methods that offer reduced complexity in multi-stream (multi-user), virtualized scenarios in both DL and UL systems.

In Chapter 3, I examined a novel design for a virtualized resources’ sharing technique. This novel approach can be used to efficiently schedule traffic streams with differing QoS parameters without needing to result to full scale optimization techniques while still guaranteeing throughput and average delay constraints.

Wherein, SPs using different scheduling algorithms are sharing their physical radio RBs in one eNB in a virtualized scheme as a promising solution for reducing operational and capital expenditures. The proposed method makes use to schedule traffic with various delay and priority requirements.
However, next in Chapters 4 and 5 this dynamic virtualization was considered. First, the main contributions in Chapter 4 resulted in a detailed study of modeling an optimized solution for the simulated sharing scheme methodology used in Chapter 3. Wherein, an optimized efficient power scheduling was proposed for a dynamic policy framework, which meets exclusive and contiguous allocation, maximum transmission power, and rate constraints restrictions while minimizing the average applied transmission power for a time-invariant channel to achieve green communication.

This dynamic virtualized scheme was used in Chapter 5 to design an extended scheduling scheme that exploited this information about the underlying channel statistics. The main contribution of this Chapter 5 was an extension of the work in Chapter 3. Wherein, the performance of UEs random-way mobility model and HO algorithms for high-mobility users was analyzed in a virtualized LTE systems. A HY-HO technique is proposed to address the shortcomings of the existing approaches and the challenges caused by the demand for high data rates. The results confirm that the HY-HO framework yields notable improvements in average packet delay, without degrading QoS.

Overall, one of the primary arguments made in this thesis is the large complexity associated with heterogenous scheduling techniques, particularly when attempting to minimize energy expended in the mobile radio. While in this thesis, methods of complexity reduction in scheduling were shown while attempting to minimize energy expenditure, it is important to note that this research area is still wide open and that there is no single solution to this complexity problems. This is particularly true as the constraints imposed by practical systems vary dramatically from system to system.

### 6.2 Future Work

The work in this thesis presents some investigation into the multi-stream scheduling problems, particularly with a focus on complexity issues in virtualized LTE systems. Although,
some novel techniques to reduce complexity and address this problem were proposed, there still remains numerous open issues in this area. In this section, I highlight some of these major issues that can use Virtualization in order to improve the network performance in wireless communications, enhance the QoSs’ parameters, and move towards the future.

### 6.2.1 Optimal D2D User Allocation in Virtualized Scheduling Algorithm

The device-to-device (D2D) communication is a type of close range data transmission over a direct link and coexists with cellular networks in an underlay manner [117]. The D2D communication has advantages of enhancing network throughput, saving the power of user equipment and increasing an instantaneous data rate, which draw much attention in the recent years.

Spectrum sharing mechanism and transmission capacity are two fundamental issues of the heterogeneous system which allows secondary users sharing resource with primary users in the licensed band.

Hence, how the schedule D2D pairs working on different bands to reduce interference and improve the network capacity is an important issue that should be discussed in dynamic virtualized network environment.

### 6.2.2 Energy-Efficient for Green Smart Grid Communication in Virtualized Scheduling Algorithm

A smart grid is conceptualized as a combination of underlay electrical network and overlay communication network. Therefore, the communication network plays an important role for exchanging real-time information [118]. Consequently, the smart meters deployed at the customers end communicate with the SP for cost-effective and reliable energy supply to the users.

Therefore, it is necessary to establish a green wireless communication architecture that takes into account the environmental issues. Therefore, the smart meters consume huge amount of energy for real-time communication. On the other hand, plug-in hybrid vehicles (PHEVs)
play an important role to relieve the on-peak hour load from the grid, and acts as storage device as well. Intuitively, PHEVs will also communicate with the SP in order to have real-time information.

Therefore, implementation of cooperative strategies of smart meters and PHEVs can have significant impact in reducing the energy consumption in smart grids. Consequently, it is important to propose an energy-efficient technique for smart metering towards green wireless communications in the smart grid in virtualized scheduling algorithm.

6.2.3 Green Heterogeneous Networks in Virtualized Scheduling Algorithm

Despite the ever growing investment in macro-cell base stations, users still often suffer from low signal strength and poor service quality in indoor environments, especially 3G cellular networks operating in high-frequency bands [119]. To solve this problems, in UMTS LTE network, macro-cell eNB implements a significant high DL power to guarantee the QoS of associated with macro-mobile stations. However, for the edge MSs or the MSs located in a spot with their specific locations and significant interferences to the eNB, the QoS can never been guaranteed well.

More importantly, deploying femtocell underlying macrocell as a two-tier heterogeneous networks (HetNet) has been proven to greatly improve indoor converge and system capacity. More importantly, some unique features of HetNets present more challenges in interference mitigation in the two-tier HetNets, such as random deployment for femto-cells, non-existence of macrofemto backhaul coordination and mandates forbidding to making any modifications of existing macro-cells.

Therefore, the efficient interference mitigation techniques in HetNets require resource cognition ability, which will provide more available cognitive resource opportunity of the physical RBs in space or time of macro-cell; autonomous mechanism design, where each HetNet can selfishly adjust system parameters in a self-organising way; scalability, which is perspectively
required by the promising densely co-located femto-cell in the foreseeable future.

To tackle these challenges, cognitive radio HetNets to concise available resource and adapt to HetNet environments resource allocation scheme in virtualized scheduling algorithm should be considered.
Bibliography


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